Course of Study Mechatronics (Study Cohort w17)

| Sample | e course plan A Master Mechatronics (IMPI | | | Core qualification Elective Compulsory Specialisation Elective | | Interdisciplinary complement | | |
|---|--|---|--|--|--|------------------------------|--------------------------|-------------|
| | lisation Intelligent Systems and Robotics | Form Hrs/wk | Semester 2 | Form Hrs/wk | Semester 3 | Form Hrs/wk | Semester 4 | Form Hrs/wk |
| 1 2 3 4 5 6 7 8 9 10 | Robotics Robotics: Modelling and Control Robotics: Modelling and Control Robotics: Modelling and Control Finite Elements Methods Finite Element Methods Finite Element Methods | Form Hrs/wk VL 3 GÜ 2 VL 2 HÜ 2 | Semester 2 Mechatronic Systems Electro- and Contromechanics Mechatronics Laboratory Electro- and Contromechanics Nonlinear Dynamics Nonlinear Dynamics | Form Hrs/wk VL 2 FL 2 GÜ 1 VL 4 | Semester 3 Research Project Mechatro | | Semester 4 Master Thesis | Form Hrs/wk |
| 11 12 | | | | | | | | |
| 13 14 15 16 17 18 | Control Systems Theory and Design Control Systems Theory and Design Control Systems Theory and Design | VL 2 GÜ 2 | Embedded Systems Embedded Systems Embedded Systems | VL 3 GÜ 1 | 3D Computer Vision 3D Computer Vision 3D Computer Vision | VL 2 GÜ 2 | | |
| 19 20 21 22 23 24 | Vibration Theory Vibration Theory Vibration Theory | VL 2 HŪ 1 | Optimal and Robust Control Optimal and Robust Control Optimal and Robust Control | VL 2 GÜ 2 | Industrial Process Automat Industrial Process Automation Industrial Process Automation | VL 2 | | |
| 25 26 27 28 29 30 | Design and Implementation of Software Systems Design and Implementation of Software Systems Design and Implementation of Software Systems | VL 2 PR 2 | | | | | | |
| | Business & Management (from catalogue) - 6LP | | | | | | | |
| | Nontechnical Elective Complementary Courses for M | | | | | | | |

The choice of courses from the catalogue is flexible (depends on the semestral work load), provided the necessary number of required credits is reached.