Course of Study Mechatronics (Study Cohort w17)

						Core qualification Compulsory	Specialisation Compuls		ocus Compulsory	Thesis Compulsory
	course plan B Master Mechatronics (IMP	MEC)				Core qualification Elective Compulsory	Specialisation Elective	Compulsory Fe	ocus Elective Compulsory	Interdisciplinary complement
ecia	isation System Design	Form Hrs/wk	Semester 2	Form Hrs/wk	Semester 3		Form Hrs/wk	Semester 4		Form Hrs
	Robotics Robotics: Modelling and Control Robotics: Modelling and Control	VL 3 GÜ 2	Mechatronic Systems Electro- and Contromechanics Mechatronics Laboratory Electro- and Contromechanics	VL 2 FL 2 GÜ 1	Research Project Mechatro	vnics		Master Thesis		
0	Finite Elements Methods Finite Element Methods Finite Element Methods	VL 2 HŪ 2	Nonlinear Dynamics Nonlinear Dynamics	VL 4						
1										
.3 .4 .5 .6	Control Systems Theory and Design Control Systems Theory and Design Control Systems Theory and Design	VL 2 GÜ 2	Embedded Systems Embedded Systems Embedded Systems	VL 3 GÜ 1	Nonlinear Structural Analy Nonlinear Structural Analysis Nonlinear Structural Analysis	sis	VL 3 GÜ 1			
8										
9 20 21 22 23 24	Vibration Theory Vibration Theory Vibration Theory	VL 2 HÛ 1	Optimal and Robust Control Optimal and Robust Control Optimal and Robust Control	VL 2 GÜ 2	Microsystem Engineering Microsystem Engineering Microsystem Engineering		VL 2 PBL 2			
5 6 7 8	Design and Implementation of Software Systems Design and Implementation of Software Systems Design and Implementation of Software Systems	VL 2 PR 2								
9	Business & Management (from catalogue) - 6LP	5LP								
	Nontechnical Elective Complementary Courses for M	Aaster (from cata	logue) - 6l P							

The choice of courses from the catalogue is flexible (depends on the semestral work load), provided the necessary number of required credits is reached.