



## **Module Manual**

Master of Science

# **Theoretical Mechanical Engineering**

Cohort: Winter Term 2017

Updated: 28th September 2018

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## Module Manual

Master

# Theoretical Mechanical Engineering

Cohort: Winter Term 2017

Updated: 28th September 2018

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### Program description

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#### Content

The 4-semester research-oriented master's degree (MSc) "Theoretical Mechanical Engineering" builds on research-oriented Mechanical Engineering-oriented undergraduate degree programs (BSc). Required are in-depth knowledge in mathematics and science and engineering fundamentals. The graduates acquire basic research and methodological oriented content, including interdisciplinary orientation, mechanical engineering knowledge and associated mechanical engineering expertise to develop mathematical descriptions, analysis and synthesis of complex technical systems methods, products or processes. In this course, the program combines the two most important theoretical and methodological areas, namely the simulation technology and systems theory. For this purpose, mathematical foundations and in-depth knowledge in areas such as the Technical dynamics, control engineering, numerical and structural mechanics are learned.

#### Career prospects

The master's degree program in Theoretical Mechanical Engineering prepares its graduates for professional and managerial positions in research and development. Through the course's focus on theory-method-oriented content and principles as well as intensive scientific thinking training, graduates are qualified for a wide field of work, especially in the area of mechanical and automotive engineering, biotechnology and medical technology, power engineering, aerospace engineering, shipbuilding, automation, materials science and related fields.

#### Learning target

The graduates can:

- analyze and solve scientific problems, even if they are defined uncommon or incomplete and competing specifications
- formulate abstract and complex problems from a new or evolving the field of their discipline
- apply innovative methods in basic research oriented problem solving and develop new scientific methods
- identify information needs and find information
  - plan and perform theoretical and experimental investigations
- Evaluate data critically and draw conclusions
- analyze and evaluate the use of new and emerging technologies.

Graduates are able to:

- develop concepts and solutions to basic research, partly unusual problems, possibly involving other disciplines,
  - create and develop new products, processes and methods
- apply their scientific engineering judgment to work with complex, possibly incomplete information, to identify contradictions and deal with them
- classify knowledge from different fields methodically and systematically, to combine and handle complexity;
- familiarize themselves systematically, and in a short time frame, with new tasks
  - To reflect systematically the non-technical implications of engineering activity and to act responsibly
- to develop solutions and further methodological skills.

### Program structure

The course is divided into basic research core courses and an application-specific specialization. In addition to the core subjects and mathematics, students develop in-depth knowledge in areas such as technical dynamics, control engineering, numerical and structural mechanics. To deepen the foundations of application specific specializations, modules are selected. Other technical and non-technical elective courses may be selected from the range of subjects TUHH and the University of Hamburg. During the last semester the Master thesis is carried out.

The curricular content is thus divided into six groups:

- Key skills, required courses (24 ECTS)
- Key skills, electives (24 ECTS)
- Project Work (12 ECTS)
- A specialization (18 ECTS)
- General non-technical content (12 ECTS)
- Master's thesis (30 ECTS).

The areas of specialization are:

- Biological and Medical Engineering
- Energy Technology
- Aircraft Systems
- Maritime Technology
- Numerical and computer science
- Product development and production
- Materials Engineering

The choice of specialization is required, its contents are closely related to the research topics of the Institute. The key skills already acquired in undergraduate study for mechanical engineering are developed within the Master's program.

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### Core qualification

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Important

<b>Module M0523: Business &amp; Management</b>	
<b>Module Responsible</b>	Prof. Matthias Meyer
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	None
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students are able to find their way around selected special areas of management within the scope of business management.</li> <li>• Students are able to explain basic theories, categories, and models in selected special areas of business management.</li> <li>• Students are able to interrelate technical and management knowledge.</li> </ul>
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students are able to apply basic methods in selected areas of business management.</li> <li>• Students are able to explain and give reasons for decision proposals on practical issues in areas of business management.</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Students are able to communicate in small interdisciplinary groups and to jointly develop solutions for complex problems</li> </ul>
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students are capable of acquiring necessary knowledge independently by means of research and preparation of material.</li> </ul>
<b>Workload in Hours</b>	Depends on choice of courses
<b>Credit points</b>	6

#### Courses

**Information regarding lectures and courses can be found in the corresponding module handbook published separately.**

<b>Module M0524: Nontechnical Elective Complementary Courses for Master</b>	
<b>Module Responsible</b>	Dagmar Richter
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	None
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><b>The Nontechnical Academic Programms (NTA)</b></p> <p>imparts skills that, in view of the TUHH's training profile, professional engineering studies require but are not able to cover fully. Self-reliance, self-management, collaboration and professional and personnel management competences. The department implements these training objectives in its <b>teaching architecture</b>, in its <b>teaching and learning arrangements</b>, in <b>teaching areas</b> and by means of teaching offerings in which students can qualify by opting for <b>specific competences</b> and a <b>competence level</b> at the Bachelor's or Master's level. The teaching offerings are pooled in two different catalogues for nontechnical complementary courses.</p> <p><b>The Learning Architecture</b></p> <p>consists of a cross-disciplinarily study offering. The centrally designed teaching offering ensures that courses in the nontechnical academic programms follow the specific profiling of TUHH degree courses.</p> <p>The learning architecture demands and trains independent educational planning as regards the individual development of competences. It also provides orientation knowledge in the form of "profiles".</p> <p>The subjects that can be studied in parallel throughout the student's entire study program - if need be, it can be studied in one to two semesters. In view of the adaptation problems that individuals commonly face in their first semesters after making the transition from school to university and in order to encourage individually planned semesters abroad, there is no obligation to study these subjects in one or two specific semesters during the course of studies.</p> <p><b>Teaching and Learning Arrangements</b></p> <p>provide for students, separated into B.Sc. and M.Sc., to learn with and from each other across semesters. The challenge of dealing with interdisciplinarity and a variety of stages of learning in courses are part of the learning architecture and are deliberately encouraged in specific courses.</p> <p><b>Fields of Teaching</b></p> <p>are based on research findings from the academic disciplines cultural studies, social studies, arts, historical studies, communication studies, migration studies and sustainability research, and from engineering didactics. In addition, from the winter semester 2014/15 students on all Bachelor's courses will have the opportunity to learn about business management and start-ups in a goal-oriented way.</p> <p>The fields of teaching are augmented by soft skills offers and a foreign language offer. Here, the focus is on encouraging goal-oriented communication skills, e.g. the skills required by outgoing engineers in international and intercultural situations.</p> <p><b>The Competence Level</b></p> <p>of the courses offered in this area is different as regards the basic training objective in the Bachelor's and Master's fields. These differences are reflected in the practical examples used, in content topics that refer to different professional application contexts, and in the higher scientific and theoretical level of abstraction in the B.Sc.</p> <p>This is also reflected in the different quality of soft skills, which relate to the different team positions and different group leadership functions of Bachelor's and Master's graduates in their future working life.</p> <p><b>Specialized Competence (Knowledge)</b></p> <p>Students can</p> <ul style="list-style-type: none"> <li>• explain specialized areas in context of the relevant non-technical disciplines,</li> <li>• outline basic theories, categories, terminology, models, concepts or artistic techniques in the disciplines represented in the learning area,</li> <li>• different specialist disciplines relate to their own discipline and differentiate it as well as make connections,</li> <li>• sketch the basic outlines of how scientific disciplines, paradigms, models, instruments, methods and forms of representation in the specialized sciences are subject to individual and socio-cultural interpretation and historicity,</li> <li>• Can communicate in a foreign language in a manner appropriate to the subject.</li> </ul> <p><b>Professional Competence (Skills)</b></p> <p>In selected sub-areas students can</p> <ul style="list-style-type: none"> <li>• apply basic and specific methods of the said scientific disciplines,</li> <li>• question a specific technical phenomena, models, theories from the viewpoint of another, aforementioned specialist discipline,</li> <li>• to handle simple and advanced questions in aforementioned scientific disciplines in a successful manner,</li> <li>• justify their decisions on forms of organization and application in practical questions in contexts that go beyond the technical relationship to the subject.</li> </ul>
<b>Personal Competence</b>	<p><b>Personal Competences (Social Skills)</b></p> <p>Students will be able</p>

<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• to learn to collaborate in different manner,</li> <li>• to present and analyze problems in the abovementioned fields in a partner or group situation in a manner appropriate to the addressees,</li> <li>• to express themselves competently, in a culturally appropriate and gender-sensitive manner in the language of the country (as far as this study-focus would be chosen),</li> <li>• to explain nontechnical items to auditorium with technical background knowledge.</li> </ul>
<i>Autonomy</i>	<p><b>Personal Competences (Self-reliance)</b></p> <p>Students are able in selected areas</p> <ul style="list-style-type: none"> <li>• to reflect on their own profession and professionalism in the context of real-life fields of application</li> <li>• to organize themselves and their own learning processes</li> <li>• to reflect and decide questions in front of a broad education background</li> <li>• to communicate a nontechnical item in a competent way in written form or verbally</li> <li>• to organize themselves as an entrepreneurial subject country (as far as this study-focus would be chosen)</li> </ul>
<b>Workload in Hours</b>	Depends on choice of courses
<b>Credit points</b>	6

<b>Courses</b>	
Information regarding lectures and courses can be found in the corresponding module handbook published separately.	



<b>Module M1259: Technical Complementary Course Core Studies for TMBMS (according to Subject Specific Regulations)</b>	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
<b>Hrs/wk</b>	<b>CP</b>
<b>Module Responsible</b>	Prof. Robert Seifried
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	see FSPO
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	see FSPO
<i>Skills</i>	see FSPO
<b>Personal Competence</b>	
<i>Social Competence</i>	see FSPO
<i>Autonomy</i>	see FSPO
<b>Workload in Hours</b>	Independent Study Time 180, Study Time in Lecture 0
<b>Credit points</b>	6
<b>Examination</b>	according to Subject Specific Regulations
<b>Examination duration and scale</b>	see FSPO
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Module M0751: Vibration Theory			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Vibration Theory (L0701)	Lecture	4	6
<b>Module Responsible</b>	Prof. Norbert Hoffmann		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Calculus</li> <li>• Linear Algebra</li> <li>• Engineering Mechanics</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students are able to denote terms and concepts of Vibration Theory and develop them further.</p> <p><i>Skills</i> Students are able to denote methods of Vibration Theory and develop them further.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i> Students can reach working results also in groups.</p> <p><i>Autonomy</i> Students are able to approach individually research tasks in Vibration Theory.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	2 Hours		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Core qualification: Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0701: Vibration Theory	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Norbert Hoffmann, Merten Tiedemann, Sebastian Kruse
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	Linear and Nonlinear Single and Multiple Degree of Freedom Oscillations and Waves.
<b>Literature</b>	K. Magnus, K. Popp, W. Sextro: Schwingungen. Physikalische Grundlagen und mathematische Behandlung von Schwingungen. Springer Verlag, 2013.

Module M0808: Finite Elements Methods			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Finite Element Methods (L0291)	Lecture	2	3
Finite Element Methods (L0804)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Otto von Estorff		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Mechanics I (Statics, Mechanics of Materials) and Mechanics II (Hydrostatics, Kinematics, Dynamics) Mathematics I, II, III (in particular differential equations)		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>The students possess an in-depth knowledge regarding the derivation of the finite element method and are able to give an overview of the theoretical and methodical basis of the method.</p> <p><i>Skills</i></p> <p>The students are capable to handle engineering problems by formulating suitable finite elements, assembling the corresponding system matrices, and solving the resulting system of equations.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p><i>Autonomy</i></p> <p>The students are able to independently solve challenging computational problems and develop own finite element routines. Problems can be identified and the results are critically scrutinized.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 min		
<b>Assignment for the Following Curricula</b>	Civil Engineering: Core qualification: Compulsory Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Mechatronics: Core qualification: Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Product Development, Materials and Production: Core qualification: Compulsory Technomathematics: Specialisation III. Engineering Science: Elective Compulsory Technomathematics: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Compulsory		

Course L0291: Finite Element Methods	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- General overview on modern engineering</li> <li>- Displacement method</li> <li>- Hybrid formulation</li> <li>- Isoparametric elements</li> <li>- Numerical integration</li> <li>- Solving systems of equations (statics, dynamics)</li> <li>- Eigenvalue problems</li> <li>- Non-linear systems</li> <li>- Applications</li>   <li>- Programming of elements (Matlab, hands-on sessions)</li> <li>- Applications</li> </ul>
<b>Literature</b>	Bathe, K.-J. (2000): Finite-Elemente-Methoden. Springer Verlag, Berlin

Course L0804: Finite Element Methods	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Module M0846: Control Systems Theory and Design</b>			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	
Control Systems Theory and Design (L0656)		Lecture	2
Control Systems Theory and Design (L0657)		Recitation Section (small)	2
<b>Module Responsible</b>	Prof. Herbert Werner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Introduction to Control Systems		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>Students can explain how linear dynamic systems are represented as state space models; they can interpret the system response to initial states or external excitation as trajectories in state space</li> <li>They can explain the system properties controllability and observability, and their relationship to state feedback and state estimation, respectively</li> <li>They can explain the significance of a minimal realisation</li> <li>They can explain observer-based state feedback and how it can be used to achieve tracking and disturbance rejection</li> <li>They can extend all of the above to multi-input multi-output systems</li> <li>They can explain the z-transform and its relationship with the Laplace Transform</li> <li>They can explain state space models and transfer function models of discrete-time systems</li> <li>They can explain the experimental identification of ARX models of dynamic systems, and how the identification problem can be solved by solving a normal equation</li> <li>They can explain how a state space model can be constructed from a discrete-time impulse response</li> </ul>		
<i>Skills</i>	<ul style="list-style-type: none"> <li>Students can transform transfer function models into state space models and vice versa</li> <li>They can assess controllability and observability and construct minimal realisations</li> <li>They can design LQG controllers for multivariable plants</li> <li>They can carry out a controller design both in continuous-time and discrete-time domain, and decide which is appropriate for a given sampling rate</li> <li>They can identify transfer function models and state space models of dynamic systems from experimental data</li> <li>They can carry out all these tasks using standard software tools (Matlab Control Toolbox, System Identification Toolbox, Simulink)</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students can work in small groups on specific problems to arrive at joint solutions.		
<i>Autonomy</i>	Students can obtain information from provided sources (lecture notes, software documentation, experiment guides) and use it when solving given problems.		
	They can assess their knowledge in weekly on-line tests and thereby control their learning progress.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Core qualification: Compulsory Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Electrical Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Core qualification: Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Compulsory		

Course L0656: Control Systems Theory and Design	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>State space methods (single-input single-output)</p> <ul style="list-style-type: none"> <li>• State space models and transfer functions, state feedback</li> <li>• Coordinate basis, similarity transformations</li> <li>• Solutions of state equations, matrix exponentials, Caley-Hamilton Theorem</li> <li>• Controllability and pole placement</li> <li>• State estimation, observability, Kalman decomposition</li> <li>• Observer-based state feedback control, reference tracking</li> <li>• Transmission zeros</li> <li>• Optimal pole placement, symmetric root locus</li> </ul> <p>Multi-input multi-output systems</p> <ul style="list-style-type: none"> <li>• Transfer function matrices, state space models of multivariable systems, Gilbert realization</li> <li>• Poles and zeros of multivariable systems, minimal realization</li> <li>• Closed-loop stability</li> <li>• Pole placement for multivariable systems, LQR design, Kalman filter</li> </ul> <p>Digital Control</p> <ul style="list-style-type: none"> <li>• Discrete-time systems: difference equations and z-transform</li> <li>• Discrete-time state space models, sampled data systems, poles and zeros</li> <li>• Frequency response of sampled data systems, choice of sampling rate</li> </ul> <p>System identification and model order reduction</p> <ul style="list-style-type: none"> <li>• Least squares estimation, ARX models, persistent excitation</li> <li>• Identification of state space models, subspace identification</li> <li>• Balanced realization and model order reduction</li> </ul> <p>Case study</p> <ul style="list-style-type: none"> <li>• Modelling and multivariable control of a process evaporator using Matlab and Simulink</li> </ul> <p>Software tools</p> <ul style="list-style-type: none"> <li>• Matlab/Simulink</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Werner, H., Lecture Notes „Control Systems Theory and Design“</li> <li>• T. Kailath "Linear Systems", Prentice Hall, 1980</li> <li>• K.J. Astrom, B. Wittenmark "Computer Controlled Systems" Prentice Hall, 1997</li> <li>• L. Ljung "System Identification - Theory for the User", Prentice Hall, 1999</li> </ul>

Course L0657: Control Systems Theory and Design	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1204: Modelling and Optimization in Dynamics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Flexible Multibody Systems (L1632)	Lecture	2	3
Optimization of dynamical systems (L1633)	Lecture	2	3
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematics I, II, III</li> <li>• Mechanics I, II, III, IV</li> <li>• Simulation of dynamical Systems</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students demonstrate basic knowledge and understanding of modeling, simulation and analysis of complex rigid and flexible multibody systems and methods for optimizing dynamic systems after successful completion of the module.</p> <p><i>Skills</i></p> <p>Students are able</p> <ul style="list-style-type: none"> <li>+ to think holistically</li> <li>+ to independently, securely and critically analyze and optimize basic problems of the dynamics of rigid and flexible multibody systems</li> <li>+ to describe dynamics problems mathematically</li> <li>+ to optimize dynamics problems</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ solve problems in heterogeneous groups and to document the corresponding results.</li> </ul> <p><i>Autonomy</i></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ assess their knowledge by means of exercises.</li> <li>+ acquaint themselves with the necessary knowledge to solve research oriented tasks.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

<b>Course L1632: Flexible Multibody Systems</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Seifried
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Basics of Multibody Systems</li> <li>2. Basics of Continuum Mechanics</li> <li>3. Linear finite element modelles and modell reduction</li> <li>4. Nonlinear finite element Modelles: absolute nodal coordinate formulation</li> <li>5. Kinematics of an elastic body</li> <li>6. Kinetics of an elastic body</li> <li>7. System assembly</li> </ol>
<b>Literature</b>	<p>Schwertassek, R. und Wallrapp, O.: Dynamik flexibler Mehrkörpersysteme. Braunschweig, Vieweg, 1999.</p> <p>Seifried, R.: Dynamics of Underactuated Multibody Systems, Springer, 2014.</p> <p>Shabana, A.A.: Dynamics of Multibody Systems. Cambridge Univ. Press, Cambridge, 2004, 3. Auflage.</p>

<b>Course L1633: Optimization of dynamical systems</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Seifried, Dr. Alexander Held
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Formulation and classification of optimization problems</li> <li>2. Scalar Optimization</li> <li>3. Sensitivity Analysis</li> <li>4. Unconstrained Parameter Optimization</li> <li>5. Constrained Parameter Optimization</li> <li>6. Stochastic optimization</li> <li>7. Multicriteria Optimization</li> <li>8. Topology Optimization</li> </ol>
<b>Literature</b>	<p>Bestle, D.: Analyse und Optimierung von Mehrkörpersystemen. Springer, Berlin, 1994.</p> <p>Nocedal, J. , Wright , S.J. : Numerical Optimization. New York: Springer, 2006.</p>



Module M0939: Control Lab A			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Control Lab I (L1093)	Practical Course	1	1
Control Lab II (L1291)	Practical Course	1	1
Control Lab III (L1665)	Practical Course	1	1
Control Lab IV (L1666)	Practical Course	1	1
<b>Module Responsible</b>	Prof. Herbert Werner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• State space methods</li> <li>• LQG control</li> <li>• H2 and H-infinity optimal control</li> <li>• uncertain plant models and robust control</li> <li>• LPV control</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>• Students can explain the difference between validation of a control loop in simulation and experimental validation</li> </ul> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>• Students are capable of applying basic system identification tools (Matlab System Identification Toolbox) to identify a dynamic model that can be used for controller synthesis</li> <li>• They are capable of using standard software tools (Matlab Control Toolbox) for the design and implementation of LQG controllers</li> <li>• They are capable of using standard software tools (Matlab Robust Control Toolbox) for the mixed-sensitivity design and the implementation of H-infinity optimal controllers</li> <li>• They are capable of representing model uncertainty, and of designing and implementing a robust controller</li> <li>• They are capable of using standard software tools (Matlab Robust Control Toolbox) for the design and the implementation of LPV gain-scheduled controllers</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <ul style="list-style-type: none"> <li>• Students can work in teams to conduct experiments and document the results</li> </ul> <p><i>Autonomy</i></p> <ul style="list-style-type: none"> <li>• Students can independently carry out simulation studies to design and validate control loops</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 64, Study Time in Lecture 56		
<b>Credit points</b>	4		
<b>Examination</b>	Written elaboration		
<b>Examination duration and scale</b>			
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L1093: Control Lab I	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner, Antonio Mendez Gonzalez, Patrick Götsch, Adwait Datar
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Course L1291: Control Lab II	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner, Antonio Mendez Gonzalez, Patrick Götsch, Adwait Datar
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Course L1665: Control Lab III	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner, Antonio Mendez Gonzalez, Patrick Götsch, Adwait Datar
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Course L1666: Control Lab IV	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner, Antonio Mendez Gonzalez, Patrick Götsch, Adwait Datar
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Module M1306: Control Lab C	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Control Lab IX (L1836)	Practical Course 1 1
Control Lab VII (L1834)	Practical Course 1 1
Control Lab VIII (L1835)	Practical Course 1 1
<b>Module Responsible</b>	Prof. Herbert Werner
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• State space methods</li> <li>• LQG control</li> <li>• H2 and H-infinity optimal control</li> <li>• uncertain plant models and robust control</li> <li>• LPV control</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can explain the difference between validation of a control loop in simulation and experimental validation</li> </ul>
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students are capable of applying basic system identification tools (Matlab System Identification Toolbox) to identify a dynamic model that can be used for controller synthesis</li> <li>• They are capable of using standard software tools (Matlab Control Toolbox) for the design and implementation of LQG controllers</li> <li>• They are capable of using standard software tools (Matlab Robust Control Toolbox) for the mixed-sensitivity design and the implementation of H-infinity optimal controllers</li> <li>• They are capable of representing model uncertainty, and of designing and implementing a robust controller</li> <li>• They are capable of using standard software tools (Matlab Robust Control Toolbox) for the design and the implementation of LPV gain-scheduled controllers</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Students can work in teams to conduct experiments and document the results</li> </ul>
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students can independently carry out simulation studies to design and validate control loops</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Credit points</b>	3
<b>Examination</b>	Written elaboration
<b>Examination duration and scale</b>	
<b>Assignment for the Following Curricula</b>	Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L1836: Control Lab IX	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Course L1834: Control Lab VII	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Course L1835: Control Lab VIII	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe/SoSe
<b>Content</b>	One of the offered experiments in control theory.
<b>Literature</b>	Experiment Guides

Module M0714: Numerical Treatment of Ordinary Differential Equations			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Numerical Treatment of Ordinary Differential Equations (L0576)	Lecture	2	3
Numerical Treatment of Ordinary Differential Equations (L0582)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Sabine Le Borne		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematik I, II, III für Ingenieurstudierende (deutsch oder englisch) oder Analysis &amp; Lineare Algebra I + II sowie Analysis III für Technomathematiker</li> <li>• Basic MATLAB knowledge</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><b>Knowledge</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• list numerical methods for the solution of ordinary differential equations and explain their core ideas,</li> <li>• repeat convergence statements for the treated numerical methods (including the prerequisites tied to the underlying problem),</li> <li>• explain aspects regarding the practical execution of a method.</li> <li>• select the appropriate numerical method for concrete problems, implement the numerical algorithms efficiently and interpret the numerical results</li> </ul> <p><b>Skills</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• implement (MATLAB), apply and compare numerical methods for the solution of ordinary differential equations,</li> <li>• to justify the convergence behaviour of numerical methods with respect to the posed problem and selected algorithm,</li> <li>• for a given problem, develop a suitable solution approach, if necessary by the composition of several algorithms, to execute this approach and to critically evaluate the results.</li> </ul> <p><b>Personal Competence</b></p> <p><b>Social Competence</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• work together in heterogeneously composed teams (i.e., teams from different study programs and background knowledge), explain theoretical foundations and support each other with practical aspects regarding the implementation of algorithms.</li> </ul> <p><b>Autonomy</b></p> <p>Students are capable</p> <ul style="list-style-type: none"> <li>• to assess whether the supporting theoretical and practical exercises are better solved individually or in a team,</li> <li>• to assess their individual progress and, if necessary, to ask questions and seek help.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation General Process Engineering: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Compulsory Process Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory		

Course L0576: Numerical Treatment of Ordinary Differential Equations	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Numerical methods for Initial Value Problems <ul style="list-style-type: none"> <li>• single step methods</li> <li>• multistep methods</li> <li>• stiff problems</li> <li>• differential algebraic equations (DAE) of index 1</li> </ul> Numerical methods for Boundary Value Problems <ul style="list-style-type: none"> <li>• initial value methods</li> <li>• multiple shooting method</li> <li>• difference methods</li> <li>• variational methods</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• E. Hairer, S. Noersett, G. Wanner: Solving Ordinary Differential Equations I: Nonstiff Problems</li> <li>• E. Hairer, G. Wanner: Solving Ordinary Differential Equations II: Stiff and Differential-Algebraic Problems</li> </ul>

Course L0582: Numerical Treatment of Ordinary Differential Equations	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0807: Boundary Element Methods			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Boundary Element Methods (L0523)	Lecture	2	3
Boundary Element Methods (L0524)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Otto von Estorff		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Mechanics I (Statics, Mechanics of Materials) and Mechanics II (Hydrostatics, Kinematics, Dynamics) Mathematics I, II, III (in particular differential equations)		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>The students possess an in-depth knowledge regarding the derivation of the boundary element method and are able to give an overview of the theoretical and methodical basis of the method.</p> <p><i>Skills</i></p> <p>The students are capable to handle engineering problems by formulating suitable boundary elements, assembling the corresponding system matrices, and solving the resulting system of equations.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p><i>Autonomy</i></p> <p>The students are able to independently solve challenging computational problems and develop own boundary element routines. Problems can be identified and the results are critically scrutinized.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Civil Engineering: Specialisation Structural Engineering: Elective Compulsory Civil Engineering: Specialisation Geotechnical Engineering: Elective Compulsory Civil Engineering: Specialisation Coastal Engineering: Elective Compulsory Energy Systems: Core qualification: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mechanical Engineering and Management: Specialisation Product Development and Production: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Technomathematics: Specialisation III. Engineering Science: Elective Compulsory Technomathematics: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0523: Boundary Element Methods	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Boundary value problems</li> <li>- Integral equations</li> <li>- Fundamental Solutions</li> <li>- Element formulations</li> <li>- Numerical integration</li> <li>- Solving systems of equations (statics, dynamics)</li> <li>- Special BEM formulations</li> <li>- Coupling of FEM and BEM</li> <li>- Hands-on Sessions (programming of BE routines)</li> <li>- Applications</li> </ul>
<b>Literature</b>	Gaul, L.; Fiedler, Ch. (1997): Methode der Randlelemente in Statik und Dynamik. Vieweg, Braunschweig, Wiesbaden Bathe, K.-J. (2000): Finite-Elemente-Methoden. Springer Verlag, Berlin

<b>Course L0524: Boundary Element Methods</b>	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course



<b>Module M0906: Molecular Modeling and Computational Fluid Dynamics</b>	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Computational Fluid Dynamics - Exercises in OpenFoam (L1375)	Recitation Section (small)
Computational Fluid Dynamics in Process Engineering (L1052)	Lecture
Statistical Thermodynamics and Molecular Modelling (L0099)	Lecture
<b>Hrs/wk</b>	<b>CP</b>
1	1
2	2
2	3
<b>Module Responsible</b>	Prof. Michael Schlüter
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematics I-IV</li> <li>• Basic knowledge in Fluid Mechanics</li> <li>• Basic knowledge in chemical thermodynamics</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p>After successful completion of the module the students are able to</p> <p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>• explain the the basic principles of statistical thermodynamics (ensembles, simple systems)</li> <li>• describe the main approaches in classical Molecular Modeling (Monte Carlo, Molecular Dynamics) in various ensembles</li> <li>• discuss examples of computer programs in detail,</li> <li>• evaluate the application of numerical simulations,</li> <li>• list the possible start and boundary conditions for a numerical simulation.</li> </ul> <p><i>Skills</i></p> <p>The students are able to:</p> <ul style="list-style-type: none"> <li>• set up computer programs for solving simple problems by Monte Carlo or molecular dynamics,</li> <li>• solve problems by molecular modeling,</li> <li>• set up a numerical grid,</li> <li>• perform a simple numerical simulation with OpenFoam,</li> <li>• evaluate the result of a numerical simulation.</li> </ul> <p><b>Personal Competence</b></p> <p>The students are able to</p> <ul style="list-style-type: none"> <li>• develop joint solutions in mixed teams and present them in front of the other students,</li> <li>• to collaborate in a team and to reflect their own contribution toward it.</li> </ul> <p><i>Social Competence</i></p> <p>The students are able to:</p> <ul style="list-style-type: none"> <li>• evaluate their learning progress and to define the following steps of learning on that basis,</li> <li>• evaluate possible consequences for their profession.</li> </ul> <p><i>Autonomy</i></p>
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	1h examen in teams
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Bioprocess Engineering: Specialisation B - Industrial Bioprocess Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation General Process Engineering: Elective Compulsory Energy and Environmental Engineering: Specialisation Energy and Environmental Engineering: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory

Course L1375: Computational Fluid Dynamics - Exercises in OpenFoam	
Typ	Recitation Section (small)
Hrs/wk	1
CP	1
Workload in Hours	Independent Study Time 16, Study Time in Lecture 14
Lecturer	Prof. Michael Schlüter
Language	EN
Cycle	SoSe
Content	<ul style="list-style-type: none"> <li>• generation of numerical grids with a common grid generator</li> <li>• selection of models and boundary conditions</li> <li>• basic numerical simulation with OpenFoam within the TUHH CIP-Pool</li> </ul>
Literature	OpenFoam Tutorials (StudIP)

Course L1052: Computational Fluid Dynamics in Process Engineering	
Typ	Lecture
Hrs/wk	2
CP	2
Workload in Hours	Independent Study Time 32, Study Time in Lecture 28
Lecturer	Prof. Michael Schlüter
Language	EN
Cycle	SoSe
Content	<ul style="list-style-type: none"> <li>• Introduction into partial differential equations</li> <li>• Basic equations</li> <li>• Boundary conditions and grids</li> <li>• Numerical methods</li> <li>• Finite difference method</li> <li>• Finite volume method</li> <li>• Time discretisation and stability</li> <li>• Population balance</li> <li>• Multiphase Systems</li> <li>• Modeling of Turbulent Flows</li> <li>• Exercises: Stability Analysis</li> <li>• Exercises: Example on CFD - analytically/numerically</li> </ul>
Literature	<p>Paschedag A.R.: CFD in der Verfahrenstechnik: Allgemeine Grundlagen und mehrphasige Anwendungen, Wiley-VCH, 2004 ISBN 3-527-30994-2.</p> <p>Ferziger, J.H.; Peric, M.: Numerische Strömungsmechanik. Springer-Verlag, Berlin, 2008, ISBN: 3540675868.</p> <p>Ferziger, J.H.; Peric, M.: Computational Methods for Fluid Dynamics. Springer, 2002, ISBN 3-540-42074-6</p>

Course L0099: Statistical Thermodynamics and Molecular Modelling	
Typ	Lecture
Hrs/wk	2
CP	3
Workload in Hours	Independent Study Time 62, Study Time in Lecture 28
Lecturer	Dr. Sven Jakobtorweihen
Language	EN
Cycle	SoSe
Content	<ul style="list-style-type: none"> <li>• <b>Some lectures will be carried out as computer exercises</b></li> <li>• Introduction to Statistical Mechanics</li> <li>• The ensemble concept</li> <li>• The classical limit</li> <li>• Intermolecular potentials, force fields</li> <li>• Monte Carlo simulations (acceptance rules) (Übungen im Rechnerpool) (exercises in computer pool)</li> <li>• Molecular Dynamics Simulations (integration of equations of motion, calculating transport properties) (exercises in computer pool)</li> <li>• Molecular simulation of Phase equilibria (Gibbs Ensemble)</li> <li>• Methods for the calculation of free energies</li> </ul>
Literature	<p>Daan Frenkel, Berend Smit: Understanding Molecular Simulation, Academic Press</p> <p>M. P. Allen, D. J. Tildesley: Computer Simulations of Liquids, Oxford Univ. Press</p> <p>A.R. Leach: Molecular Modelling - Principles and Applications, Prentice Hall, N.Y.</p> <p>D. A. McQuarrie: Statistical Mechanics, University Science Books</p> <p>T. L. Hill: Statistical Mechanics, Dover Publications</p>

Module M1203: Applied Dynamics: Numerical and experimental methods	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Lab Applied Dynamics (L1631)	Laboratory
Applied Dynamics (L1630)	Lecture
	<b>Hrs/wk</b>
	3
	2
	<b>CP</b>
	3
<b>Module Responsible</b>	Prof. Robert Seifried
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Mathematics I, II, III, Mechanics I, II, III, IV Numerical Treatment of Ordinary Differential Equations
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><i>Knowledge</i> Students can represent the most important methods of dynamics after successful completion of the module Technical dynamics and have a good understanding of the main concepts in the technical dynamics.</p> <p><i>Skills</i> Students are able            + to think holistically            + to independently, securely and critically analyze and optimize basic problems of the dynamics of rigid and flexible multibody systems            + to describe dynamics problems mathematically            + to investigate dynamics problems both experimentally and numerically</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> Students are able to            + solve problems in heterogeneous groups and to document the corresponding results.</p> <p><i>Autonomy</i> Students are able to            + assess their knowledge by means of exercises and experiments.            + acquaint themselves with the necessary knowledge to solve research oriented tasks.</p>
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 min
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Core qualification: Compulsory

Course L1631: Lab Applied Dynamics	
<b>Typ</b>	Laboratory
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Robert Seifried, Dr. Marc-André Pick
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Practical exercises are performed in groups. The examples are taken from different areas of applied dynamics, such as numerical simulation, experimental validation and experimental vibration analysis.
<b>Literature</b>	Schiehlen, W.; Eberhard, P.: Technische Dynamik, 4. Auflage, Vieweg+Teubner: Wiesbaden, 2014.

Course L1630: Applied Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Seifried
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Modelling of Multibody Systems</li> <li>2. Basics from kinematics and kinetics</li> <li>3. Constraints</li> <li>4. Multibody systems in minimal coordinates</li> <li>5. State space, linearization and modal analysis</li> <li>6. Multibody systems with kinematic constraints</li> <li>7. Multibody systems as DAE</li> <li>8. Non-holonomic multibody systems</li> <li>9. Experimental Methods in Dynamics</li> </ol>
<b>Literature</b>	<p>Schiehlen, W.; Eberhard, P.: Technische Dynamik, 4. Auflage, Vieweg+Teubner: Wiesbaden, 2014.</p> <p>Woernle, C.: Mehrkörpersysteme, Springer: Heidelberg, 2011.</p> <p>Seifried, R.: Dynamics of Underactuated Multibody Systems, Springer, 2014.</p>

Module M0752: Nonlinear Dynamics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Nonlinear Dynamics (L0702)	Lecture
	<b>Hrs/wk</b>
	4
	<b>CP</b>
	6
<b>Module Responsible</b>	Prof. Norbert Hoffmann
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Calculus</li> <li>• Linear Algebra</li> <li>• Engineering Mechanics</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to reflect existing terms and concepts in Nonlinear Dynamics and to develop and research new terms and concepts.
<i>Skills</i>	Students are able to apply existing methods and procedures of Nonlinear Dynamics and to develop novel methods and procedures.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students can reach working results also in groups.
<i>Autonomy</i>	Students are able to approach given research tasks individually and to identify and follow up novel research tasks by themselves.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	2 Hours
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L0702: Nonlinear Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Norbert Hoffmann
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Fundamentals of Nonlinear Dynamics.
<b>Literature</b>	S. Strogatz: Nonlinear Dynamics and Chaos. Perseus, 2013.

Module M1339: Design optimization and probabilistic approaches in structural analysis			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Design Optimization and Probabilistic Approaches in Structural Analysis (L1873)	Lecture	2	3
Design Optimization and Probabilistic Approaches in Structural Analysis (L1874)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Benedikt Kriegesmann		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Technical mechanics</li> <li>• Higher math</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Design optimization               <ul style="list-style-type: none"> <li>◦ Gradient based methods</li> <li>◦ Genetic algorithms</li> <li>◦ Optimization with constraints</li> <li>◦ Topology optimization</li> </ul> </li> <li>• Reliability analysis               <ul style="list-style-type: none"> <li>◦ Stochastic basics</li> <li>◦ Monte Carlo methods</li> <li>◦ Semi-analytic approaches</li> </ul> </li> <li>• robust design optimization               <ul style="list-style-type: none"> <li>◦ Robustness measures</li> <li>◦ Coupling of design optimization and reliability analysis</li> </ul> </li> </ul>		
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Application of optimization algorithms and probabilistic methods in the design of structures</li> <li>• Programming with Matlab</li> <li>• Implementation of algorithms</li> <li>• Debugging</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Team work</li> <li>• Oral explanation of the the work</li> </ul>		
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Application of methods learned in the framework of a home work</li> <li>• Familiarizing with source code provided</li> <li>• Description of approaches and results</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written elaboration		
<b>Examination duration and scale</b>			
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L1873: Design Optimization and Probabilistic Approaches in Structural Analysis	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Benedikt Kriegesmann
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>In the course the theoretic basics for design optimization and reliability analysis are taught, where the focus is on the application of such methods. The lectures will consist of presentations as well as computer exercises. In the computer exercises, the methods learned will be implemented in Matlab for understanding the practical realization.</p> <p>The following contents will be considered:</p> <ul style="list-style-type: none"> <li>• Design optimization           <ul style="list-style-type: none"> <li>◦ Gradient based methods</li> <li>◦ Genetic algorithms</li> <li>◦ Optimization with constraints</li> <li>◦ Topology optimization</li> </ul> </li> <li>• Reliability analysis           <ul style="list-style-type: none"> <li>◦ Stochastic basics</li> <li>◦ Monte Carlo methods</li> <li>◦ Semi-analytic approaches</li> </ul> </li> <li>• robust design optimization           <ul style="list-style-type: none"> <li>◦ Robustness measures</li> <li>◦ Coupling of design optimization and reliability analysis</li> </ul> </li> </ul>
<b>Literature</b>	<p>[1] Arora, Jasbir. Introduction to Optimum Design. 3rd ed. Boston, MA: Academic Press, 2011.</p> <p>[2] Haldar, A., and S. Mahadevan. Probability, Reliability, and Statistical Methods in Engineering Design. John Wiley &amp; Sons New York/Chichester, UK, 2000.</p>

Course L1874: Design Optimization and Probabilistic Approaches in Structural Analysis	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Benedikt Kriegesmann
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Matlab exercises complementing the lecture
<b>Literature</b>	siehe Vorlesung

Module M0835: Humanoid Robotics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Humanoid Robotics (L0663)	Seminar
<b>Hrs/wk</b>	<b>CP</b>
2	2
<b>Module Responsible</b>	Prof. Herbert Werner
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Introduction to control systems</li> <li>• Control theory and design</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can explain humanoid robots.</li> <li>• Students learn to apply basic control concepts for different tasks in humanoid robotics.</li> </ul>
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students acquire knowledge about selected aspects of humanoid robotics, based on specified literature</li> <li>• Students generalize developed results and present them to the participants</li> <li>• Students practice to prepare and give a presentation</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Students are capable of developing solutions in interdisciplinary teams and present them</li> <li>• They are able to provide appropriate feedback and handle constructive criticism of their own results</li> </ul>
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students evaluate advantages and drawbacks of different forms of presentation for specific tasks and select the best solution</li> <li>• Students familiarize themselves with a scientific field, are able of introduce it and follow presentations of other students, such that a scientific discussion develops</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Credit points</b>	2
<b>Examination</b>	Presentation
<b>Examination duration and scale</b>	30 min
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L0663: Humanoid Robotics	
<b>Typ</b>	Seminar
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Grundlagen der Regelungstechnik</li> <li>• Control systems theory and design</li> </ul>
<b>Literature</b>	- B. Siciliano, O. Khatib. "Handbook of Robotics. Part A: Robotics Foundations", Springer (2008).



Module M0838: Linear and Nonlinear System Identifikation	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Linear and Nonlinear System Identification (L0660)	Lecture
	<b>Hrs/wk</b>
	2
	<b>CP</b>
	3
<b>Module Responsible</b>	Prof. Herbert Werner
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Classical control (frequency response, root locus)</li> <li>• State space methods</li> <li>• Discrete-time systems</li> <li>• Linear algebra, singular value decomposition</li> <li>• Basic knowledge about stochastic processes</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can explain the general framework of the prediction error method and its application to a variety of linear and nonlinear model structures</li> <li>• They can explain how multilayer perceptron networks are used to model nonlinear dynamics</li> <li>• They can explain how an approximate predictive control scheme can be based on neural network models</li> <li>• They can explain the idea of subspace identification and its relation to Kalman realisation theory</li> </ul>
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students are capable of applying the prediction error method to the experimental identification of linear and nonlinear models for dynamic systems</li> <li>• They are capable of implementing a nonlinear predictive control scheme based on a neural network model</li> <li>• They are capable of applying subspace algorithms to the experimental identification of linear models for dynamic systems</li> <li>• They can do the above using standard software tools (including the Matlab System Identification Toolbox)</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	Students can work in mixed groups on specific problems to arrive at joint solutions.
<i>Autonomy</i>	Students are able to find required information in sources provided (lecture notes, literature, software documentation) and use it to solve given problems.
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Credit points</b>	3
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	30 min
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Compulsory Mechanical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L0660: Linear and Nonlinear System Identification	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Prediction error method</li> <li>• Linear and nonlinear model structures</li> <li>• Nonlinear model structure based on multilayer perceptron network</li> <li>• Approximate predictive control based on multilayer perceptron network model</li> <li>• Subspace identification</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Lennart Ljung, System Identification - Theory for the User, Prentice Hall 1999</li> <li>• M. Norgaard, O. Ravn, N.K. Poulsen and L.K. Hansen, Neural Networks for Modeling and Control of Dynamic Systems, Springer Verlag, London 2003</li> <li>• T. Kailath, A.H. Sayed and B. Hassibi, Linear Estimation, Prentice Hall 2000</li> </ul>

Module M0657: Computational Fluid Dynamics II			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Computational Fluid Dynamics II (L0237)	Lecture	2	3
Computational Fluid Dynamics II (L0421)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Thomas Rung		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basics of computational and general thermo/fluid dynamics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Establish a thorough understanding of Finite-Volume approaches. Familiarise with details of the theoretical background of complex CFD algorithms.</p> <p><i>Skills</i> Ability to manage of interface problems and build-up of coding skills. Ability to evaluate, assess and benchmark different solution options.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i> Practice of team working during team exercises.</p> <p><i>Autonomy</i> Independent analysis of specific solution approaches.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	0.5h-0.75h		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L0237: Computational Fluid Dynamics II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Computational Modelling of complex single- and multiphase flows using higher-order approximations for unstructured grids and meshless particle-based methods.
<b>Literature</b>	

Course L0421: Computational Fluid Dynamics II	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0840: Optimal and Robust Control			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Optimal and Robust Control (L0658)	Lecture	2	3
Optimal and Robust Control (L0659)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Herbert Werner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Classical control (frequency response, root locus)</li> <li>• State space methods</li> <li>• Linear algebra, singular value decomposition</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>• Students can explain the significance of the matrix Riccati equation for the solution of LQ problems.</li> <li>• They can explain the duality between optimal state feedback and optimal state estimation.</li> <li>• They can explain how the H2 and H-infinity norms are used to represent stability and performance constraints.</li> <li>• They can explain how an LQG design problem can be formulated as special case of an H2 design problem.</li> <li>• They can explain how model uncertainty can be represented in a way that lends itself to robust controller design</li> <li>• They can explain how - based on the small gain theorem - a robust controller can guarantee stability and performance for an uncertain plant.</li> <li>• They understand how analysis and synthesis conditions on feedback loops can be represented as linear matrix inequalities.</li> </ul> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>• Students are capable of designing and tuning LQG controllers for multivariable plant models.</li> <li>• They are capable of representing a H2 or H-infinity design problem in the form of a generalized plant, and of using standard software tools for solving it.</li> <li>• They are capable of translating time and frequency domain specifications for control loops into constraints on closed-loop sensitivity functions, and of carrying out a mixed-sensitivity design.</li> <li>• They are capable of constructing an LFT uncertainty model for an uncertain system, and of designing a mixed-objective robust controller.</li> <li>• They are capable of formulating analysis and synthesis conditions as linear matrix inequalities (LMI), and of using standard LMI-solvers for solving them.</li> <li>• They can carry out all of the above using standard software tools (Matlab robust control toolbox).</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> Students can work in small groups on specific problems to arrive at joint solutions.</p> <p><i>Autonomy</i> Students are able to find required information in sources provided (lecture notes, literature, software documentation) and use it to solve given problems.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L0658: Optimal and Robust Control	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Optimal regulator problem with finite time horizon, Riccati differential equation</li> <li>• Time-varying and steady state solutions, algebraic Riccati equation, Hamiltonian system</li> <li>• Kalman's identity, phase margin of LQR controllers, spectral factorization</li> <li>• Optimal state estimation, Kalman filter, LQG control</li> <li>• Generalized plant, review of LQG control</li> <li>• Signal and system norms, computing H2 and H<math>\infty</math> norms</li> <li>• Singular value plots, input and output directions</li> <li>• Mixed sensitivity design, H<math>\infty</math> loop shaping, choice of weighting filters</li> <li>• Case study: design example flight control</li> <li>• Linear matrix inequalities, design specifications as LMI constraints (H2, H<math>\infty</math> and pole region)</li> <li>• Controller synthesis by solving LMI problems, multi-objective design</li> <li>• Robust control of uncertain systems, small gain theorem, representation of parameter uncertainty</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Werner, H., Lecture Notes: "Optimale und Robuste Regelung"</li> <li>• Boyd, S., L. El Ghaoui, E. Feron and V. Balakrishnan "Linear Matrix Inequalities in Systems and Control", SIAM, Philadelphia, PA, 1994</li> <li>• Skogestad, S. and I. Postlewaite "Multivariable Feedback Control", John Wiley, Chichester, England, 1996</li> <li>• Strang, G. "Linear Algebra and its Applications", Harcourt Brace Jovanovic, Orlando, FA, 1988</li> <li>• Zhou, K. and J. Doyle "Essentials of Robust Control", Prentice Hall International, Upper Saddle River, NJ, 1998</li> </ul>

Course L0659: Optimal and Robust Control	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0605: Computational Structural Dynamics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Computational Structural Dynamics (L0282)	Lecture
Computational Structural Dynamics (L0283)	Recitation Section (small)
	<b>Hrs/wk</b>
	3
	1
	<b>CP</b>
	4
	2
<b>Module Responsible</b>	Prof. Alexander Düster
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Mathematics I, II, III, Mechanics I, II, III, IV Differential Equations 2 (Partial Differential Equations)
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to + give an overview of the computational procedures for problems of structural dynamics. + explain the application of finite element programs to solve problems of structural dynamics. + specify problems of computational structural dynamics, to identify them in a given situation and to explain their mathematical and mechanical background.
<i>Skills</i>	Students are able to + model problems of structural dynamics. + select a suitable solution procedure for a given problem of structural dynamics. + apply computational procedures to solve problems of structural dynamics. + verify and critically judge results of computational structural dynamics.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to + solve problems in heterogeneous groups and to document the corresponding results.
<i>Autonomy</i>	Students are able to + assess their knowledge by means of exercises and E-Learning.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	2h
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Materials Science: Specialisation Modeling: Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L0282: Computational Structural Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	1. Motivation 2. Basics of dynamics 3. Time integration methods 4. Modal analysis 5. Fourier transform 6. Applications
<b>Literature</b>	[1] K.-J. Bathe, Finite-Elemente-Methoden, Springer, 2002. [2] J.L. Humar, Dynamics of Structures, Taylor & Francis, 2012.

Course L0283: Computational Structural Dynamics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0604: High-Order FEM	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
High-Order FEM (L0280)	Lecture
High-Order FEM (L0281)	Recitation Section (large)
<b>Hrs/wk</b>	<b>CP</b>
3	4
1	2
<b>Module Responsible</b>	Prof. Alexander Düster
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Mathematics I, II, III, Mechanics I, II, III, IV Differential Equations 2 (Partial Differential Equations)
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to + give an overview of the different (h, p, hp) finite element procedures. + explain high-order finite element procedures. + specify problems of finite element procedures, to identify them in a given situation and to explain their mathematical and mechanical background.
<i>Skills</i>	Students are able to + apply high-order finite elements to problems of structural mechanics. + select for a given problem of structural mechanics a suitable finite element procedure. + critically judge results of high-order finite elements. + transfer their knowledge of high-order finite elements to new problems.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to + solve problems in heterogeneous groups and to document the corresponding results.
<i>Autonomy</i>	Students are able to + assess their knowledge by means of exercises and E-Learning. + acquaint themselves with the necessary knowledge to solve research oriented tasks.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Materials Science: Specialisation Modeling: Elective Compulsory Mechanical Engineering and Management: Specialisation Product Development and Production: Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory

Course L0280: High-Order FEM	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	1. Introduction 2. Motivation 3. Hierarchic shape functions 4. Mapping functions 5. Computation of element matrices, assembly, constraint enforcement and solution 6. Convergence characteristics 7. Mechanical models and finite elements for thin-walled structures 8. Computation of thin-walled structures 9. Error estimation and hp-adaptivity 10. High-order fictitious domain methods
<b>Literature</b>	[1] Alexander Düster, High-Order FEM, Lecture Notes, Technische Universität Hamburg-Harburg, 164 pages, 2014 [2] Barna Szabo, Ivo Babuska, Introduction to Finite Element Analysis – Formulation, Verification and Validation, John Wiley & Sons, 2011

Course L0281: High-Order FEM	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0603: Nonlinear Structural Analysis	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Nonlinear Structural Analysis (L0277)	Lecture 3 4
Nonlinear Structural Analysis (L0279)	Recitation Section (small) 1 2
<b>Module Responsible</b>	Prof. Alexander Düster
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Knowledge of partial differential equations is recommended.
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><b>Knowledge</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ give an overview of the different nonlinear phenomena in structural mechanics.</li> <li>+ explain the mechanical background of nonlinear phenomena in structural mechanics.</li> <li>+ to specify problems of nonlinear structural analysis, to identify them in a given situation and to explain their mathematical and mechanical background.</li> </ul> <p><b>Skills</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ model nonlinear structural problems.</li> <li>+ select for a given nonlinear structural problem a suitable computational procedure.</li> <li>+ apply finite element procedures for nonlinear structural analysis.</li> <li>+ critically verify and judge results of nonlinear finite elements.</li> <li>+ to transfer their knowledge of nonlinear solution procedures to new problems.</li> </ul> <p><b>Personal Competence</b></p> <p><b>Social Competence</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ solve problems in heterogeneous groups and to document the corresponding results.</li> <li>+ share new knowledge with group members.</li> </ul> <p><b>Autonomy</b></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>+ acquire independently knowledge to solve complex problems.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Civil Engineering: Specialisation Structural Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Civil Engineering: Elective Compulsory Materials Science: Specialisation Modeling: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Ship and Offshore Technology: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0277: Nonlinear Structural Analysis	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	1. Introduction 2. Nonlinear phenomena 3. Mathematical preliminaries 4. Basic equations of continuum mechanics 5. Spatial discretization with finite elements 6. Solution of nonlinear systems of equations 7. Solution of elastoplastic problems 8. Stability problems 9. Contact problems
<b>Literature</b>	[1] Alexander Düster, Nonlinear Structural Analysis, Lecture Notes, Technische Universität Hamburg-Harburg, 2014. [2] Peter Wriggers, Nonlinear Finite Element Methods, Springer 2008. [3] Peter Wriggers, Nichtlineare Finite-Elemente-Methoden, Springer 2001. [4] Javier Bonet and Richard D. Wood, Nonlinear Continuum Mechanics for Finite Element Analysis, Cambridge University Press, 2008.



Course L0279: Nonlinear Structural Analysis	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Module M0832: Advanced Topics in Control</b>			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Advanced Topics in Control (L0661)	Lecture	2	3
Advanced Topics in Control (L0662)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Herbert Werner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	H-infinity optimal control, mixed-sensitivity design, linear matrix inequalities		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<ul style="list-style-type: none"> <li>• Students can explain the advantages and shortcomings of the classical gain scheduling approach</li> <li>• They can explain the representation of nonlinear systems in the form of quasi-LPV systems</li> <li>• They can explain how stability and performance conditions for LPV systems can be formulated as LMI conditions</li> <li>• They can explain how gridding techniques can be used to solve analysis and synthesis problems for LPV systems</li> <li>• They are familiar with polytopic and LFT representations of LPV systems and some of the basic synthesis techniques associated with each of these model structures</li> </ul>		
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can explain how graph theoretic concepts are used to represent the communication topology of multiagent systems</li> <li>• They can explain the convergence properties of first order consensus protocols</li> <li>• They can explain analysis and synthesis conditions for formation control loops involving either LTI or LPV agent models</li> </ul>		
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students can explain the state space representation of spatially invariant distributed systems that are discretized according to an actuator/sensor array</li> <li>• They can explain (in outline) the extension of the bounded real lemma to such distributed systems and the associated synthesis conditions for distributed controllers</li> </ul> <ul style="list-style-type: none"> <li>• Students are capable of constructing LPV models of nonlinear plants and carry out a mixed-sensitivity design of gain-scheduled controllers; they can do this using polytopic, LFT or general LPV models</li> <li>• They are able to use standard software tools (Matlab robust control toolbox) for these tasks</li> </ul> <ul style="list-style-type: none"> <li>• Students are able to design distributed formation controllers for groups of agents with either LTI or LPV dynamics, using Matlab tools provided</li> </ul> <ul style="list-style-type: none"> <li>• Students are able to design distributed controllers for spatially interconnected systems, using the Matlab MD-toolbox</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students can work in small groups and arrive at joint results.		
<i>Autonomy</i>	Students are able to find required information in sources provided (lecture notes, literature, software documentation) and use it to solve given problems.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Avionic and Embedded Systems: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0661: Advanced Topics in Control	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Linear Parameter-Varying (LPV) Gain Scheduling               <ul style="list-style-type: none"> <li>- Linearizing gain scheduling, hidden coupling</li> <li>- Jacobian linearization vs. quasi-LPV models</li> <li>- Stability and induced L2 norm of LPV systems</li> <li>- Synthesis of LPV controllers based on the two-sided projection lemma</li> <li>- Simplifications: controller synthesis for polytopic and LFT models</li> <li>- Experimental identification of LPV models</li> <li>- Controller synthesis based on input/output models</li> <li>- Applications: LPV torque vectoring for electric vehicles, LPV control of a robotic manipulator</li> </ul> </li> <li>• Control of Multi-Agent Systems               <ul style="list-style-type: none"> <li>- Communication graphs</li> <li>- Spectral properties of the graph Laplacian</li> <li>- First and second order consensus protocols</li> <li>- Formation control, stability and performance</li> <li>- LPV models for agents subject to nonholonomic constraints</li> <li>- Application: formation control for a team of quadrotor helicopters</li> </ul> </li> <li>• Control of Spatially Interconnected Systems               <ul style="list-style-type: none"> <li>- Multidimensional signals, l2 and L2 signal norm</li> <li>- Multidimensional systems in Roesser state space form</li> <li>- Extension of real-bounded lemma to spatially interconnected systems</li> <li>- LMI-based synthesis of distributed controllers</li> <li>- Spatial LPV control of spatially varying systems</li> <li>- Applications: control of temperature profiles, vibration damping for an actuated beam</li> </ul> </li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Werner, H., Lecture Notes "Advanced Topics in Control"</li> <li>• Selection of relevant research papers made available as pdf documents via StudIP</li> </ul>

Course L0662: Advanced Topics in Control	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Module M1181: Research Project Theoretical Mechanical Engineering</b>	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
<b>Module Responsible</b>	Dozenten des SD M
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Finite-element-methods</li> <li>• Control systems theory and design</li> <li>• Applied dynamics</li> <li>• Numerics of ordinary differential equations</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p>The students are able to demonstrate their detailed knowledge in the field of theoretical mechanical engineering. They can exemplify the state of technology and application and discuss critically in the context of actual problems and general conditions of science and society.</p> <p><i>Knowledge</i> The students can develop solving strategies and approaches for fundamental and practical problems in theoretical mechanical engineering. They may apply theory based procedures and integrate safety-related, ecological, ethical, and economic view points of science and society.</p> <p><i>Skills</i> Scientific work techniques that are used can be described and critically reviewed.</p> <p>The students are able to independently select methods for the project work and to justify this choice. They can explain how these methods relate to the field of work and how the context of application has to be adjusted. General findings and further developments may essentially be outlined.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> The students are able to condense the relevance and the structure of the project work, the work steps and the sub-problems for the presentation and discussion in front of a bigger group. They can lead the discussion and give a feedback on the project to their colleagues.</p> <p><i>Autonomy</i> The students are capable of independently planning and documenting the work steps and procedures while considering the given deadlines. This includes the ability to accurately procure the newest scientific information. Furthermore, they can obtain feedback from experts with regard to the progress of the work, and to accomplish results on the state of the art in science and technology.</p>
<b>Workload in Hours</b>	Independent Study Time 360, Study Time in Lecture 0
<b>Credit points</b>	12
<b>Examination</b>	Study work
<b>Examination duration and scale</b>	according to FSPO
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Core qualification: Compulsory

Module M1398: Selected Topics in Multibody Dynamics and Robotics			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	<b>Hrs/wk</b> <b>CP</b>
Formulas and Vehicles - Mathematics and Mechanics in Autonomous Driving (L1981)		Project-/problem-based Learning	2            6
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Mechanics IV, Applied Dynamics or Robotics Numerical Treatment of Ordinary Differential Equations Control Systems Theory and Design		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> After successful completion of the module students demonstrate deeper knowledge and understanding in selected application areas of multibody dynamics and robotics</p> <p>Students are able</p> <ul style="list-style-type: none"> <li>+ to think holistically</li> </ul> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>+ to independently, securely and critically analyze and optimize basic problems of the dynamics of rigid and flexible multibody systems</li> <li>+ to describe dynamics problems mathematically</li> <li>+ to implement dynamical problems on hardware</li> </ul> <p><b>Personal Competence</b></p> <p>Students are able to</p> <p><i>Social Competence</i></p> <ul style="list-style-type: none"> <li>+ solve problems in heterogeneous groups and to document the corresponding results and present them</li> </ul> <p>Students are able to</p> <p><i>Autonomy</i></p> <ul style="list-style-type: none"> <li>+ assess their knowledge by means of exercises and projects.</li> <li>+ acquaint themselves with the necessary knowledge to solve research oriented tasks.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 152, Study Time in Lecture 28		
<b>Credit points</b>	6		
<b>Examination</b>	Presentation		
<b>Examination duration and scale</b>	TBA		
<b>Assignment for the Following Curricula</b>	Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L1981: Formulas and Vehicles - Mathematics and Mechanics in Autonomous Driving	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 152, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Seifried
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	Seifried, R.: Dynamics of underactuated multibody systems, Springer, 2014 Popp, K.; Schiehlen, W.: Ground vehicle dynamics, Springer, 2010

Module M1150: Continuum Mechanics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Continuum Mechanics (L1533)	Lecture	2	3
Continuum Mechanics Exercise (L1534)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Christian Cyron		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basics of linear continuum mechanics as taught, e.g., in the module Mechanics II (forces and moments, stress, linear strain, free-body principle, linear-elastic constitutive laws, strain energy).		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	The students can explain the fundamental concepts to calculate the mechanical behavior of materials.		
<i>Skills</i>	The students can set up balance laws and apply basics of deformation theory to specific aspects, both in applied contexts as in research contexts.		
<b>Personal Competence</b>			
<i>Social Competence</i>	The students are able to develop solutions, to present them to specialists in written form and to develop ideas further.		
<i>Autonomy</i>	The students are able to assess their own strengths and weaknesses. They can independently and on their own identify and solve problems in the area of continuum mechanics and acquire the knowledge required to this end.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	45 min		
<b>Assignment for the Following Curricula</b>	Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Materials Science: Specialisation Modeling: Elective Compulsory Mechanical Engineering and Management: Specialisation Materials: Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Core qualification: Elective Compulsory		

Course L1533: Continuum Mechanics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Christian Cyron
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• kinematics of undeformed and deformed bodies</li> <li>• balance equations (balance of mass, balance of energy, ...)</li> <li>• stress states</li> <li>• material modelling</li> </ul>
<b>Literature</b>	R. Greve: Kontinuumsmechanik: Ein Grundkurs für Ingenieure und Physiker I-S. Liu: Continuum Mechanics, Springer

<b>Course L1534: Continuum Mechanics Exercise</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Christian Cyron
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• kinematics of undeformed and deformed bodies</li> <li>• balance equations (balance of mass, balance of energy, ...)</li> <li>• stress states</li> <li>• material modelling</li> </ul>
<b>Literature</b>	R. Greve: Kontinuumsmechanik: Ein Grundkurs für Ingenieure und Physiker I-S. Liu: Continuum Mechanics, Springer

## Specialization Bio- and Medical Technology

The specialization „biotechnology and medical technology“ consists of modules for Intelligent Systems, Robotics and Navigation in medicine, supplemented by Endoprotheses and Materials and Regenerative Medicine, and completed by the modules Imaging Systems in medicine and Industrial Image Transformations in electives. Thus, the acquisition of knowledge and skills in engineering specific aspects of biotechnology and medical technology is at the heart of this specialization. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M1334: BIO II: Biomaterials	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Biomaterials (L0593)	Lecture
<b>Hrs/wk</b>	<b>CP</b>
2	3
<b>Module Responsible</b>	Prof. Michael Morlock
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	
<i>Skills</i>	
<b>Personal Competence</b>	
<i>Social Competence</i>	
<i>Autonomy</i>	
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Credit points</b>	3
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 min
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Process Engineering and Biotechnology: Elective Compulsory Materials Science: Specialisation Nano and Hybrid Materials: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprotheses: Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory



Course L0593: Biomaterials	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Michael Morlock
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Topics to be covered include:</p> <ol style="list-style-type: none"> <li>1. Introduction (Importance, nomenclature, relations)</li> <li>2. Biological materials               <ol style="list-style-type: none"> <li>2.1 Basics (components, testing methods)</li> <li>2.2 Bone (composition, development, properties, influencing factors)</li> <li>2.3 Cartilage (composition, development, structure, properties, influencing factors)</li> <li>2.4 Fluids (blood, synovial fluid)</li> </ol> </li> <li>3. Biological structures               <ol style="list-style-type: none"> <li>3.1 Menisci of the knee joint</li> <li>3.2 Intervertebral discs</li> <li>3.3 Teeth</li> <li>3.4 Ligaments</li> <li>3.5 Tendons</li> </ol> </li> <li>3.6 Skin</li> <li>3.7 Nerves</li> <li>3.8 Muscles</li> <li>4. Replacement materials               <ol style="list-style-type: none"> <li>4.1 Basics (history, requirements, norms)</li> <li>4.2 Steel (alloys, properties, reaction of the body)</li> <li>4.3 Titan (alloys, properties, reaction of the body)</li> <li>4.4 Ceramics and glas (properties, reaction of the body)</li> <li>4.5 Plastics (properties of PMMA, HDPE, PET, reaction of the body)</li> <li>4.6 Natural replacement materials</li> </ol> </li> </ol> <p>Knowledge of composition, structure, properties, function and changes/adaptations of biological and technical materials (which are used for replacements in-vivo). Acquisition of basics for theses work in the area of biomechanics.</p>
<b>Literature</b>	<p>Hastings G and Ducheyne P.: Natural and living biomaterials. Boca Raton: CRC Press, 1984.</p> <p>Williams D.: Definitions in biomaterials. Oxford: Elsevier, 1987.</p> <p>Hastings G.: Mechanical properties of biomaterials: proceedings held at Keele University, September 1978. New York: Wiley, 1998.</p> <p>Black J.: Orthopaedic biomaterials in research and practice. New York: Churchill Livingstone, 1988.</p> <p>Park J. Biomaterials: an introduction. New York: Plenum Press, 1980.</p> <p>Wintermantel, E. und Ha, S.-W : Biokompatible Werkstoffe und Bauweisen. Berlin, Springer, 1996.</p>

Module M1173: Applied Statistics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Applied Statistics (L1584)	Lecture	2	3
Applied Statistics (L1586)	Project-/problem-based Learning	2	2
Applied Statistics (L1585)	Recitation Section (small)	1	1
<b>Module Responsible</b>	Prof. Michael Morlock		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge of statistical methods		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> Students can explain the statistical methods and the conditions of their use. <i>Skills</i> Students are able to use the statistics program to solve statistics problems and to interpret and depict the results		
<b>Personal Competence</b>	<i>Social Competence</i> Team Work, joined presentation of results <i>Autonomy</i> To understand and interpret the question and solve		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 minutes, 28 questions		
<b>Assignment for the Following Curricula</b>	Mechanical Engineering and Management: Specialisation Management: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Biomedical Engineering: Core qualification: Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1584: Applied Statistics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Michael Morlock
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	The goal is to introduce students to the basic statistical methods and their application to simple problems. The topics include: <ul style="list-style-type: none"> <li>• Chi square test</li> <li>• Simple regression and correlation</li> <li>• Multiple regression and correlation</li> <li>• One way analysis of variance</li> <li>• Two way analysis of variance</li> <li>• Discriminant analysis</li> <li>• Analysis of categorial data</li> <li>• Choosing the appropriate statistical method</li> <li>• Determining critical sample sizes</li> </ul>
<b>Literature</b>	Applied Regression Analysis and Multivariable Methods, 3rd Edition, David G. Kleinbaum Emory University, Lawrence L. Kupper University of North Carolina at Chapel Hill, Keith E. Muller University of North Carolina at Chapel Hill, Azhar Nizam Emory University, Published by Duxbury Press, CB © 1998, ISBN/ISSN: 0-534-20910-6

Course L1586: Applied Statistics	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Michael Morlock
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	The students receive a problem task, which they have to solve in small groups (n=5). They do have to collect their own data and work with them. The results have to be presented in an executive summary at the end of the course.
<b>Literature</b>	Selbst zu finden

Course L1585: Applied Statistics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Michael Morlock
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	The different statistical tests are applied for the solution of realistic problems using actual data sets and the most common used commercial statistical software package (SPSS).
<b>Literature</b>	Student Solutions Manual for Kleinbaum/Kupper/Muller/Nizam's Applied Regression Analysis and Multivariable Methods, 3rd Edition, David G. Kleinbaum Emory University Lawrence L. Kupper University of North Carolina at Chapel Hill, Keith E. Muller University of North Carolina at Chapel Hill, Azhar Nizam Emory University, Published by Duxbury Press, Paperbound © 1998, ISBN/ISSN: 0-534-20913-0

Module M1302: Applied Humanoid Robotics			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	<b>Hrs/wk</b> <b>CP</b>
Humanoid Robotics (L1794)		Project-/problem-based Learning	6            6
<b>Module Responsible</b>	Prof. Herbert Werner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Object oriented programming; algorithms and data structures</li> <li>• Introduction to control systems</li> <li>• Control systems theory and design</li> <li>• Mechanics</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<ul style="list-style-type: none"> <li>• Students can explain humanoid robots.</li> <li>• Students can explain the basic concepts, relationships and methods of forward- and inverse kinematics</li> <li>• Students learn to apply basic control concepts for different tasks in humanoid robotics.</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students can implement models for humanoid robotic systems in Matlab and C++, and use these models for robot motion or other tasks.</li> <li>• They are capable of using models in Matlab for simulation and testing these models if necessary with C++ code on the real robot system.</li> <li>• They are capable of selecting methods for solving abstract problems, for which no standard methods are available, and apply it successfully.</li> </ul>		
<b>Personal Competence</b>	<ul style="list-style-type: none"> <li>• Students can develop joint solutions in mixed teams and present these.</li> <li>• They can provide appropriate feedback to others, and constructively handle feedback on their own results</li> </ul>		
<i>Social Competence</i>			
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students are able to obtain required information from provided literature sources, and to put in into the context of the lecture.</li> <li>• They can independently define tasks and apply the appropriate means to solve them.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written elaboration		
<b>Examination duration and scale</b>	5-10 pages		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1794: Humanoid Robotics	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	6
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Lecturer</b>	Prof. Herbert Werner
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Fundamentals of kinematics</li> <li>• Static and dynamic stability of humanoid robotic systems</li> <li>• Combination of different software environments (Matlab, C++, etc.)</li> <li>• Introduction to the necessary software frameworks</li> <li>• Team project</li> <li>• Presentation and Demonstration of intermediate and final results</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• B. Siciliano, O. Khatib. "Handbook of Robotics. Part A: Robotics Foundations", Springer (2008)</li> </ul>

Module M0630: Robotics and Navigation in Medicine	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Robotics and Navigation in Medicine (L0335)	Lecture                                      2                                      3
Robotics and Navigation in Medicine (L0338)	Project Seminar                                      2                                      2
Robotics and Navigation in Medicine (L0336)	Recitation Section (small)                                      1                                      1
<b>Module Responsible</b>	Prof. Alexander Schlaefer
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• principles of math (algebra, analysis/calculus)</li> <li>• principles of programming, e.g., in Java or C++</li> <li>• solid R or Matlab skills</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The students can explain kinematics and tracking systems in clinical contexts and illustrate systems and their components in details. Systems can be evaluated with respect to collision detection and safety and regulations. Students can assess typical systems regarding design and limitations.
<i>Skills</i>	The students are able to design and evaluate navigation systems and robotic systems for medical applications.
<b>Personal Competence</b>	
<i>Social Competence</i>	The students discuss the results of other groups, provide helpful feedback and can incorporate feedback into their work.
<i>Autonomy</i>	The students can reflect their knowledge and document the results of their work. They can present the results in an appropriate manner.
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 minutes
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Electrical Engineering: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory

Course L0335: Robotics and Navigation in Medicine	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	- kinematics - calibration - tracking systems - navigation and image guidance - motion compensation The seminar extends and complements the contents of the lecture with respect to recent research results.
<b>Literature</b>	Spong et al.: Robot Modeling and Control, 2005 Troccaz: Medical Robotics, 2012 Further literature will be given in the lecture.

<b>Course L0338: Robotics and Navigation in Medicine</b>	
<b>Typ</b>	Project Seminar
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Course L0336: Robotics and Navigation in Medicine</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1335: BIO II: Artificial Joint Replacement			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Artificial Joint Replacement (L1306)	Lecture	2	3
<b>Module Responsible</b>	Prof. Michael Morlock		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28		
<b>Credit points</b>	3		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Process Engineering and Biotechnology: Elective Compulsory Materials Science: Specialisation Nano and Hybrid Materials: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1306: Artificial Joint Replacement	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Michael Morlock
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Inhalt (deutsch) 1. EINLEITUNG (Bedeutung, Ziel, Grundlagen, allg. Geschichte des künstlichen Gelenkersatzes) 2. FUNKTIONSANALYSE (Der menschliche Gang, die menschliche Arbeit, die sportliche Aktivität) 3. DAS HÜFTGELENK (Anatomie, Biomechanik, Gelenkersatz Schaffseite und Pfannenseite, Evolution der Implantate) 4. DAS KNIEGELENK (Anatomie, Biomechanik, Bandersatz, Gelenkersatz femorale, tibiale und patelläre Komponenten) 5. DER FUß (Anatomie, Biomechanik, Gelenkersatz, orthopädische Verfahren) 6. DIE SCHULTER (Anatomie, Biomechanik, Gelenkersatz) 7. DER ELLBOGEN (Anatomie, Biomechanik, Gelenkersatz) 8. DIE HAND (Anatomie, Biomechanik, Gelenkersatz) 9. TRIBOLOGIE NATÜRLICHER UND KÜNSTLICHER GELENKE (Korrosion, Reibung, Verschleiß)
<b>Literature</b>	Literatur: Kapandji, I.: Funktionelle Anatomie der Gelenke (Band 1-4), Enke Verlag, Stuttgart, 1984. Nigg, B., Herzog, W.: Biomechanics of the musculo-skeletal system, John Wiley&Sons, New York 1994 Nordin, M., Frankel, V.: Basic Biomechanics of the Musculoskeletal System, Lea&Febiger, Philadelphia, 1989. Czichos, H.: Tribologiehandbuch, Vieweg, Wiesbaden, 2003. Sobotta und Netter für Anatomie der Gelenke

Module M0811: Medical Imaging Systems			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Medical Imaging Systems (L0819)	Lecture	4	6
<b>Module Responsible</b>	Dr. Michael Grass		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	none		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>Students can:</p> <ul style="list-style-type: none"> <li>• Describe the system configuration and components of the main clinical imaging systems;</li> <li>• Explain how the system components and the overall system of the imaging systems function;</li> <li>• Explain and apply the physical processes that make imaging possible and use with the fundamental physical equations;</li> <li>• Name and describe the physical effects required to generate image contrasts;</li> <li>• Explain how spatial and temporal resolution can be influenced and how to characterize the images generated;</li> <li>• Explain which image reconstruction methods are used to generate images;</li> </ul> <p>Describe and explain the main clinical uses of the different systems.</p> <p>Students are able to:</p> <ul style="list-style-type: none"> <li>• Explain the physical processes of images and assign to the systems the basic mathematical or physical equations required;               <ul style="list-style-type: none"> <li>◦ Calculate the parameters of imaging systems using the mathematical or physical equations;</li> <li>◦ Determine the influence of different system components on the spatial and temporal resolution of imaging systems;</li> <li>◦ Explain the importance of different imaging systems for a number of clinical applications;</li> </ul> </li> </ul> <p>Select a suitable imaging system for an application.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i> none</p> <p><i>Autonomy</i> Students can:</p> <ul style="list-style-type: none"> <li>• Understand which physical effects are used in medical imaging;</li> <li>• Decide independently for which clinical issue a measuring system can be used.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>			
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Biomedical Engineering: Core qualification: Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Course L0819: Medical Imaging Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Dr. Michael Grass, Dr. Tim Nielsen, Dr. Sven Prevrhal, Frank Michael Weber
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	
<b>Literature</b>	Primary book: 1. P. Suetens, "Fundamentals of Medical Imaging", Cambridge Press  Secondary books: - A. Webb, "Introduction to Biomedical Imaging", IEEE Press 2003. - W.R. Hendee and E.R. Ritenour, "Medical Imaging Physics", Wiley-Liss, New York, 2002. - H. Morneburg (Edt), "Bildgebende Systeme für die medizinische Diagnostik", Erlangen: Siemens Publicis MCD Verlag, 1995. - O. Dössel, "Bildgebende Verfahren in der Medizin", Springer Verlag Berlin, 2000.



Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> see FSPO <i>Skills</i> see FSPO		
<b>Personal Competence</b>	<i>Social Competence</i> see FSPO <i>Autonomy</i> see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Module M1249: Numerical Methods for Medical Imaging			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Numerical Methods for Medical Imaging (L1694)	Lecture	2	3
Numerical Methods for Medical Imaging (L1695)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Tobias Knopp		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1694: Numerical Methods for Medical Imaging	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Tobias Knopp
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	<b>Bildgebende Verfahren in der Medizin</b> ; O. Dössel; Springer, Berlin, 2000 <b>Bildgebende Systeme für die medizinische Diagnostik</b> ; H. Morneburg (Hrsg.); Publicis MCD, München, 1995 <b>Introduction to the Mathematics of Medical Imaging</b> ; C. L. Epstein; Siam, Philadelphia, 2008 <b>Medical Image Processing, Reconstruction and Restoration</b> ; J. Jan; Taylor and Francis, Boca Raton, 2006 <b>Principles of Magnetic Resonance Imaging</b> ; Z.-P. Liang and P. C. Lauterbur; IEEE Press, New York, 1999

Course L1695: Numerical Methods for Medical Imaging	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Tobias Knopp
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0921: Electronic Circuits for Medical Applications	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Electronic Circuits for Medical Applications (L0696)	Lecture                                      2                                      3
Electronic Circuits for Medical Applications (L1056)	Recitation Section (small)                      1                                      2
Electronic Circuits for Medical Applications (L1408)	Practical Course                                      1                                      1
<b>Module Responsible</b>	Prof. Matthias Kuhl
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Fundamentals of electrical engineering
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can explain the basic functionality of the information transfer by the central nervous system</li> <li>• Students are able to explain the build-up of an action potential and its propagation along an axon</li> <li>• Students can exemplify the communication between neurons and electronic devices</li> <li>• Students can describe the special features of low-noise amplifiers for medical applications</li> <li>• Students can explain the functions of prostheses, e. g. an artificial hand</li> <li>• Students are able to discuss the potential and limitations of cochlea implants and artificial eyes</li> </ul>
<i>Skills</i>	<ul style="list-style-type: none"> <li>• Students can calculate the time dependent voltage behavior of an action potential</li> <li>• Students can give scenarios for further improvement of low-noise and low-power signal acquisition.</li> <li>• Students can develop the block diagrams of prosthetic systems</li> <li>• Students can define the building blocks of electronic systems for an artificial eye.</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Students are trained to solve problems in the field of medical electronics in teams together with experts with different professional background.</li> <li>• Students are able to recognize their specific limitations, so that they can ask for assistance to the right time.</li> <li>• Students can document their work in a clear manner and communicate their results in a way that others can be involved whenever it is necessary</li> </ul>
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students are able to realistically judge the status of their knowledge and to define actions for improvements when necessary.</li> <li>• Students can break down their work in appropriate work packages and schedule their work in a realistic way.</li> <li>• Students can handle the complex data structures of bioelectrical experiments without needing support.</li> <li>• Students are able to act in a responsible manner in all cases and situations of experimental work.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	40 min
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprotheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Microelectronics and Microsystems: Specialisation Microelectronics Complements: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0696: Electronic Circuits for Medical Applications	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Matthias Kuhl
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Market for medical instruments</li> <li>• Membrane potential, action potential, sodium-potassium pump</li> <li>• Information transfer by the central nervous system</li> <li>• Interface tissue - electrode</li> <li>• Amplifiers for medical applications, analog-digital converters</li> <li>• Examples for electronic implants</li> <li>• Artificial eye, cochlea implant</li> </ul>
<b>Literature</b>	<p>Kim E. Barret, Susan M. Barman, Scott Boitano and Heddwen L. Brooks</p> <p>Ganong's Review of Medical Physiology, 24nd Edition, McGraw Hill Lange, 2010</p> <p>Tier- und Humanphysiologie: Eine Einführung von Werner A. Müller (Author), Stephan Frings (Author), 657 p., 4. editions, Springer, 2009</p> <p>Robert F. Schmidt (Editor), Hans-Georg Schaible (Editor)</p> <p>Neuro- und Sinnesphysiologie (Springer-Lehrbuch) (Paper back), 488 p., Springer, 2006, 5. Edition, currently online only</p> <p>Russell K. Hobbie, Bradley J. Roth, Intermediate Physics for Medicine and Biology, Springer, 4th ed., 616 p., 2007</p> <p>Vorlesungen der Universität Heidelberg zur Tier- und Humanphysiologie:  <a href="http://www.sinnesphysiologie.de/gruvo03/gruvoin.htm">http://www.sinnesphysiologie.de/gruvo03/gruvoin.htm</a></p> <p>Internet: <a href="http://butler.cc.tut.fi/~malmivuo/bem/bembook/">http://butler.cc.tut.fi/~malmivuo/bem/bembook/</a></p>

Course L1056: Electronic Circuits for Medical Applications	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Matthias Kuhl
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Course L1408: Electronic Circuits for Medical Applications</b>	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Matthias Kuhl
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Market for medical instruments</li> <li>• Membrane potential, action potential, sodium-potassium pump</li> <li>• Information transfer by the central nervous system</li> <li>• Interface tissue - electrode</li> <li>• Amplifiers for medical applications, analog-digital converters</li> <li>• Examples for electronic implants</li> <li>• Artificial eye, cochlea implant</li> </ul>
<b>Literature</b>	<p>Kim E. Barret, Susan M. Barman, Scott Boitano and Heddwen L. Brooks            Ganong's Review of Medical Physiology, 24nd Edition, McGraw Hill Lange, 2010</p> <p>Tier- und Humanphysiologie: Eine Einführung von Werner A. Müller (Author), Stephan Frings (Author), 657 p., 4. editions, Springer, 2009</p> <p>Robert F. Schmidt (Editor), Hans-Georg Schaible (Editor)</p> <p>Neuro- und Sinnesphysiologie (Springer-Lehrbuch) (Paper back), 488 p., Springer, 2006, 5. Edition, currently online only</p> <p>Russell K. Hobbie, Bradley J. Roth, Intermediate Physics for Medicine and Biology, Springer, 4th ed., 616 p., 2007</p> <p>Vorlesungen der Universität Heidelberg zur Tier- und Humanphysiologie:  <a href="http://www.sinnesphysiologie.de/gruvo03/gruvoin.htm">http://www.sinnesphysiologie.de/gruvo03/gruvoin.htm</a></p> <p>Internet: <a href="http://butler.cc.tut.fi/~malmivuo/bem/bembook/">http://butler.cc.tut.fi/~malmivuo/bem/bembook/</a></p>

Module M0746: Microsystem Engineering	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Microsystem Engineering (L0680)	Lecture
Microsystem Engineering (L0682)	Project-/problem-based Learning
<b>Hrs/wk</b>	<b>CP</b>
2	4
2	2
<b>Module Responsible</b>	Prof. Manfred Kasper
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Basic courses in physics, mathematics and electric engineering
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The students know about the most important technologies and materials of MEMS as well as their applications in sensors and actuators.
<i>Skills</i>	Students are able to analyze and describe the functional behaviour of MEMS components and to evaluate the potential of microsystems.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to solve specific problems alone or in a group and to present the results accordingly.
<i>Autonomy</i>	Students are able to acquire particular knowledge using specialized literature and to integrate and associate this knowledge with other fields.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	2h
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Core qualification: Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Electrical Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Microelectronics and Microsystems: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory

Course L0680: Microsystem Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Manfred Kasper
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	Object and goal of MEMS Scaling Rules Lithography Film deposition Structuring and etching Energy conversion and force generation Electromagnetic Actuators Reluctance motors Piezoelectric actuators, bi-metal-actuator Transducer principles Signal detection and signal processing Mechanical and physical sensors Acceleration sensor, pressure sensor Sensor arrays System integration Yield, test and reliability
<b>Literature</b>	M. Kasper: Mikrosystementwurf, Springer (2000) M. Madou: Fundamentals of Microfabrication, CRC Press (1997)

Course L0682: Microsystem Engineering	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Manfred Kasper
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	Examples of MEMS components Layout consideration Electric, thermal and mechanical behaviour Design aspects
<b>Literature</b>	Wird in der Veranstaltung bekannt gegeben

Module M0623: Intelligent Systems in Medicine			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Intelligent Systems in Medicine (L0331)	Lecture	2	3
Intelligent Systems in Medicine (L0334)	Project Seminar	2	2
Intelligent Systems in Medicine (L0333)	Recitation Section (small)	1	1
<b>Module Responsible</b>	Prof. Alexander Schlaefer		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• principles of math (algebra, analysis/calculus)</li> <li>• principles of stochastics</li> <li>• principles of programming, Java/C++ and R/Matlab</li> <li>• advanced programming skills</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>The students are able to analyze and solve clinical treatment planning and decision support problems using methods for search, optimization, and planning. They are able to explain methods for classification and their respective advantages and disadvantages in clinical contexts. The students can compare different methods for representing medical knowledge. They can evaluate methods in the context of clinical data and explain challenges due to the clinical nature of the data and its acquisition and due to privacy and safety requirements.</p> <p><i>Skills</i></p> <p>The students can give reasons for selecting and adapting methods for classification, regression, and prediction. They can assess the methods based on actual patient data and evaluate the implemented methods.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>The students discuss the results of other groups, provide helpful feedback and can incorporate feedback into their work.</p> <p><i>Autonomy</i></p> <p>The students can reflect their knowledge and document the results of their work. They can present the results in an appropriate manner.</p>		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 minutes		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Course L0331: Intelligent Systems in Medicine	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- methods for search, optimization, planning, classification, regression and prediction in a clinical context</li> <li>- representation of medical knowledge</li> <li>- understanding challenges due to clinical and patient related data and data acquisition</li> </ul> <p>The students will work in groups to apply the methods introduced during the lecture using problem based learning.</p>
<b>Literature</b>	Russel & Norvig: Artificial Intelligence: a Modern Approach, 2012 Berner: Clinical Decision Support Systems: Theory and Practice, 2007 Greenes: Clinical Decision Support: The Road Ahead, 2007 Further literature will be given in the lecture



<b>Course L0334: Intelligent Systems in Medicine</b>	
<b>Typ</b>	Project Seminar
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Course L0333: Intelligent Systems in Medicine</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

## Specialization Energy Systems

The focus of the specialization „energy technology“ lies on the acquisition of knowledge and skills on an economically and ecologically sensible provision of electricity, heating and cooling on the basis of conventional and renewable energy systems. This is made possible by modules in the areas of fluid mechanics and ocean energy, solar energy, electric energy, heating technology, air conditioners, power plants, steam and Cogeneration and combustion technology electives. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M1037: Nuclear Power Plants and Steam Turbines			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>		
<b>Hrs/wk</b>	<b>CP</b>		
Steam Turbines in Renewable and Conventional Applications (L1286)	Lecture	2	2
Steam Turbines in Renewable and Conventional Applications (L1287)	Recitation Section (small)	1	1
Basics of Nuclear Power Plants (L1283)	Lecture	2	2
Basics of Nuclear Power Plants (L1285)	Recitation Section (small)	1	1
<b>Module Responsible</b>	Prof. Alfons Kather		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<p>For the part "Steam Turbines":</p> <ul style="list-style-type: none"> <li>• "Gas and Steam Power Plants"</li> <li>• "Technical Thermodynamics I &amp; II"</li> </ul> <p>For the part "Basics of Nuclear Power Plants" knowledge of:</p> <ul style="list-style-type: none"> <li>• Thermodynamics</li> <li>• Fluid Mechanics</li> <li>• Gas-Steam Power Plants</li> </ul> <p>is required</p>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>After successful completion of the part "Steam Turbines" of the module the students must be in a position to:</p> <ul style="list-style-type: none"> <li>• name and identify the various constructive sections and groups of steam turbines</li> <li>• describe and explain the key operating conditions for the application of steam turbines</li> <li>• classify different construction types and differentiate among steam turbines according to size and operating ranges</li> <li>• describe the thermodynamic processes and the constructive and operational repercussions resulting from the latter</li> <li>• calculate thermodynamically a turbine stage and a stage grouping</li> <li>• calculate or estimate and evaluate further sections of the turbine</li> <li>• outline diagrams describing the operating range and the constructive characteristics</li> <li>• investigate the constructive aspects and develop from the thermodynamic requirements the required construction characteristics</li> <li>• discuss and argue on the operation characteristics of different turbine types</li> <li>• evaluate thermodynamically the integration of different turbine designs in heat cycles.</li> </ul> <p>In the part of the module "Basics of Nuclear Power Plants" the students gain an overview of the safety requirements for the design, construction and operation of nuclear power plants.</p> <p>Students of various study programmes, who wish to specialise in the field of nuclear power engineering in future, are introduced to the special requirements of the nuclear power technology, which are important for the perception of this field.</p> <p>After successful completion of this part of the module the students acquire the following skills:</p> <ul style="list-style-type: none"> <li>• Know the fundamental physical processes for the energetic use of nuclear energy, which extends up to using nuclear fission in a regulated reactor</li> <li>• Know the physical and technical features of different reactor types</li> <li>• Know the construction of a nuclear plant for electricity generation</li> <li>• Understand and elucidate the heat generation in the fuel rods and the heat transfer to the cooling medium of the nuclear reactor (reactor thermodynamics)</li> <li>• Understand and explain the concepts for regulating water cooled reactors</li> <li>• Comprehend the concepts behind the safety systems that safeguard the necessary reliability and the fundamental constructive features of existing and new nuclear power plants</li> <li>• Understand the basic technical safety requirements on component integrity and their verification under long-term operation.</li> </ul> <p>In the part of the module "Steam Turbines" the students learn the fundamental approaches and methods for the design and operational evaluation of complex plant and gain confidence in seeking optimisations.</p> <p>In the part of the module "Basics of Nuclear Power Plants" the students:</p> <ul style="list-style-type: none"> <li>• obtain the ability to estimate the potential of nuclear power generation from an economical and technical standpoint in comparison to fossil plants</li> <li>• can evaluate the performance and technical limitations in using nuclear power plants for supplying the electric grid both with base-load electricity and regulating energy</li> <li>• can judge the hazards from radioactive radiation and the behaviour of radioactive elements based on the tables of nuclides</li> <li>• can evaluate the effectiveness of safety systems against various failure events being considered</li> <li>• from knowledge obtained on the impact of power plant operation on component integrity can identify the</li> </ul>		
<b>Knowledge</b>			
<b>Skills</b>			

	<p>requirements aiming at failure prevention</p> <ul style="list-style-type: none"> <li>• can define the fundamental repercussions for design and management of nuclear power plants on the basis of the overlaying requirements of the technical nuclear Regulations.</li> </ul>
<b>Personal Competence</b>	In the part of the module "Steam Turbines" the students learn: <ul style="list-style-type: none"> <li>• to work together with others whilst seeking a solution</li> <li>• to assist each other in problem solving.</li> </ul>
<b>Social Competence</b>	In the part of the module "Basics of Nuclear Power Plants" the students learn to: <ul style="list-style-type: none"> <li>• participate in discussions</li> <li>• present results</li> <li>• work together in a team.</li> </ul>
<b>Autonomy</b>	In the part of the module "Steam Turbines" the students learn the independent working of a complex theme whilst considering various aspects. They also learn how to carry independently single functions in a system combination. In the part of the module "Basics of Nuclear Power Plants" the students become the ability to gain independently knowledge and transfer it also to new problem solving.
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	180 min
<b>Assignment for the Following Curricula</b>	Energy and Environmental Engineering: Specialisation Energy and Environmental Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Energy and Environmental Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L1286: Steam Turbines in Renewable and Conventional Applications	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Christian Scharfetter
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Introduction</li> <li>• Construction Aspects of a Steam Turbine</li> <li>• Energy Conversion in a Steam Turbine</li> <li>• Construction Types of Steam Turbines</li> <li>• Behaviour of Steam Turbines</li> <li>• Sealing Systems for Steam Turbines</li> <li>• Axial Thrust</li> <li>• Regulation of Steam Turbines</li> <li>• Stiffness Calculation of the Blades</li> <li>• Blade and Rotor Oscillations</li> <li>• Fundamentals of a Safe Steam Turbine Operation</li> <li>• Application in Conventional and Renewable Power Stations</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Traupel, W.: Thermische Turbomaschinen. Berlin u. a., Springer (TUB HH: Signatur MSI-105)</li> <li>• Menny, K.: Strömungsmaschinen: hydraulische und thermische Kraft- und Arbeitsmaschinen. Ausgabe: 5. Wiesbaden, Teubner, 2006 (TUB HH: Signatur MSI-121)</li> <li>• Bohl, W.: Aufbau und Wirkungsweise. Ausgabe 6. Würzburg, Vogel, 1994 (TUB HH: Signatur MSI-109)</li> <li>• Bohl, W.: Berechnung und Konstruktion. Ausgabe 6. Aufl. Würzburg, Vogel, 1999 (TUB HH: Signatur MSI-110)</li> </ul>

Course L1287: Steam Turbines in Renewable and Conventional Applications	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Christian Scharfetter
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1283: Basics of Nuclear Power Plants	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Uwe Kleen
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Fundamentals of nuclear physics:               <ol style="list-style-type: none"> <li>1. Radioactive decay, half-life</li> <li>2. Release of energy from nuclear reactions</li> <li>3. Nuclear fission</li> <li>4. Neutron balance</li> <li>5. Reactor balancing</li> </ol> </li> <li>• Types of reactors</li> <li>• Radioactivity and radiation protection</li> <li>• Nuclear fuel cycle and final disposal</li> <li>• Reactor dynamics, regulation behaviour of reactors</li> <li>• Reactor thermodynamics of water cooled reactors</li> <li>• Nuclear technical Regulations, safety technical requirements</li> <li>• Safety technical design, safety systems for water cooled reactors</li> <li>• Component integrity</li> <li>• Operation and maintenance</li> <li>• Novel and future reactor types</li> </ul> <p>The lecture is supplemented by solving example exercises and is accompanied by an excursion.</p>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Fassbender, Einführung in die Reaktorphysik, Verlag Karl Thiemig, München</li> <li>• Ziegler, Lehrbuch der Reaktortechnik, Springer Verlag Berlin</li> <li>• Lamarsh, Introduction to Nuclear Engineering, Prentice Hall</li> </ul>

Course L1285: Basics of Nuclear Power Plants	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Uwe Kleen
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0742: Thermal Engineering	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Thermal Engineering (L0023)	Lecture 3 5
Thermal Engineering (L0024)	Recitation Section (large) 1 1
<b>Module Responsible</b>	Prof. Gerhard Schmitz
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Technical Thermodynamics I, II, Fluid Dynamics, Heat Transfer
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><b>Knowledge</b></p> <p>Students know the different energy conversion stages and the difference between efficiency and annual efficiency. They have increased knowledge in heat and mass transfer, especially in regard to buildings and mobile applications. They are familiar with German energy saving code and other technical relevant rules. They know to differ different heating systems in the domestic and industrial area and how to control such heating systems. They are able to model a furnace and to calculate the transient temperatures in a furnace. They have the basic knowledge of emission formations in the flames of small burners and how to conduct the flue gases into the atmosphere. They are able to model thermodynamic systems with object oriented languages.</p> <p><b>Skills</b></p> <p>Students are able to calculate the heating demand for different heating systems and to choose the suitable components. They are able to calculate a pipeline network and have the ability to perform simple planning tasks, regarding solar energy. They can write Modelica programs and can transfer research knowledge into practice. They are able to perform scientific work in the field of thermal engineering.</p> <p><b>Personal Competence</b></p> <p><b>Social Competence</b></p> <p>The students are able to discuss in small groups and develop an approach.</p> <p><b>Autonomy</b></p> <p>Students are able to define independently tasks, to get new knowledge from existing knowledge as well as to find ways to use the knowledge in practice.</p>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	60 min
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Energy and Environmental Engineering: Specialisation Energy Engineering: Elective Compulsory Energy Systems: Specialisation Energy Systems: Compulsory Energy Systems: Specialisation Marine Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Energy and Environmental Engineering: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Renewable Energies: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory

Course L0023: Thermal Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	5
<b>Workload in Hours</b>	Independent Study Time 108, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Gerhard Schmitz
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	1. Introduction 2. Fundamentals of Thermal Engineering 2.1 Heat Conduction 2.2 Convection 2.3 Radiation 2.4 Heat transition 2.5 Combustion parameters 2.6 Electrical heating 2.7 Water vapor transport 3. Heating Systems 3.1 Warm water heating systems 3.2 Warm water supply 3.3 piping calculation 3.4 boilers, heat pumps, solar collectors 3.5 Air heating systems 3.6 radiative heating systems 4. Thermal treatment systems 4.1 Industrial furnaces 4.2 Melting furnaces 4.3 Drying plants 4.4 Emission control 4.5 Chimney calculation 4.6 Energy measuring 5. Laws and standards 5.1 Buildings 5.2 Industrial plants
<b>Literature</b>	<ul style="list-style-type: none"> <li>Schmitz, G.: Klimateanlagen, Skript zur Vorlesung</li> <li>VDI Wärmeatlas, 11. Auflage, Springer Verlag, Düsseldorf 2013</li> <li>Herwig, H.; Moschallski, A.: Wärmeübertragung, Vieweg+Teubner Verlag, Wiesbaden 2009</li> <li>Recknagel, H.; Sprenger, E.; Schrammek, E.-R.: Taschenbuch für Heizung- und Klimatechnik 2013/2014, 76. Auflage, Deutscher Industrieverlag, 2013</li> </ul>

Course L0024: Thermal Engineering	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Gerhard Schmitz
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0512: Use of Solar Energy			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Energy Meteorology (L0016)	Lecture	1	1
Energy Meteorology (L0017)	Recitation Section (small)	1	1
Collector Technology (L0018)	Lecture	2	2
Solar Power Generation (L0015)	Lecture	2	2
<b>Module Responsible</b>	Prof. Martin Kaltschmitt		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	none		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	With the completion of this module, students will be able to deal with technical foundations and current issues and problems in the field of solar energy and explain and evaluate these critically in consideration of the prior curriculum and current subject specific issues. In particular they can professionally describe the processes within a solar cell and explain the specific features of application of solar modules. Furthermore, they can provide an overview of the collector technology in solar thermal systems.		
<i>Skills</i>	Students can apply the acquired theoretical foundations of exemplary energy systems using solar radiation. In this context, for example they can assess and evaluate potential and constraints of solar energy systems with respect to different geographical assumptions. They are able to dimension solar energy systems in consideration of technical aspects and given assumptions. Using module-comprehensive knowledge students can evaluate the economic and ecologic conditions of these systems. They can select calculation methods within the radiation theory for these topics.		
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>	Students can independently exploit sources and acquire the particular knowledge about the subject area with respect to emphasis to the lectures. Furthermore, with the assistance of lecturers, they can discrete use calculation methods for analysing and dimensioning solar energy systems. Based on this procedure they can concrete assess their specific learning level and can consequently define the further workflow.		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	3 hours written exam		
<b>Assignment for the Following Curricula</b>	Energy and Environmental Engineering: Specialisation Energy and Environmental Engineering: Elective Compulsory Energy Systems: Specialisation Energy Systems: Elective Compulsory Energy Systems: Specialisation Energy Systems: Elective Compulsory International Management and Engineering: Specialisation II. Renewable Energy: Elective Compulsory International Management and Engineering: Specialisation II. Energy and Environmental Engineering: Elective Compulsory Renewable Energies: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Environmental Process Engineering: Elective Compulsory		

Course L0016: Energy Meteorology	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Volker Matthias, Dr. Beate Geyer
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Introduction: radiation source Sun, Astronomical Foundations, Fundamentals of radiation</li> <li>• Structure of the atmosphere</li> <li>• Properties and laws of radiation               <ul style="list-style-type: none"> <li>◦ Polarization</li> <li>◦ Radiation quantities</li> <li>◦ Planck's radiation law</li> <li>◦ Wien's displacement law</li> <li>◦ Stefan-Boltzmann law</li> <li>◦ Kirchhoffs law</li> <li>◦ Brightness temperature</li> <li>◦ Absorption, reflection, transmission</li> </ul> </li> <li>• Radiation balance, global radiation, energy balance</li> <li>• Atmospheric extinction</li> <li>• Mie and Rayleigh scattering</li> <li>• Radiative transfer</li> <li>• Optical effects in the atmosphere</li> <li>• Calculation of the sun and calculate radiation on inclined surfaces</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Helmut Kraus: Die Atmosphäre der Erde</li> <li>• Hans Häckel: Meteorologie</li> <li>• Grant W. Petty: A First Course in Atmospheric Radiation</li> <li>• Martin Kaltschmitt, Wolfgang Streicher, Andreas Wiese: Renewable Energy</li> <li>• Alexander Löw, Volker Matthias: Skript Optik Strahlung Fernerkundung</li> </ul>

Course L0017: Energy Meteorology	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Beate Geyer
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L0018: Collector Technology	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Agis Papadopoulos
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Introduction: Energy demand and application of solar energy.</li> <li>• Heat transfer in the solar thermal energy: conduction, convection, radiation.</li> <li>• Collectors: Types, structure, efficiency, dimensioning, concentrated systems.</li> <li>• Energy storage: Requirements, types.</li> <li>• Passive solar energy: components and systems.</li> <li>• Solar thermal low temperature systems: collector variants, construction, calculation.</li> <li>• Solar thermal high temperature systems: Classification of solar power plants construction.</li> <li>• Solar air conditioning.</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Vorlesungsskript.</li> <li>• Kaltschmitt, Streicher und Wiese (Hrsg.). Erneuerbare Energien: Systemtechnik, Wirtschaftlichkeit, Umweltaspekte, 5. Auflage, Springer, 2013.</li> <li>• Stieglitz und Heinzel .Thermische Solarenergie: Grundlagen, Technologie, Anwendungen. Springer, 2012.</li> <li>• Von Böckh und Wetzel. Wärmeübertragung: Grundlagen und Praxis, Springer, 2011.</li> <li>• Baehr und Stephan. Wärme- und Stoffübertragung. Springer, 2009.</li> <li>• de Vos. Thermodynamics of solar energy conversion. Wiley-VCH, 2008.</li> <li>• Mohr, Svoboda und Unger. Praxis solarthermischer Kraftwerke. Springer, 1999.</li> </ul>



Course L0015: Solar Power Generation	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dietmar Obst, Martin Schlecht
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Introduction</li> <li>2. Primary energy and consumption, available solar energy</li> <li>3. Physics of the ideal solar cell</li> <li>4. Light absorption PN junction characteristic values of the solar cell efficiency</li> <li>5. Physics of the real solar cell</li> <li>6. Charge carrier recombination characteristics, junction layer recombination, equivalent circuit</li> <li>7. Increasing the efficiency</li> <li>8. Methods for increasing the quantum yield, and reduction of recombination</li> <li>9. Straight and tandem structures</li> <li>10. Hetero-junction, Schottky, electrochemical, MIS and SIS-cell tandem cell</li> <li>11. Concentrator</li> <li>12. Concentrator optics and tracking systems</li> <li>13. Technology and properties: types of solar cells, manufacture, single crystal silicon and gallium arsenide, polycrystalline silicon, and silicon thin film cells, thin-film cells on carriers (amorphous silicon, CIS, electrochemical cells)</li> <li>14. Modules</li> <li>15. Circuits</li> </ol>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• A. Götzberger, B. Voß, J. Knobloch: Sonnenenergie: Photovoltaik, Teubner Studienskripten, Stuttgart, 1995</li> <li>• A. Götzberger: Sonnenenergie: Photovoltaik : Physik und Technologie der Solarzelle, Teubner Stuttgart, 1994</li> <li>• H.-J. Lewerenz, H. Jungblut: Photovoltaik, Springer, Berlin, Heidelberg, New York, 1995</li> <li>• A. Götzberger: Photovoltaic solar energy generation, Springer, Berlin, 2005</li> <li>• C. Hu, R. M. White: Solar Cells, Mc Graw Hill, New York, 1983</li> <li>• H.-G. Wagemann: Grundlagen der photovoltaischen Energiewandlung: Solarstrahlung, Halbleitereigenschaften und Solarzellenkonzepte, Teubner, Stuttgart, 1994</li> <li>• R. J. van Overstraeten, R.P. Mertens: Physics, technology and use of photovoltaics, Adam Hilger Ltd, Bristol and Boston, 1986</li> <li>• B. O. Seraphin: Solar energy conversion Topics of applied physics V 01 31, Springer, Berlin, Heidelberg, New York, 1995</li> <li>• P. Würfel: Physics of Solar cells, Principles and new concepts, Wiley-VCH, Weinheim 2005</li> <li>• U. Rindelhardt: Photovoltaische Stromversorgung, Teubner-Reihe Umwelt, Stuttgart 2001</li> <li>• V. Quaschnig: Regenerative Energiesysteme, Hanser, München, 2003</li> <li>• G. Schmitz: Regenerative Energien, Ringvorlesung TU Hamburg-Harburg 1994/95, Institut für Energietechnik</li> </ul>

Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> see FSPO <i>Skills</i> see FSPO		
<b>Personal Competence</b>	<i>Social Competence</i> see FSPO <i>Autonomy</i> see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Module M1000: Combined Heat and Power and Combustion Technology	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Combined Heat and Power and Combustion Technology (L0216)	Lecture                                      3                                      5
Combined Heat and Power and Combustion Technology (L0220)	Recitation Section (large)                      1                                      1
<b>Module Responsible</b>	Prof. Alfons Kather
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• "Gas-Steam Power Plants"</li> <li>• "Technical Thermodynamics I and II"</li> <li>• "Heat Transfer"</li> <li>• "Fluid Mechanics"</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p>The students outline the thermodynamic and chemical fundamentals of combustion processes. From the knowledge of the characteristics and reaction kinetics of various fuels they can describe the behaviour of premixed flames and non-premixed flames, in order to describe the fundamentals of furnace design in gas-, oil- and coal combustion plant. The students are furthermore able to describe the formation of NO<sub>x</sub> and the primary NO<sub>x</sub> reduction measures, and evaluate the impact of regulations and allowable limit levels.</p> <p><i>Knowledge</i> The students present the layout, design and operation of Combined Heat and Power plants and are in a position to compare with each other district heating plants with back-pressure steam turbine or condensing turbine with pressure-controlled extraction tapping, CHP plants with gas turbine or with combined steam and gas turbine, or even district heating plants with an internal combustion engine. They can explain and analyse aspects of combined heat, power and cooling (CCHP) and describe the layout of the key components needed. Through this specialised knowledge they are able to evaluate the ecological significance of district CHP generation, as well as its economics.</p> <p><i>Skills</i> Using thermodynamic calculations and considering the reaction kinetics the students will be able to determine interdisciplinary correlations between thermodynamic and chemical processes during combustion. This then enables quantitative analysis of the combustion of gaseous, liquid and solid fuels and determination of the quantities and concentrations of the exhaust gases. In this module the first step toward the utilisation of an energy source (combustion) to provide usable energy (electricity and heat) is taught. An understanding of both procedures enables the students to holistically consider energy utilisation. Examples taken from the praxis, such as the CHP energy supply facility of the TUHH and the district heating network of Hamburg will be used, to highlight the potential from electricity generation plants with simultaneous heat extraction.</p> <p>Within the framework of the exercises the students will first learn to calculate the energetic and mass balances of combustion processes. Moreover, the students will gain a deeper understanding of the combustion processes by the calculation of reaction kinetics and fundamentals of burner design. In order to perform further analyses they will familiarise themselves to the specialised software suite EBSILON Professional™. With this tool small and close to reality tasks are solved on the PC, to highlight aspects of the design and balancing of heating plant cycles. In addition CHP will also be considered in its economic and social contexts.</p>
<b>Personal Competence</b>	
<i>Social Competence</i>	Especially during the exercises the focus is placed on communication with the tutor. This animates the students to reflect on their existing knowledge and ask specific questions for improving further this knowledge level.
<i>Autonomy</i>	The students assisted by the tutors will be able to perform estimating calculations. In this manner the theoretical and practical knowledge from the lecture is consolidated and the potential impact of different process arrangements and boundary conditions highlighted.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Energy and Environmental Engineering: Specialisation Energy Engineering: Elective Compulsory Energy Systems: Specialisation Energy Systems: Compulsory Energy Systems: Specialisation Marine Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Energy and Environmental Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0216: Combined Heat and Power and Combustion Technology	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	5
<b>Workload in Hours</b>	Independent Study Time 108, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Alfons Kather
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The subject area of "Combined Heat and Power" covers the following themes:</p> <ul style="list-style-type: none"> <li>• Layout, design and operation of Combined Heat and Power plants</li> <li>• District heating plants with back-pressure steam turbine and condensing turbine with pressure-controlled extraction tapping</li> <li>• District heating plants with gas turbine</li> <li>• District heating plants with combined steam and gas turbine</li> <li>• District heating plants with motor engine</li> <li>• Combined cooling heat and power (CCHP)</li> <li>• Layout of the key components</li> <li>• Regulatory framework and allowable limits</li> <li>• Economic significance and calculation of the profitability of district CHP plant</li> </ul> <p>whereas the subject of Combustion Technology includes:</p> <ul style="list-style-type: none"> <li>• Thermodynamic and chemical fundamentals</li> <li>• Fuels</li> <li>• Reaction kinetics</li> <li>• Premixed flames</li> <li>• Non-premixed flames</li> <li>• Combustion of gaseous fuels</li> <li>• Combustion of liquid fuels</li> <li>• Combustion of solid fuels</li> <li>• Combustion Chamber design</li> <li>• NO<sub>x</sub> reduction</li> </ul>
<b>Literature</b>	<p>Bezüglich des Themenbereichs "Kraft-Wärme-Kopplung":</p> <ul style="list-style-type: none"> <li>• W. Piller, M. Rudolph: Kraft-Wärme-Kopplung, VVEW Verlag</li> <li>• Kehlhofer, Kunze, Lehmann, Schüller: Handbuch Energie, Band 7, Technischer Verlag Resch</li> <li>• W. Suttor: Praxis Kraft-Wärme-Kopplung, C.F. Müller Verlag</li> <li>• K.W. Schmitz, G. Koch: Kraft-Wärme-Kopplung, VDI Verlag</li> <li>• K.-H. Suttor, W. Suttor: Die KWK Fibel, Resch Verlag</li> </ul> <p>und für die Grundlagen der "Verbrennungstechnik":</p> <ul style="list-style-type: none"> <li>• J. Warnatz, U. Maas, R.W. Dibble; Technische Verbrennung: physikalisch-chemische Grundlagen, Modellbildung, Schadstoffentstehung. Springer, Berlin [u. a.], 2001</li> </ul>

Course L0220: Combined Heat and Power and Combustion Technology	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Alfons Kather
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0721: Air Conditioning			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Air Conditioning (L0594)	Lecture	3	5
Air Conditioning (L0595)	Recitation Section (large)	1	1
<b>Module Responsible</b>	Prof. Gerhard Schmitz		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Technical Thermodynamics I, II, Fluid Dynamics, Heat Transfer		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students know the different kinds of air conditioning systems for buildings and mobile applications and how these systems are controlled. They are familiar with the change of state of humid air and are able to draw the state changes in a <math>h_1+x,x</math>-diagram. They are able to calculate the minimum airflow needed for hygienic conditions in rooms and can choose suitable filters. They know the basic flow pattern in rooms and are able to calculate the air velocity in rooms with the help of simple methods. They know the principles to calculate an air duct network. They know the different possibilities to produce cold and are able to draw these processes into suitable thermodynamic diagrams. They know the criteria for the assessment of refrigerants.</p> <p><i>Skills</i></p> <p>Students are able to configure air condition systems for buildings and mobile applications. They are able to calculate an air duct network and have the ability to perform simple planning tasks, regarding natural heat sources and heat sinks. They can transfer research knowledge into practice. They are able to perform scientific work in the field of air conditioning.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>The students are able to discuss in small groups and develop an approach.</p> <p><i>Autonomy</i></p> <p>Students are able to define independently tasks, to get new knowledge from existing knowledge as well as to find ways to use the knowledge in practice.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	60 min		
<b>Assignment for the Following Curricula</b>	Energy and Environmental Engineering: Specialisation Energy and Environmental Engineering: Elective Compulsory Energy Systems: Specialisation Energy Systems: Elective Compulsory Energy Systems: Specialisation Marine Engineering: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory International Management and Engineering: Specialisation II. Energy and Environmental Engineering: Elective Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory		

Course L0594: Air Conditioning	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	5
<b>Workload in Hours</b>	Independent Study Time 108, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Gerhard Schmitz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	1. Overview 1.1 Kinds of air conditioning systems 1.2 Ventilating 1.3 Function of an air condition system 2. Thermodynamic processes 2.1 Psychrometric chart 2.2 Mixer preheater, heater 2.3 Cooler 2.4 Humidifier 2.5 Air conditioning process in a Psychrometric chart 2.6 Desiccant assisted air conditioning 3. Calculation of heating and cooling loads 3.1 Heating loads 3.2 Cooling loads 3.3 Calculation of inner cooling load 3.4 Calculation of outer cooling load 4. Ventilating systems 4.1 Fresh air demand 4.2 Air flow in rooms 4.3 Calculation of duct systems 4.4 Fans 4.5 Filters 5. Refrigeration systems 5.1. compression chillers 5.2 Absorption chillers
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Schmitz, G.: Klimaanlage, Skript zur Vorlesung</li> <li>• VDI Wärmeatlas, 11. Auflage, Springer Verlag, Düsseldorf 2013</li> <li>• Herwig, H.; Moschallski, A.: Wärmeübertragung, Vieweg+Teubner Verlag, Wiesbaden 2009</li> <li>• Recknagel, H.; Sprenger, E.; Schrammek, E.-R.: Taschenbuch für Heizung- und Klimatechnik 2013/2014, 76. Auflage, Deutscher Industrieverlag, 2013</li> </ul>

Course L0595: Air Conditioning	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Gerhard Schmitz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0508: Fluid Mechanics and Ocean Energy			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Energy from the Ocean (L0002)	Lecture	2	2
Fluid Mechanics II (L0001)	Lecture	2	4
<b>Module Responsible</b>	Prof. Michael Schlüter		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Technische Thermodynamik I-II Wärme- und Stoffübertragung		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> The students are able to describe different applications of fluid mechanics for the field of Renewable Energies. They are able to use the fundamentals of fluid mechanics for calculations of certain engineering problems in the field of ocean energy. The students are able to estimate if a problem can be solved with an analytical solution and what kind of alternative possibilities are available (e.g. self-similarity, empirical solutions, numerical methods).</p> <p><i>Skills</i> Students are able to use the governing equations of Fluid Dynamics for the design of technical processes. Especially they are able to formulate momentum and mass balances to optimize the hydrodynamics of technical processes. They are able to transform a verbal formulated message into an abstract formal procedure.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> The students are able to discuss a given problem in small groups and to develop an approach. They are able to solve a problem within a team, to prepare a poster with the results and to present the poster.</p> <p><i>Autonomy</i> Students are able to define independently tasks for problems related to fluid mechanics. They are able to work out the knowledge that is necessary to solve the problem by themselves on the basis of the existing knowledge from the lecture.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	3h		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory International Management and Engineering: Specialisation II. Renewable Energy: Elective Compulsory Renewable Energies: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0002: Energy from the Ocean	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Introduction to ocean energy conversion</li> <li>2. Wave properties                             <ul style="list-style-type: none"> <li>o Linear wave theory</li> <li>o Nonlinear wave theory</li> <li>o Irregular waves</li> <li>o Wave energy</li> <li>o Refraction, reflection and diffraction of waves</li> </ul> </li> <li>3. Wave energy converters                             <ul style="list-style-type: none"> <li>o Overview of the different technologies</li> <li>o Methods for design and calculation</li> </ul> </li> <li>4. Ocean current turbine</li> </ol>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Cruz, J., Ocean wave energy, Springer Series in Green Energy and Technology, UK, 2008.</li> <li>• Brooke, J., Wave energy conversion, Elsevier, 2003.</li> <li>• McCormick, M.E., Ocean wave energy conversion, Courier Dover Publications, USA, 2013.</li> <li>• Falnes, J., Ocean waves and oscillating systems, Cambridge University Press, UK, 2002.</li> <li>• Charlier, R. H., Charles, W. F., Ocean energy. Tide and tidal Power. Berlin, Heidelberg, 2009.</li> <li>• Clauss, G. F., Lehmann, E., Østergaard, C., Offshore Structures. Volume 1, Conceptual Design. Springer-Verlag, Berlin 1992</li> </ul>

Course L0001: Fluid Mechanics II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Michael Schlüter
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Differential equations for momentum-, heat and mass transfer</li> <li>• Examples for simplifications of the Navier-Stokes Equations</li> <li>• Unsteady momentum transfer</li> <li>• Free shear layer, turbulence and free jets</li> <li>• Flow around particles - Solids Process Engineering</li> <li>• Coupling of momentum and heat transfer - Thermal Process Engineering</li> <li>• Rheology – Bioprocess Engineering</li> <li>• Coupling of momentum- and mass transfer – Reactive mixing, Chemical Process Engineering</li> <li>• Flow threwn porous structures - heterogeneous catalysis</li> <li>• Pumps and turbines - Energy- and Environmental Process Engineering</li> <li>• Wind- and Wave-Turbines - Renewable Energy</li> <li>• Introduction into Computational Fluid Dynamics</li> </ul>
<b>Literature</b>	<ol style="list-style-type: none"> <li>1. Brauer, H.: Grundlagen der Einphasen- und Mehrphasenströmungen. Verlag Sauerländer, Aarau, Frankfurt (M), 1971.</li> <li>2. Brauer, H.; Mewes, D.: Stoffaustausch einschließlich chemischer Reaktion. Frankfurt: Sauerländer 1972.</li> <li>3. Crowe, C. T.: Engineering fluid mechanics. Wiley, New York, 2009.</li> <li>4. Durst, F.: Strömungsmechanik: Einführung in die Theorie der Strömungen von Fluiden. Springer-Verlag, Berlin, Heidelberg, 2006.</li> <li>5. Fox, R.W.; et al.: Introduction to Fluid Mechanics. J. Wiley &amp; Sons, 1994.</li> <li>6. Herwig, H.: Strömungsmechanik: Eine Einführung in die Physik und die mathematische Modellierung von Strömungen. Springer Verlag, Berlin, Heidelberg, New York, 2006.</li> <li>7. Herwig, H.: Strömungsmechanik: Einführung in die Physik von technischen Strömungen: Vieweg+Teubner Verlag / GWV Fachverlage GmbH, Wiesbaden, 2008.</li> <li>8. Kuhlmann, H.C.: Strömungsmechanik. München, Pearson Studium, 2007</li> <li>9. Oertl, H.: Strömungsmechanik: Grundlagen, Grundgleichungen, Lösungsmethoden, Softwarebeispiele. Vieweg+ Teubner / GWV Fachverlage GmbH, Wiesbaden, 2009.</li> <li>10. Schade, H.; Kunz, E.: Strömungslehre. Verlag de Gruyter, Berlin, New York, 2007.</li> <li>11. Truckenbrodt, E.: Fluidmechanik 1: Grundlagen und elementare Strömungsvorgänge dichtebeständiger Fluide. Springer-Verlag, Berlin, Heidelberg, 2008.</li> <li>12. Schlichting, H. : Grenzschicht-Theorie. Springer-Verlag, Berlin, 2006.</li> <li>13. van Dyke, M.: An Album of Fluid Motion. The Parabolic Press, Stanford California, 1882.</li> </ol>



Module M0658: Innovative CFD Approaches			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	<b>Hrs/wk</b> <b>CP</b>
Application of Innovative CFD Methods in Research and Development (L0239)		Lecture	2            3
Application of Innovative CFD Methods in Research and Development (L1685)		Recitation Section (small)	2            3
<b>Module Responsible</b>	Prof. Thomas Rung		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Attendance of a computational fluid dynamics course (CFD1/CFD2) Competent knowledge of numerical analysis in addition to general and computational thermo/fluid dynamics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	Student can explain the theoretical background of different CFD strategies (e.g. Lattice-Boltzmann, Smoothed Particle-Hydrodynamics, Finite-Volume methods) and describe the fundamentals of simulation-based optimisation.		
<i>Skills</i>	Student is able to identify an appropriate CFD-based solution strategy on a justified basis.		
<b>Personal Competence</b>			
<i>Social Competence</i>	Student should practice her/his team-working abilities, learn to lead team sessions and present solutions to experts.		
<i>Autonomy</i>	Student should be able to structure and perform a simulation-based project independently,		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Ship and Offshore Technology: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory		

Course L0239: Application of Innovative CFD Methods in Research and Development	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	Computational Optimisation, Parallel Computing, Efficient CFD-Procedures for GPU Architectures, Alternative Approximations (Lattice-Boltzmann Methods, Particle Methods), Fluid/Structure-Interaction, Modelling of Hybrid Continua
<b>Literature</b>	Vorlesungsmaterialien /lecture notes

Course L1685: Application of Innovative CFD Methods in Research and Development	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1149: Marine Power Engineering			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Electrical Installation on Ships (L1531)	Lecture	2	2
Electrical Installation on Ships (L1532)	Recitation Section (large)	1	1
Marine Engineering (L1569)	Lecture	2	2
Marine Engineering (L1570)	Recitation Section (large)	1	1
<b>Module Responsible</b>	Prof. Christopher Friedrich Wirz		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>The students are able to describe the state-of-the-art regarding the wide range of propulsion components on ships and apply their knowledge. They further know how to analyze and optimize the interaction of the components of the propulsion system and how to describe complex correlations with the specific technical terms in German and English. The students are able to name the operating behaviour of consumers, describe special requirements on the design of supply networks and to the electrical equipment in isolated networks, as e.g. onboard ships, offshore units, factories and emergency power supply systems, explain power generation and distribution in isolated grids, wave generator systems on ships, and name requirements for network protection, selectivity and operational monitoring.</p> <p><i>Skills</i></p> <p>The students are skilled to employ basic and detail knowledge regarding reciprocating machinery, their selection and operation on board ships. They are further able to assess, analyse and solve technical and operational problems with propulsion and auxiliary plants and to design propulsion systems. The students have the skills to describe complex correlations and bring them into context with related disciplines. Students are able to calculate short-circuit currents, switchgear, and design electrical propulsion systems for ships.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>The students are able to communicate and cooperate in a professional environment in the shipbuilding and component supply industry.</p> <p><i>Autonomy</i></p> <p>The widespread scope of gained knowledge enables the students to handle situations in their future profession independently and confidently.</p>		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 minutes plus 20 minutes oral exam		
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Energy Systems: Elective Compulsory Energy Systems: Specialisation Marine Engineering: Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1531: Electrical Installation on Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Günter Ackermann
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• performance in service of electrical consumers.</li> <li>• special requirements for power supply systems and for electrical equipment in isolated systems/networks e. g. aboard ships, offshore installations, factory systems and emergency power supply systems.</li> <li>• power generation and distribution in isolated networks, shaft generators for ships</li> <li>• calculation of short circuits and behaviour of switching devices</li> <li>• protective devices, selectivity monitoring</li> <li>• electrical Propulsion plants for ships</li> </ul>
<b>Literature</b>	H. Meier-Peter, F. Bernhardt u. a.: Handbuch der Schiffsbetriebstechnik, Seehafen Verlag (engl. Version: "Compendium Marine Engineering") Gleiß, Thamm: Schiffselektrotechnik, VEB Verlag Technik Berlin

Course L1532: Electrical Installation on Ships	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Günter Ackermann
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1569: Marine Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	Wird in der Veranstaltung bekannt gegeben

Course L1570: Marine Engineering	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0515: Energy Information Systems and Electromobility			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Electrical Power Systems II (L1696)	Lecture	2	4
Electro mobility (L1833)	Lecture	2	2
<b>Module Responsible</b>	Prof. Martin Kaltschmitt		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Fundamentals of Electrical Engineering		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students are able to give an overview of the electric power engineering in the field of renewable energies. They can explain in detail the possibilities for the integration of renewable energy systems into the existing grid, the electrical storage possibilities and the electric power transmission and distribution, and can take critically a stand on it.</p> <p><i>Skills</i> With completion of this module the students are able to apply the acquired skills in applications of the design, integration, development of renewable energy systems and to assess the results.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> The students can participate in specialized and interdisciplinary discussions, advance ideas and represent their own work results in front of others.</p> <p><i>Autonomy</i> Students can independently tap knowledge of the emphasis of the lectures.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	45 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Energy Systems: Elective Compulsory Renewable Energies: Specialisation Wind Energy Systems: Elective Compulsory Renewable Energies: Specialisation Solar Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1696: Electrical Power Systems II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Christian Becker
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• steady-state modelling of electric power systems               <ul style="list-style-type: none"> <li>◦ conventional components</li> <li>◦ Flexible AC Transmission Systems (FACTS) and HVDC</li> <li>◦ grid modelling</li> </ul> </li> <li>• grid operation               <ul style="list-style-type: none"> <li>◦ electric power supply processes</li> <li>◦ grid and power system management</li> <li>◦ grid provision</li> </ul> </li> <li>• grid control systems               <ul style="list-style-type: none"> <li>◦ information and communication systems for power system management</li> <li>◦ IT architectures of bay-, substation and network control level</li> <li>◦ IT integration (energy market / supply shortfall management / asset management)</li> <li>◦ future trends of process control technology</li> <li>◦ smart grids</li> </ul> </li> <li>• functions and steady-state computations for power system operation and planning               <ul style="list-style-type: none"> <li>◦ load-flow calculations</li> <li>◦ sensitivity analysis and power flow control</li> <li>◦ power system optimization</li> <li>◦ short-circuit calculation</li> <li>◦ asymmetric failure calculation                   <ul style="list-style-type: none"> <li>▪ symmetric components</li> <li>▪ calculation of asymmetric failures</li> </ul> </li> <li>◦ state estimation</li> </ul> </li> </ul>
<b>Literature</b>	E. Handschin: Elektrische Energieübertragungssysteme, Hüthig Verlag B. R. Oswald: Berechnung von Drehstromnetzen, Springer-Vieweg Verlag V. Crastan: Elektrische Energieversorgung Bd. 1 & 3, Springer Verlag E.-G. Tietze: Netzleittechnik Bd. 1 & 2, VDE-Verlag

Course L1833: Electro mobility	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Klaus Bonhoff
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	Inhalt (englisch) <ul style="list-style-type: none"> <li>• Introduction and environment</li> <li>• Definition of electric vehicles</li> <li>• Excursus: Electric vehicles with fuel cell</li> <li>• Market uptake of electric cars</li> <li>• Political / Regulatory Framework</li> <li>• Historical Review</li> <li>• Electric vehicle portfolio / application examples</li> <li>• Mild hybrids with 48 volt technology</li> <li>• Lithium-ion battery incl. Costs, roadmap, production, raw materials</li> <li>• Vehicle Integration</li> <li>• Energy consumption of electric cars</li> <li>• Battery life</li> <li>• Charging Infrastructure</li> <li>• Electric road transport</li> <li>• Electric public transport</li> <li>• Battery Safety</li> </ul>
<b>Literature</b>	Vorlesungsunterlagen/ lecture material

## Specialization Aircraft Systems Engineering

Central to the specialization Aircraft Systems is learning the ability to systems engineering and cross-divisional thinking and problem solving in aeronautical engineering. This is made possible by modules in the field of physics of flight, aircraft systems and cabin systems, Aircraft Design, as well as airport planning and operation in the elective area. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M0763: Aircraft Systems I	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Aircraft Systems I (L0735)	Lecture                                      3                                      4
Aircraft Systems I (L0739)	Recitation Section (large)              2                                      2
<b>Module Responsible</b>	Prof. Frank Thielecke
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Electrical Engineering</li> <li>• Hydraulics</li> <li>• Control Systems</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• Describe essential components and design points of hydraulic, electrical and high-lift systems</li> <li>• Give an overview of the functionality of air conditioning systems</li> <li>• Explain the need for high-lift systems such as ist functionality and effects</li> <li>• Assess the challenge during the design of supply systems of an aircraft</li> </ul>
<i>Knowledge</i>	
<i>Skills</i>	Students are able to: <ul style="list-style-type: none"> <li>• Design hydraulic and electric supply systems of aircrafts</li> <li>• Design high-lift systems of aircrafts</li> <li>• Analyze the thermodynamic behaviour of air conditioning systems</li> </ul>
<b>Personal Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• Perform system design in groups and present and discuss results</li> </ul>
<i>Social Competence</i>	
<i>Autonomy</i>	Students are able to: <ul style="list-style-type: none"> <li>• Reflect the contents of lectures autonomously</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	165 Minutes
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Energy Systems: Elective Compulsory Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0735: Aircraft Systems I	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Frank Thielecke
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>Hydraulic Energy Systems (Fluids; pressure loss in valves and pipes; components of hydraulic systems like pumps, valves, etc.; pressure/flow characteristics; actuators; tanks; power and heat balances; emergency power)</li> <li>Electric Energy Systems (Generators; constant-speed-drives; DC and AC converters; electrical power distribution; bus systems; monitoring; load analysis)</li> <li>High Lift Systems (Principles; investigation of loads and system actuation power; principles and sizing of actuation and positioning systems; safety requirements and devices)</li> <li>Environmental Control Systems (Thermodynamic analysis; expansion and compression cooling systems; control strategies; cabin pressure control systems)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>Moir, Seabridge: Aircraft Systems</li> <li>Green: Aircraft Hydraulic Systems</li> <li>Torenbek: Synthesis of Subsonic Airplane Design</li> <li>SAE1991: ARP; Air Conditioning Systems for Subsonic Airplanes</li> </ul>

Course L0739: Aircraft Systems I	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Frank Thielecke
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0812: Aircraft Design	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Aircraft Design I (L0820)	Lecture
Aircraft Design I (L0834)	Recitation Section (large)
Aircraft Design II (Detailed Design Methods for Aerodynamics and Aircraft Structures, Multidisciplinary Design) (L0844)	Lecture
Aircraft Design II (Detailed Design Methods for Aerodynamics and Aircraft Structures, Multidisciplinary Design) (L0847)	Project Seminar
<b>Hrs/wk</b>	<b>CP</b>
2	2
1	1
2	2
1	1
<b>Module Responsible</b>	Prof. Volker Gollnick
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Bachelor Mech. Eng.</li> <li>• Vordiplom Mech. Eng.</li> <li>• Module Air Transport Systems</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ol style="list-style-type: none"> <li>1. Principle understanding of integrated aircraft design</li> <li>2. Understanding of the interactions and contributions of the various disciplines</li> <li>3. Impact of the relevant design parameter on the aircraft design</li> <li>4. Introduction of the principle design methods</li> </ol>
<i>Skills</i>	<p>Understanding and application of design and calculation methods</p> <p>Understanding of interdisciplinary and integrative interdependencies</p>
<b>Personal Competence</b>	Working in interdisciplinary teams
<i>Social Competence</i>	Communication
<i>Autonomy</i>	Organization of workflows and -strategies
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0820: Aircraft Design I	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Volker Gollnick
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	Introduction into the aircraft design process <ol style="list-style-type: none"> <li>1. Introduction/process of aircraft design/various aircraft configurations</li> <li>2. Requirements and design objectives, main design parameter (u.a. payload-range-diagramme)</li> <li>3. Statistical methods in overall aircraft design/data base methods</li> <li>4. Principles of aircraft performance design (stability, V-n-diagramme)</li> <li>5. Principles of aerodynamic aircraft design (polar, geometry, 2D/3D aerodynamics)</li> <li>6. Principles of structural fuselage and wing design (mass analysis, beam/tube models, geometry)</li> <li>7. Principles of engine design and integration</li> <li>8. Cruise design</li> <li>9. Design of runway and landing field length</li> <li>10. Cabin design (fuselage dimensioning, cabin interior, loading systems)</li> <li>11. System- and equipment aspects</li> <li>12. Design variations and operating cost calculation</li> </ol>
<b>Literature</b>	J. Roskam: "Airplane Design" D.P. Raymer: "Aircraft Design - A Conceptual Approach" J.P. Fielding: "Introduction to Aircraft Design" Jenkinson, Simpkin, Rhoads: "Civil Jet Aircraft Design"



<b>Course L0834: Aircraft Design I</b>	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Volker Gollnick
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	Training in applying MatLab Application of design methods for civil aircraft concerning: Fuselage and Cabin sizing and design Calculation of aircraft masses Aerodynamic and geometric wing design TakeOff, landing cruise performance calculation Manoeuvre and gust load calculation
<b>Literature</b>	J. Roskam: "Airplane Design" D.P. Raymer: "Aircraft Design - A Conceptual Approach" J.P. Fielding: "Introduction to Aircraft Design" Jenkinson, Simpkin, Rhoads: "Civil Jet Aircraft Design"

<b>Course L0844: Aircraft Design II (Detailed Design Methods for Aerodynamics and Aircraft Structures, Multidisciplinary Design)</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Volker Gollnick, Dr.-Ing. Bernd Liebhardt
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Physical modelling in aircraft design Introduction - Numerical design process Parameterization and data formats Numerical beam models and lifting line Data base driven engine design Coupling (interpolation, time incremental process Aeroelastic effects Optimization methods in aircraft design Light weight design aspects in aircraft design Limits of simple design methods Numerical wing design
<b>Literature</b>	Horst Kossira: "Grundlagen des Leichtbaus. Einführung in die Theorie dünnwandiger stabförmiger Tragwerke" Johannes Wiedemann: "Leichtbau - Elemente und Konstruktion"

<b>Course L0847: Aircraft Design II (Detailed Design Methods for Aerodynamics and Aircraft Structures, Multidisciplinary Design)</b>	
<b>Typ</b>	Project Seminar
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Volker Gollnick, Dr.-Ing. Bernd Liebhardt
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1043: Aircraft Systems Engineering			
Courses			
Title	Typ	Hrs/wk	CP
Design Optimization and Probabilistic Approaches in Structural Analysis (L1814)	Seminar	3	3
Fatigue & Damage Tolerance (L0310)	Lecture	2	3
Lightweight Construction with Fibre Reinforced Polymers - Structural Mechanics (L1514)	Lecture	2	2
Lightweight Construction with Fibre Reinforced Polymers - Structural Mechanics (L1515)	Recitation Section (large)	1	1
Lightweight Design Practical Course (L1258)	Project-/problem-based Learning	3	3
Aviation Security (L1549)	Lecture	2	2
Aviation Security (L1550)	Recitation Section (small)	1	1
Mechanisms, Systems and Processes of Materials Testing (L0950)	Lecture	2	2
Turbo Jet Engines (L0908)	Lecture	2	3
System Analysis in Air Transportation (L0855)	Lecture	3	3
Materials Testing (L0949)	Lecture	2	2
Reliability in Engineering Dynamics (L0176)	Lecture	2	2
Reliability in Engineering Dynamics (L1303)	Recitation Section (small)	1	2
Reliability of avionics assemblies (L1554)	Lecture	2	2
Reliability of avionics assemblies (L1555)	Recitation Section (small)	1	1
Reliability of Aircraft Systems (L0749)	Lecture	2	3
<b>Module Responsible</b>	Prof. Frank Thielecke		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Electrical Engineering</li> <li>• Hydraulics</li> <li>• Control Systems</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<ul style="list-style-type: none"> <li>• Students are able to find their way through selected special areas within systems engineering, air transportation system and material science</li> <li>• Students are able to explain basic models and procedures in selected special areas.</li> <li>• Students are able to interrelate scientific and technical knowledge.</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	Students are able to apply basic methods in selected areas of engineering.		
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>	Students can chose independently, in which fields they want to deepen their knowledge and skills through the election of courses.		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1814: Design Optimization and Probabilistic Approaches in Structural Analysis	
<b>Typ</b>	Seminar
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Examination Form</b>	Schriftliche Ausarbeitung
<b>Examination duration and scale</b>	ca. 10 Seiten und Diskussion
<b>Lecturer</b>	Prof. Benedikt Kriegesmann
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>In the course the theoretic basics for design optimization and reliability analysis are taught, where the focus is on the application of such methods. The lectures will consist of presentations as well as computer exercises. In the computer exercises, the methods learned will be implemented in Matlab for understanding the practical realization.</p> <p>The following contents will be considered:</p> <ul style="list-style-type: none"> <li>• Design optimization           <ul style="list-style-type: none"> <li>◦ Gradient based methods</li> <li>◦ Genetic algorithms</li> <li>◦ Optimization with constraints</li> <li>◦ Topology optimization</li> </ul> </li> <li>• Reliability analysis           <ul style="list-style-type: none"> <li>◦ Stochastic basics</li> <li>◦ Monte Carlo methods</li> <li>◦ Semi-analytic approaches</li> </ul> </li> <li>• robust design optimization           <ul style="list-style-type: none"> <li>◦ Robustness measures</li> <li>◦ Coupling of design optimization and reliability analysis</li> </ul> </li> </ul>
<b>Literature</b>	<p>[1] Arora, Jasbir. Introduction to Optimum Design. 3rd ed. Boston, MA: Academic Press, 2011.</p> <p>[2] Haldar, A., and S. Mahadevan. Probability, Reliability, and Statistical Methods in Engineering Design. John Wiley &amp; Sons New York/Chichester, UK, 2000.</p>

Course L0310: Fatigue & Damage Tolerance	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	45 min
<b>Lecturer</b>	Dr. Martin Flamm
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	Design principles, fatigue strength, crack initiation and crack growth, damage calculation, counting methods, methods to improve fatigue strength, environmental influences
<b>Literature</b>	Jaap Schijve, Fatigue of Structures and Materials. Kluwer Academic Publisher, Dordrecht, 2001 E. Haibach. Betriebsfestigkeit Verfahren und Daten zur Bauteilberechnung. VDI-Verlag, Düsseldorf, 1989

Course L1514: Lightweight Construction with Fibre Reinforced Polymers - Structural Mechanics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Marco Schürg
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p><b>Fundamentals of Anisotropic Elasticity</b></p> <p>Displacements, strains and stresses; Equilibrium equations; Kinematics; Hooke's generalized law</p> <p><b>Behaviour of a single laminate layer</b></p> <p>Material law of a single laminate layer; Full anisotropy and coupling effects; Material symmetries; Engineering constants; Plane state of stress; Transformation rules</p> <p><b>Fundamentals of Micromechanics of a laminate layer</b></p> <p>Representative unit cell; Determination of effective material constants; Effective stiffness properties of a single layer</p> <p><b>Classical Laminate Plate Theory</b></p> <p>Notations and laminate code; Kinematics and displacement field; Strains and stresses, stress resultants; Constitutive equations and coupling effects; Special laminates and their behavior; Effective laminate properties</p> <p><b>Strength of Laminated Plates</b></p> <p>Fundamental concept; Phenomenological failure criteria: maximum stresses, maximum strains, Tsai-Hill, Tsai-Wu, Puck, Hashin</p> <p><b>Bending of Composite Laminated Plates</b></p> <p>Differential Equations; Boundary Conditions; Navier-type solutions; Lévy-type solutions</p> <p><b>Stress Concentration Problems</b></p> <p>Free-edge effects; Stress concentrations at holes, cracks, delaminations; Aspects of failure analysis</p> <p><b>Stability of Thin-Walled Composite Structures</b></p> <p>Buckling of anisotropic plates and shells; Influence of loading conditions; Influence of boundary conditions; Exact transcendental solutions and their evaluation; Buckling of stiffened composite plates; Minimum stiffness requirements; Local buckling of stiffener profiles</p> <p><b>Written exercise (report required)</b></p> <p>Assessment of a thin-walled composite laminated beam taking several different dimensioning criteria into account</p>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Schürmann, H., „Konstruieren mit Faser-Kunststoff-Verbunden“, Springer, Berlin, aktuelle Auflage.</li> <li>• Wiedemann, J., „Leichtbau Band 1: Elemente“, Springer, Berlin, Heidelberg, , aktuelle Auflage.</li> <li>• Reddy, J.N., „Mechanics of Composite Laminated Plates and Shells“, CRC Publishing, Boca Raton et al., current edition.</li> <li>• Jones, R.M., „Mechanics of Composite Materials“, Scripta Book Co., Washington, current edition.</li> <li>• Timoshenko, S.P., Gere, J.M., „Theory of elastic stability“, McGraw-Hill Book Company, Inc., New York, current edition.</li> <li>• Turvey, G.J., Marshall, I.H., „Buckling and postbuckling of composite plates“, Chapman and Hall, London, current edition.</li> <li>• Herakovich, C.T., „Mechanics of fibrous composites“, John Wiley and Sons, Inc., New York, current edition.</li> <li>• Mittelstedt, C., Becker, W., „Strukturmechanik ebener Laminate“, aktuelle Auflage.</li> </ul>

Course L1515: Lightweight Construction with Fibre Reinforced Polymers - Structural Mechanics	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Marco Schürg
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1258: Lightweight Design Practical Course	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Development of a sandwich structure made of fibre reinforced plastics</p> <ul style="list-style-type: none"> <li>• getting familiar with fibre reinforced plastics as well as lightweight design</li> <li>• Design of a sandwich structure made of fibre reinforced plastics using finite element analysis (FEA)</li> <li>• Determination of material properties based on sample tests</li> <li>• manufacturing of the structure in the composite lab</li> <li>• Testing of the developed structure</li> <li>• Concept presentation</li> <li>• Self-organised teamwork</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Schürmann, H., „Konstruieren mit Faser-Kunststoff-Verbunden“, Springer, Berlin, 2005.</li> <li>• Puck, A., „Festigkeitsanalyse von Faser-Matrix-Laminaten“, Hanser, München, Wien, 1996.</li> <li>• R&amp;G, „Handbuch Faserverbundwerkstoffe“, Waldenbuch, 2009.</li> <li>• VDI 2014 „Entwicklung von Bauteilen aus Faser-Kunststoff-Verbund“</li> <li>• Ehrenstein, G. W., „Faserverbundkunststoffe“, Hanser, München, 2006.</li> <li>• Klein, B., „Leichtbau-Konstruktion“, Vieweg &amp; Sohn, Braunschweig, 1989.</li> <li>• Wiedemann, J., „Leichtbau Band 1: Elemente“, Springer, Berlin, Heidelberg, 1986.</li> <li>• Wiedemann, J., „Leichtbau Band 2: Konstruktion“, Springer, Berlin, Heidelberg, 1986.</li> <li>• Backmann, B.F., „Composite Structures, Design, Safety and Innovation“, Oxford (UK), Elsevier, 2005.</li> <li>• Krause, D., „Leichtbau“, In: Handbuch Konstruktion, Hrsg.: Rieg, F., Steinhilper, R., München, Carl Hanser Verlag, 2012.</li> <li>• Schulte, K., Fiedler, B., „Structure and Properties of Composite Materials“, Hamburg, TUHH - TuTech Innovation GmbH, 2005.</li> </ul>

Course L1549: Aviation Security	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge about tasks and measures for protection against attacks on the security of the commercial air transport system. Tasks and measures will be elicited in the context of the three system components man, technology and organization.</p> <p>The course teaches the basics of aviation security. Aviation security is a necessary prerequisite for an economically successful air transport system. Risk management for the entire system can only be successful in an integrated approach, considering man, technology and organization:</p> <ul style="list-style-type: none"> <li>• Historical development</li> <li>• The special role of air transport</li> <li>• Motive and attack vectors</li> <li>• The human factor</li> <li>• Threats and risk</li> <li>• Regulations and law</li> <li>• Organization and implementation of aviation security tasks</li> <li>• Passenger and baggage checks</li> <li>• Cargo screening and secure supply chain</li> <li>• Safety technologies</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- Gjemulla, E.M., Rothe B.R. (Hrsg.): Handbuch Luftsicherheit. Universitätsverlag TU Berlin, 2011</li> <li>- Thomas, A.R. (Ed.): Aviation Security Management. Praeger Security International, 2008</li> </ul>

Course L1550: Aviation Security	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge about tasks and measures for protection against attacks on the security of the commercial air transport system. Tasks and measures will be elicited in the context of the three system components man, technology and organization.</p> <p>The course teaches the basics of aviation security. Aviation security is a necessary prerequisite for an economically successful air transport system. Risk management for the entire system can only be successful in an integrated approach, considering man, technology and organization:</p> <ul style="list-style-type: none"> <li>• Historical development</li> <li>• The special role of air transport</li> <li>• Motive and attack vectors</li> <li>• The human factor</li> <li>• Threats and risk</li> <li>• Regulations and law</li> <li>• Organization and implementation of aviation security tasks</li> <li>• Passenger and baggage checks</li> <li>• Cargo screening and secure supply chain</li> <li>• Safety technologies</li> </ul>
<b>Literature</b>	<p>- Skript zur Vorlesung</p> <p>- Gjemulla, E.M., Rothe B.R. (Hrsg.): Handbuch Luftsicherheit. Universitätsverlag TU Berlin, 2011</p> <p>- Thomas, A.R. (Ed.): Aviation Security Management. Praeger Security International, 2008</p>

Course L0950: Mechanisms, Systems and Processes of Materials Testing	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Dr. Jan Oke Peters
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Application, analysis and discussion of basic and advanced testing methods to ensure correct selection of applicable testing procedure for investigation of part/materials deficiencies</p> <ul style="list-style-type: none"> <li>• Stress-strain relationships</li> <li>• Strain gauge application</li> <li>• Visko elastic behavior</li> <li>• Tensile test (strain hardening, necking, strain rate)</li> <li>• Compression test, bending test, torsion test</li> <li>• Crack growth upon static loading (J-Integral)</li> <li>• Crack growth upon cyclic loading (micro- und macro cracks)</li> <li>• Effect of notches</li> <li>• Creep testing (physical creep test, influence of stress and temperature, Larson Miller parameter)</li> <li>• Wear testing</li> <li>• Non destructive testing application for overhaul of jet engines</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• E. Macherauch: Praktikum in Werkstoffkunde, Vieweg</li> <li>• G. E. Dieter: Mechanical Metallurgy, McGraw-Hill</li> <li>• R. Bürgel: Lehr- und Übungsbuch Festigkeitslehre, Vieweg</li> <li>• R. Bürgel: Werkstoffe sicher beurteilen und richtig einsetzen, Vieweg</li> </ul>

Course L0908: Turbo Jet Engines	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	45 min
<b>Lecturer</b>	Dr. Burkhard Andrich
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Cycle of the gas turbine</li> <li>• Thermodynamics of gas turbine components</li> <li>• Wing-, grid- and stage-sizing</li> <li>• Operating characteristics of gas turbine components</li> <li>• Sizing criteria's for jet engines</li> <li>• Development trends of gas turbines and jet engines</li> <li>• Maintenance of jet engines</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Bräunling: Flugzeugtriebwerke</li> <li>• Engmann: Technologie des Fliegens</li> <li>• Kerrebrock: Aircraft Engines and Gas Turbines</li> </ul>

Course L0855: System Analysis in Air Transportation	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	60 Minuten
<b>Lecturer</b>	Dr. Marco Weiss
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Introduction to the Air Transport System</li> <li>2. System analysis methodologies</li> <li>3. Technology management</li> <li>4. Technical analysis methods</li> <li>5. Economical analysis methods</li> <li>6. Ecological analysis methods</li> <li>7. Societal analysis methods</li> <li>8. Research on the future</li> <li>9. Synthesis, overall assessment, decision making</li> <li>10. Case studies - Technology Push</li> <li>11. Case studies - Scenario Pull</li> </ol>
<b>Literature</b>	Hand out

Course L0949: Materials Testing	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Dr. Jan Oke Peters
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Application and analysis of basic mechanical as well as non-destructive testing of materials</p> <ul style="list-style-type: none"> <li>• Determination elastic constants</li> <li>• Tensile test</li> <li>• Fatigue test (testing with constant stress, strain, or plastiv strain amplitude, low and high cycle fatigue, mean stress effect)</li> <li>• Crack growth upon static loading (stress intensity factor, fracture toughness)</li> <li>• Creep test</li> <li>• Hardness test</li> <li>• Charpy impact test</li> <li>• Non destructive testing</li> </ul>
<b>Literature</b>	<p>E. Macherauch: Praktikum in Werkstoffkunde, Vieweg            G. E. Dieter: Mechanical Metallurgy, McGraw-Hill</p>

Course L0176: Reliability in Engineering Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 min.
<b>Lecturer</b>	Prof. Uwe Weltin
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Method for calculation and testing of reliability of dynamic machine systems</p> <ul style="list-style-type: none"> <li>• Modeling</li> <li>• System identification</li> <li>• Simulation</li> <li>• Processing of measurement data</li> <li>• Damage accumulation</li> <li>• Test planning and execution</li> </ul>
<b>Literature</b>	<p>Bertsche, B.: Reliability in Automotive and Mechanical Engineering. Springer, 2008. ISBN: 978-3-540-33969-4            Inman, Daniel J.: Engineering Vibration. Prentice Hall, 3rd Ed., 2007. ISBN-13: 978-0132281737            Dresig, H., Holzweißig, F.: Maschinendynamik, Springer Verlag, 9. Auflage, 2009. ISBN 3540876936.            VDA (Hg.): Zuverlässigkeitssicherung bei Automobilherstellern und Lieferanten. Band 3 Teil 2, 3. überarbeitete Auflage, 2004. ISSN 0943-9412</p>

Course L1303: Reliability in Engineering Dynamics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 min
<b>Lecturer</b>	Prof. Uwe Weltin
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course



Course L1554: Reliability of avionics assemblies	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge for development, electronic packaging technology and the production of electronic components for safety-critical applications. On an item, component and system level it is shown, how the specified safety objectives for electronics in aircraft can be achieved. Current challenges, such as availability of components, component counterfeiting and the use of components off-the-shelf (COTS) will be discussed:</p> <ul style="list-style-type: none"> <li>• Survey of the role of electronics in aviation</li> <li>• System levels: From silicon to mechatronic systems</li> <li>• Semiconductor components, assemblies, systems</li> <li>• Challenges of electronic packaging technology (AVT)</li> <li>• System integration in electronics: Requirements for AVT</li> <li>• Methods and techniques of AVT</li> <li>• Error patterns for assemblies and avoidance of errors</li> <li>• Reliability analysis for printed circuit boards (PCBs)</li> <li>• Reliability of Avionics</li> <li>• COTS, ROTS, MOTS and the F<sup>3</sup>I concept</li> <li>• Future challenges for electronics</li> </ul>
<b>Literature</b>	<p>- Skript zur Vorlesung</p> <p>Hanke, H.-J.: Baugruppentechologie der Elektronik. Leiterplatten. Verlag Technik, 1994</p> <p>Scheel, W.: Baugruppentechologie der Elektronik.</p> <p>Montage. Verlag Technik, 1999</p>

Course L1555: Reliability of avionics assemblies	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge for development, electronic packaging technology and the production of electronic components for safety-critical applications. On an item, component and system level it is shown, how the specified safety objectives for electronics in aircraft can be achieved. Current challenges, such as availability of components, component counterfeiting and the use of components off-the-shelf (COTS) will be discussed:</p> <ul style="list-style-type: none"> <li>• Survey of the role of electronics in aviation</li> <li>• System levels: From silicon to mechatronic systems</li> <li>• Semiconductor components, assemblies, systems</li> <li>• Challenges of electronic packaging technology (AVT)</li> <li>• System integration in electronics: Requirements for AVT</li> <li>• Methods and techniques of AVT</li> <li>• Error patterns for assemblies and avoidance of errors</li> <li>• Reliability analysis for printed circuit boards (PCBs)</li> <li>• Reliability of Avionics</li> <li>• COTS, ROTS, MOTS and the F<sup>3</sup>I concept</li> <li>• Future challenges for electronics</li> </ul>
<b>Literature</b>	<p>- Skript zur Vorlesung</p> <p>Hanke, H.-J.: Baugruppentechologie der Elektronik. Leiterplatten. Verlag Technik, 1994</p> <p>Scheel, W.: Baugruppentechologie der Elektronik.</p> <p>Montage. Verlag Technik, 1999</p>

<b>Course L0749: Reliability of Aircraft Systems</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	90 Minuten
<b>Lecturer</b>	Prof. Frank Thielecke, Dr. Andreas Vahl, Dr. Uwe Wiczorek
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Functions of reliability and safety (regulations, certification requirements)</li> <li>• Basics methods of reliability analysis (FMEA, fault tree, functional hazard assessment)</li> <li>• Reliability analysis of electrical and mechanical systems</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• CS 25.1309</li> <li>• SAE ARP 4754</li> <li>• SAE ARP 4761</li> </ul>

Module M1193: Cabin Systems Engineering			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Computer and communication technology in cabin electronics and avionics (L1557)	Lecture	2	2
Computer and communication technology in cabin electronics and avionics (L1558)	Recitation Section (small)	1	1
Model-Based Systems Engineering (MBSE) with SysML/UML (L1551)	Project-/problem-based Learning	3	3
<b>Module Responsible</b>	Prof. Ralf God		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Electrical Engineering</li> <li>• Control Systems</li> </ul> Previous knowledge in: <ul style="list-style-type: none"> <li>• Systems Engineering</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• describe the structure and operation of computer architectures</li> <li>• explain the structure and operation of digital communication Networks</li> <li>• explain architectures of cabin electronics, integrated modular avionics (IMA) and Aircraft Data Communication Network (ADCN)</li> <li>• understand the approach of Model-Based Systems Engineering (MBSE) in the design of hardware and software-based cabin systems</li> </ul>		
<b>Knowledge</b>			
<b>Skills</b>	Students are able to: <ul style="list-style-type: none"> <li>• understand, operate and maintain a Minicomputer</li> <li>• build up a network communication and communicate with other network participants</li> <li>• connect a minicomputer with a cabin management system (A380 CIDS) and communicate over a AFDX®-Network</li> <li>• model system functions by means of formal languages SysML/UML and generate software code from the models</li> <li>• execute software code on a minicomputer</li> </ul>		
<b>Personal Competence</b>			
<b>Social Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• elaborate partial results and merge with others to form a complete solution</li> </ul>		
<b>Autonomy</b>	Students are able to: <ul style="list-style-type: none"> <li>• organize and schedule their practical tasks</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 minutes		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1557: Computer and communication technology in cabin electronics and avionics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge of computer and communication technology in electronic systems in the cabin and in aircraft. For the system engineer the strong interaction of software, mechanical and electronic system components nowadays requires a basic understanding of cabin electronics and avionics.</p> <p>The course teaches the basics of design and functionality of computers and data networks. Subsequently it focuses on current principles and applications in integrated modular avionics (IMA), aircraft data communication networks (ADCN), cabin electronics and cabin networks:</p> <ul style="list-style-type: none"> <li>• History of computer and network technology</li> <li>• Layer model in computer technology</li> <li>• Computer architectures (PC, IPC, Embedded Systems)</li> <li>• BIOS, UEFI and operating system (OS)</li> <li>• Programming languages (machine code and high-level languages)</li> <li>• Applications and Application Programming Interfaces</li> <li>• External interfaces (serial, USB, Ethernet)</li> <li>• Layer model in network technology</li> <li>• Network topologies</li> <li>• Network components</li> <li>• Bus access procedures</li> <li>• Integrated Modular Avionics (IMA) and Aircraft Data Communication Networks (ADCN)</li> <li>• Cabin electronics and cabin networks</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- Schnabel, P.: Computertechnik-Fibel: Grundlagen Computertechnik, Mikroprozessortechnik, Halbleiterspeicher, Schnittstellen und Peripherie. Books on Demand; 1. Auflage, 2003</li> <li>- Schnabel, P.: Netzwerktechnik-Fibel: Grundlagen, Übertragungstechnik und Protokolle, Anwendungen und Dienste, Sicherheit. Books on Demand; 1. Auflage, 2004</li> <li>- Wüst, K.: Mikroprozessortechnik: Grundlagen, Architekturen und Programmierung von Mikroprozessoren, Mikrocontrollern und Signalprozessoren. Vieweg Verlag; 2. aktualisierte und erweiterte Auflage, 2006</li> </ul>

Course L1558: Computer and communication technology in cabin electronics and avionics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge of computer and communication technology in electronic systems in the cabin and in aircraft. For the system engineer the strong interaction of software, mechanical and electronic system components nowadays requires a basic understanding of cabin electronics and avionics.</p> <p>The course teaches the basics of design and functionality of computers and data networks. Subsequently it focuses on current principles and applications in integrated modular avionics (IMA), aircraft data communication networks (ADCN), cabin electronics and cabin networks:</p> <ul style="list-style-type: none"> <li>• History of computer and network technology</li> <li>• Layer model in computer technology</li> <li>• Computer architectures (PC, IPC, Embedded Systems)</li> <li>• BIOS, UEFI and operating system (OS)</li> <li>• Programming languages (machine code and high-level languages)</li> <li>• Applications and Application Programming Interfaces</li> <li>• External interfaces (serial, USB, Ethernet)</li> <li>• Layer model in network technology</li> <li>• Network topologies</li> <li>• Network components</li> <li>• Bus access procedures</li> <li>• Integrated Modular Avionics (IMA) and Aircraft Data Communication Networks (ADCN)</li> <li>• Cabin electronics and cabin networks</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- Schnabel, P.: Computertechnik-Fibel: Grundlagen Computertechnik, Mikroprozessortechnik, Halbleiterspeicher, Schnittstellen und Peripherie. Books on Demand; 1. Auflage, 2003</li> <li>- Schnabel, P.: Netzwerktechnik-Fibel: Grundlagen, Übertragungstechnik und Protokolle, Anwendungen und Dienste, Sicherheit. Books on Demand; 1. Auflage, 2004</li> <li>- Wüst, K.: Mikroprozessortechnik: Grundlagen, Architekturen und Programmierung von Mikroprozessoren, Mikrocontrollern und Signalprozessoren. Vieweg Verlag; 2. aktualisierte und erweiterte Auflage, 2006</li> </ul>

<b>Course L1551: Model-Based Systems Engineering (MBSE) with SysML/UML</b>	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Objectives of the problem-oriented course are the acquisition of knowledge on system design using the formal languages SysML/UML, learning about tools for modeling and finally the implementation of a project with methods and tools of Model-Based Systems Engineering (MBSE) on a realistic hardware platform (e.g. Arduino®, Raspberry Pi®):</p> <ul style="list-style-type: none"> <li>• What is a model?</li> <li>• What is Systems Engineering?</li> <li>• Survey of MBSE methodologies</li> <li>• The modelling languages SysML /UML</li> <li>• Tools for MBSE</li> <li>• Best practices for MBSE</li> <li>• Requirements specification, functional architecture, specification of a solution</li> <li>• From model to software code</li> <li>• Validation and verification: XiL methods</li> <li>• Accompanying MBSE project</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- Weilkiens, T.: Systems Engineering mit SysML/UML: Modellierung, Analyse, Design. 2. Auflage, dpunkt.Verlag, 2008</li> <li>- Holt, J., Perry, S.A., Brownsword, M.: Model-Based Requirements Engineering. Institution Engineering &amp; Tech, 2011</li> </ul>

Module M0771: Flight Physics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Aerodynamics and Flight Mechanics I (L0727)	Lecture                                      3                                      3
Flight Mechanics II (L0730)	Lecture                                      2                                      2
Flight Mechanics II (L0731)	Recitation Section (large)                      1                                      1
<b>Module Responsible</b>	Prof. Frank Thielecke
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Aviation</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	
<i>Skills</i>	
<b>Personal Competence</b>	
<i>Social Competence</i>	
<i>Autonomy</i>	
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 Minutes (WS) + 90 Minutes (SS)
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0727: Aerodynamics and Flight Mechanics I	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Klaus-Uwe Hahn, Dr. Ralf Heinrich, Mike Montel
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Aerodynamics (fundamental equations of aerodynamics; compressible and incompressible flows; airfoils and wings; viscous flows)</li> <li>• Flight Mechanics (Equations of motion; flight performance; control surfaces; derivatives; lateral stability and control; trim conditions; flight maneuvers)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Schlichting, H.; Truckenbrodt, E.: Aerodynamik des Flugzeuges I und II</li> <li>• Etkin, B.: Dynamics of Atmospheric Flight</li> <li>• Sachs/Hafer: Flugmechanik</li> <li>• Brockhaus: Flugregelung</li> <li>• J.D. Anderson: Introduction to flight</li> </ul>

Course L0730: Flight Mechanics II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Klaus-Uwe Hahn, Dr. Gerko Wende
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• stationary asymmetric flight</li> <li>• dynamics of lateral movement</li> <li>• methods of flight simulation</li> <li>• experimental methods of flight mechanics</li> <li>• model validation using system identification</li> <li>• wind tunnel techniques</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Schlichting, H.; Truckenbrodt, E.: Aerodynamik des Flugzeuges I und II</li> <li>• Etkin, B.: Dynamics of Atmospheric Flight</li> <li>• Sachs/Hafer: Flugmechanik</li> <li>• Brockhaus: Flugregelung</li> <li>• J.D. Anderson: Introduction to flight</li> </ul>

Course L0731: Flight Mechanics II	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Klaus-Uwe Hahn, Dr. Gerko Wende
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	see FSPO		
<i>Skills</i>	see FSPO		
<b>Personal Competence</b>			
<i>Social Competence</i>	see FSPO		
<i>Autonomy</i>	see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		



Module M1156: Systems Engineering			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Systems Engineering (L1547)	Lecture	3	4
Systems Engineering (L1548)	Recitation Section (large)	1	2
<b>Module Responsible</b>	Prof. Ralf God		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Electrical Engineering</li> <li>• Control Systems</li> </ul> Previous knowledge in: <ul style="list-style-type: none"> <li>• Aircraft Cabin Systems</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• understand systems engineering process models, methods and tools for the development of complex Systems</li> <li>• describe innovation processes and the need for technology Management</li> <li>• explain the aircraft development process and the process of type certification for aircraft</li> <li>• explain the system development process, including requirements for systems reliability</li> <li>• identify environmental conditions and test procedures for airborne Equipment</li> <li>• value the methodology of requirements-based engineering (RBE) and model-based requirements engineering (MBRE)</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	Students are able to: <ul style="list-style-type: none"> <li>• plan the process for the development of complex Systems</li> <li>• organize the development phases and development Tasks</li> <li>• assign required business activities and technical Tasks</li> <li>• apply systems engineering methods and tools</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students are able to: <ul style="list-style-type: none"> <li>• understand their responsibilities within a development team and integrate themselves with their role in the overall process</li> </ul>		
<i>Autonomy</i>	Students are able to: <ul style="list-style-type: none"> <li>• interact and communicate in a development team which has distributed tasks</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 Minutes		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory		

Course L1547: Systems Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is to accomplish the prerequisites for the development and integration of complex systems using the example of commercial aircraft and cabin systems. Competences in the systems engineering process, tools and methods is to be achieved. Regulations, guidelines and certification issues will be known.</p> <p>Key aspects of the course are processes for innovation and technology management, system design, system integration and certification as well as tools and methods for systems engineering:</p> <ul style="list-style-type: none"> <li>• Innovation processes</li> <li>• IP-protection</li> <li>• Technology management</li> <li>• Systems engineering</li> <li>• Aircraft program</li> <li>• Certification issues</li> <li>• Systems development</li> <li>• Safety objectives and fault tolerance</li> <li>• Environmental and operating conditions</li> <li>• Tools for systems engineering</li> <li>• Requirements-based engineering (RBE)</li> <li>• Model-based requirements engineering (MBRE)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- diverse Normen und Richtlinien (EASA, FAA, RTCA, SAE)</li> <li>- Hauschildt, J., Salomo, S.: Innovationsmanagement. Vahlen, 5. Auflage, 2010</li> <li>- NASA Systems Engineering Handbook, National Aeronautics and Space Administration, 2007</li> <li>- Hinsch, M.: Industrielles Luftfahrtmanagement: Technik und Organisation luftfahrttechnischer Betriebe. Springer, 2010</li> <li>- De Florio, P.: Airworthiness: An Introduction to Aircraft Certification. Elsevier Ltd., 2010</li> <li>- Pohl, K.: Requirements Engineering. Grundlagen, Prinzipien, Techniken. 2. korrigierte Auflage, dpunkt.Verlag, 2008</li> </ul>

Course L1548: Systems Engineering	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0764: Aircraft Systems II	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Aircraft Systems II (L0736)	Lecture
Aircraft Systems II (L0740)	Recitation Section (large)
	<b>Hrs/wk</b>
	3
	2
	<b>CP</b>
	4
	2
<b>Module Responsible</b>	Prof. Frank Thielecke
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	basic knowledge of: <ul style="list-style-type: none"> <li>• mathematics</li> <li>• mechanics</li> <li>• thermo dynamics</li> <li>• electronics</li> <li>• fluid technology</li> <li>• control technology</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	Students are able to... <ul style="list-style-type: none"> <li>• describe the structure of primary flight control systems as well as actuation-, avionic-, fuel- and landing gear-systems in general along with corresponding properties and applications.</li> <li>• explain different configurations and designs and their origins</li> <li>• explain atmospheric conditions for icing such as the functionality of anti-ice systems</li> </ul>
<i>Knowledge</i>	
<i>Skills</i>	Students are able to... <ul style="list-style-type: none"> <li>• size primary flight control actuation systems</li> <li>• perform a controller design process for the flight control actuators</li> <li>• design high-lift kinematics</li> <li>• design and analyse landing gear systems</li> <li>• design anti-ice systems</li> </ul>
<b>Personal Competence</b>	Students are able to: <ul style="list-style-type: none"> <li>• Develop joint solutions in mixed teams</li> </ul>
<i>Social Competence</i>	
<i>Autonomy</i>	Students are able to: <ul style="list-style-type: none"> <li>• derive requirements and perform appropriate yet simplified design processes for aircraft systems from complex issues and circumstances in a self-reliant manner</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	165 Minutes
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory

Course L0736: Aircraft Systems II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Frank Thielecke
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Actuation (Principles of actuators; electro-mechanical actuators; modeling, analysis and sizing of position control systems; hydro-mechanic actuation systems)</li> <li>• Flight Control Systems (control surfaces, hinge moments; requirements of stability and controllability, actuation power; principles of reversible and irreversible flight control systems; servo actuation systems)</li> <li>• Landing Gear Systems (Configurations and geometries; analysis of landing gear systems with respect to damper dynamics, dynamics of the breaking aircraft and power consumption; design and analysis of breaking systems with respect to energy and heat; anti-skid systems)</li> <li>• Fuel Systems (Architectures; aviation fuels; system components; fueling system; tank inerting system; fuel management; trim tank)</li> <li>• De- and Anti-Ice Systems: (Atmospheric icing conditions; principles of de- and anti-ice systems)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Moir, Seabridge: Aircraft Systems</li> <li>• Torenbek: Synthesis of Subsonic Airplane Design</li> <li>• Curry: Aircraft Landing Gear Design: Principles and Practices</li> </ul>

Course L0740: Aircraft Systems II	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Frank Thielecke
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1155: Aircraft Cabin Systems			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Aircraft Cabin Systems (L1545)	Lecture	3	4
Aircraft Cabin Systems (L1546)	Recitation Section (large)	1	2
<b>Module Responsible</b>	Prof. Ralf God		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Mechanics</li> <li>• Thermodynamics</li> <li>• Electrical Engineering</li> <li>• Control Systems</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students are able to:</p> <ul style="list-style-type: none"> <li>• describe cabin operations, equipment in the cabin and cabin Systems</li> <li>• explain the functional and non-functional requirements for cabin Systems</li> <li>• elucidate the necessity of cabin operating systems and emergency Systems</li> <li>• assess the challenges human factors integration in a cabin environment</li> </ul> <p><i>Skills</i></p> <p>Students are able to:</p> <ul style="list-style-type: none"> <li>• design a cabin layout for a given business model of an Airline</li> <li>• design cabin systems for safe operations</li> <li>• design emergency systems for safe man-machine interaction</li> <li>• solve comfort needs and entertainment requirements in the cabin</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>Students are able to:</p> <ul style="list-style-type: none"> <li>• understand existing system solutions and discuss their ideas with experts</li> </ul> <p><i>Autonomy</i></p> <p>Students are able to:</p> <ul style="list-style-type: none"> <li>• Reflect the contents of lectures and expert presentations self-dependent</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 Minutes		
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Energy Systems: Elective Compulsory Aircraft Systems Engineering: Core qualification: Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1545: Aircraft Cabin Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The objective of the lecture with the corresponding exercise is the acquisition of knowledge about aircraft cabin systems and cabin operations. A basic understanding of technological and systems engineering effort to maintain an artificial but comfortable and safe travel and working environment at cruising altitude is to be achieved.</p> <p>The course provides a comprehensive overview of current technology and cabin systems in modern passenger aircraft. The Fulfillment of requirements for the cabin as the central system of work are covered on the basis of the topics comfort, ergonomics, human factors, operational processes, maintenance and energy supply:</p> <ul style="list-style-type: none"> <li>• Materials used in the cabin</li> <li>• Ergonomics and human factors</li> <li>• Cabin interior and non-electrical systems</li> <li>• Cabin electrical systems and lights</li> <li>• Cabin electronics, communication-, information- and IFE-systems</li> <li>• Cabin and passenger process chains</li> <li>• RFID Aircraft Parts Marking</li> <li>• Energy sources and energy conversion</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Skript zur Vorlesung</li> <li>- Jenkinson, L.R., Simpkin, P., Rhodes, D.: Civil Jet Aircraft Design. London: Arnold, 1999</li> <li>- Rossow, C.-C., Wolf, K., Horst, P. (Hrsg.): Handbuch der Luftfahrzeugtechnik. Carl Hanser Verlag, 2014</li> <li>- Moir, I., Seabridge, A.: Aircraft Systems: Mechanical, Electrical and Avionics Subsystems Integration, Wiley 2008</li> <li>- Davies, M.: The standard handbook for aeronautical and astronautical engineers. McGraw-Hill, 2003</li> <li>- Kompendium der Flugmedizin. Verbesserte und ergänzte Neuauflage, Nachdruck April 2006. Fürstenfeldbruck, 2006</li> <li>- Campbell, F.C.: Manufacturing Technology for Aerospace Structural Materials. Elsevier Ltd., 2006</li> </ul>

Course L1546: Aircraft Cabin Systems	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Ralf God
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1213: Avionics for safety-critical Systems			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Avionics of Safty Critical Systems (L1640)	Lecture	2	3
Avionics of Safty Critical Systems (L1641)	Recitation Section (small)	1	1
Avionics of Safty Critical Systems (L1652)	Practical Course	1	2
<b>Module Responsible</b>	Dr. Martin Halle		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in: <ul style="list-style-type: none"> <li>• Mathematics</li> <li>• Electrical Engineering</li> <li>• Informatics</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	Students can: <ul style="list-style-type: none"> <li>• describe the most important principles and components of safety-critical avionics</li> <li>• denote processes and standards of safety-critical software development</li> <li>• depict the principles of Integrated Modular Avionics (IMA)</li> <li>• can compare hardware and bus systems used in avionics</li> <li>• assess the difficulties of developing a safety-critical avionics system correctly</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	Students can ... <ul style="list-style-type: none"> <li>• operate real-time hardware and simulations</li> <li>• program A653 applications</li> <li>• plan avionics architectures up to a certain extend</li> <li>• create test scripts and assess test results</li> </ul>		
<b>Personal Competence</b>	Students can: <ul style="list-style-type: none"> <li>• jointly develop solutions in inhomogeneous teams</li> <li>• exchange information formally with other teams</li> <li>• present development results in a convenient way</li> </ul>		
<i>Social Competence</i>			
<i>Autonomy</i>	Students can: <ul style="list-style-type: none"> <li>• understand the requirements for an avionics system</li> <li>• autonomously derive concepts for systems based on safety-critical avionics</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Avionic and Embedded Systems: Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory		

Course L1640: Avionics of Safty Critical Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Martin Halle
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Avionics are all kinds off flight electronics. Today there is no aircraft system function without avionics, and avionics are one main source of innovation in aerospace industry. Since many system functions are highly safety critical, the development of avionics hardware and software underlies mandatory constraints, technics, and processes. It is inevitable for system developers and computer engineers in aerospace industry to understand and master these. This lecture teaches the risks and techniques of developing safety critical hardware and software; major avionics components; integration; and test with a practical orientation. A focus is on Integrated Modular Avionics (IMA). The lecture is accompanied by a mandatory and laboratory exercises.</p> <p>Content:</p> <ol style="list-style-type: none"> <li>1. Introduction and History</li> <li>2. Flight Control</li> <li>3. Hardware</li> <li>4. I/O und Bus Systems</li> <li>5. Software</li> <li>6. Process und Certification</li> <li>7. Cockpit und Displays</li> <li>8. Integrated Modular Avionics I</li> <li>9. Integrated Modular Avionics II</li> <li>10. Design of IMA Systems</li> <li>11. Configuration of IMA Systems</li> <li>12. Verification and Test</li> <li>13. Integration</li> <li>14. Space avionics</li> </ol>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Moir, I.; Seabridge, A. &amp; Jukes, M., Civil Avionics Systems Civil Avionics Systems, John Wiley &amp; Sons, Ltd, 2013</li> <li>• Spitzer, C. R. Spitzer, Digital Avionics Handbook, CRC Press, 2007</li> <li>• FAA, Advanced Avionics Handbook U.S. Department of Transportation Federal Aviation Administration, 2009</li> <li>• Moir, I. &amp; Seabridge, A. Aircraft Systems, Wiley, 2008, 3</li> </ul>

Course L1641: Avionics of Safty Critical Systems	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Martin Halle
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1652: Avionics of Safty Critical Systems	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Martin Halle
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course



## Specialization Maritime Technology

At the center of the specialization Maritime Techniques lies the acquisition of knowledge and skills to develop, calculate and evaluate shipboard and offshore structures and their components. This is done in modules on the topics of marine engine systems, marine auxiliary systems, ship vibrations, maritime technology and maritime systems, port construction and port planning, port logistics, maritime transport and marine geotechnics and numerics in electives. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M1157: Marine Auxiliaries			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>		
<b>Hrs/wk</b>	<b>CP</b>		
Electrical Installation on Ships (L1531)	Lecture	2	2
Electrical Installation on Ships (L1532)	Recitation Section (large)	1	1
Auxiliary Systems on Board of Ships (L1249)	Lecture	2	2
Auxiliary Systems on Board of Ships (L1250)	Recitation Section (large)	1	1
<b>Module Responsible</b>	Prof. Christopher Friedrich Wirz		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>The students are able to</p> <ul style="list-style-type: none"> <li>• name the operating behaviour of consumers,</li> <li>• describe special requirements on the design of supply networks and to the electrical equipment in isolated networks, as e.g. onboard ships, offshore units, factories and emergency power supply systems,</li> <li>• explain power generation and distribution in isolated grids, wave generator systems on ships,</li> <li>• name requirements for network protection, selectivity and operational monitoring,</li> <li>• name the requirements regarding marine equipment and apply to product development, as well as</li> <li>• describe operating procedures of equipment components of standard and specialized ships and derive requirements for product development.</li> </ul> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• calculate short-circuit currents, switchgear,</li> <li>• design electrical propulsion systems for ships</li> <li>• design additional machinery components, as well as</li> <li>• to apply basic principles of hydraulics and to develop hydraulic systems.</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>	<p>The students are able to communicate and cooperate in a professional environment in the shipbuilding and component supply industry.</p> <p>The widespread scope of gained knowledge enables the students to handle situations in their future profession independently and confidently.</p>		
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	20 min		
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1531: Electrical Installation on Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Günter Ackermann
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• performance in service of electrical consumers.</li> <li>• special requirements for power supply systems and for electrical equipment in isolated systems/networks e. g. aboard ships, offshore installations, factory systems and emergency power supply systems.</li> <li>• power generation and distribution in isolated networks, shaft generators for ships</li> <li>• calculation of short circuits and behaviour of switching devices</li> <li>• protective devices, selectivity monitoring</li> <li>• electrical Propulsion plants for ships</li> </ul>
<b>Literature</b>	H. Meier-Peter, F. Bernhardt u. a.: Handbuch der Schiffsbetriebstechnik, Seehafen Verlag (engl. Version: "Compendium Marine Engineering") Gleß, Thamm: Schiffselektrotechnik, VEB Verlag Technik Berlin

Course L1532: Electrical Installation on Ships	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Günter Ackermann
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1249: Auxiliary Systems on Board of Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Vorschriften zur Schiffsausrüstung</li> <li>• Ausrüstungsanlagen auf Standard-Schiffen</li> <li>• Ausrüstungsanlagen auf Spezial-Schiffen</li> <li>• Grundlagen und Systemtechnik der Hydraulik</li> <li>• Auslegung und Betrieb von Ausrüstungsanlagen</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• H. Meyer-Peter, F. Bernhardt: Handbuch der Schiffsbetriebstechnik</li> <li>• H. Watter: Hydraulik und Pneumatik</li> </ul>

Course L1250: Auxiliary Systems on Board of Ships	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Siehe korrespondierende Vorlesung
<b>Literature</b>	

Module M1177: Maritime Technology and Maritime Systems			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Analysis of Maritime Systems (L0068)	Lecture	2	2
Analysis of Maritime Systems (L0069)	Recitation Section (small)	1	1
Introduction to Maritime Technology (L0070)	Lecture	2	2
Introduction to Maritime Technology (L1614)	Recitation Section (small)	1	1
<b>Module Responsible</b>	Prof. Moustafa Abdel-Maksoud		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Solid knowledge and competences in mechanics, fluid dynamics and analysis (series, periodic functions, continuity, differentiability, integration, multiple variables, ordinary and partial differential equations, boundary value problems, initial conditions and eigenvalue problems).		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>After successful completion of this class, students should have an overview about phenomena and methods in ocean engineering and the ability to apply and extend the methods presented.</p> <p>In detail, the students should be able to</p> <ul style="list-style-type: none"> <li>• describe the different aspects and topics in Maritime Technology,</li> <li>• apply existing methods to problems in Maritime Technology,</li> <li>• discuss limitations in present day approaches and perspectives in the future,</li> <li>• Techniques for the analysis of offshore systems,</li> <li>• Modeling and evaluation of dynamic systems,</li> <li>• System-oriented thinking, decomposition of complex systems.</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	The students learn the ability of apply and transfer existing methods and techniques on novel questions in maritime technologies. Furthermore, limits of the existing knowledge and future developments will be discussed.		
<b>Personal Competence</b>			
<i>Social Competence</i>	The processing of an exercise in a group of up to four students shall strengthen the communication and team-working skills and thus promote an important working technique of subsequent working days. The collaboration has to be illustrated in a community presentation of the results.		
<i>Autonomy</i>	The course contents are absorbed in an exercise work in a group and individually checked in a final exam in which a self-reflection of the learned is expected without tools.		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	180 min		
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0068: Analysis of Maritime Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud, Dr. Alexander Mitzlaff
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Hydrostatic analysis               <ul style="list-style-type: none"> <li>◦ Buoyancy,</li> <li>◦ Stability,</li> </ul> </li> <li>2. Hydrodynamic analysis               <ul style="list-style-type: none"> <li>◦ Froude-Krylov force</li> <li>◦ Morison's equation,</li> <li>◦ Radiation and diffraction</li> <li>◦ transparent/compact structures</li> </ul> </li> <li>3. Evaluation of offshore structures: Reliability techniques (security, reliability, disposability)               <ul style="list-style-type: none"> <li>◦ Short-term statistics</li> <li>◦ Long-term statistics and extreme events</li> </ul> </li> </ol>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• G. Clauss, E. Lehmann, C. Östergaard. Offshore Structures Volume I: Conceptual Design and Hydrodynamics. Springer Verlag Berlin, 1992</li> <li>• E. V. Lewis (Editor), Principles of Naval Architecture ,SNAME, 1988</li> <li>• Journal of Offshore Mechanics and Arctic Engineering</li> <li>• Proceedings of International Conference on Offshore Mechanics and Arctic Engineering</li> <li>• S. Chakrabarti (Ed.), Handbook of Offshore Engineering, Volumes 1-2, Elsevier, 2005</li> <li>• S. K. Chakrabarti, Hydrodynamics of Offshore Structures , WIT Press, 2001</li> </ul>

Course L0069: Analysis of Maritime Systems	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud, Dr. Alexander Mitzlaff
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Course L0070: Introduction to Maritime Technology</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Sven Hoog
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>1. Introduction</p> <ul style="list-style-type: none"> <li>• Ocean Engineering and Marine Research</li> <li>• The potentials of the seas</li> <li>• Industries and occupational structures</li> </ul> <p>2. Coastal and offshore Environmental Conditions</p> <ul style="list-style-type: none"> <li>• Physical and chemical properties of sea water and sea ice</li> <li>• Flows, waves, wind, ice</li> <li>• Biosphere</li> </ul> <p>3. Response behavior of Technical Structures</p> <p>4. Maritime Systems and Technologies</p> <ul style="list-style-type: none"> <li>• General Design and Installation of Offshore-Structures</li> <li>• Geophysical and Geotechnical Aspects</li> <li>• Fixed and Floating Platforms</li> <li>• Mooring Systems, Risers, Pipelines</li> <li>• Energy conversion: Wind, Waves, Tides</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Chakrabarti, S., Handbook of Offshore Engineering, vol. I/II, Elsevier 2005.</li> <li>• Gerwick, B.C., Construction of Marine and Offshore Structures, CRC-Press 1999.</li> <li>• Wagner, P., Meerestechnik, Ernst&amp;Sohn 1990.</li> <li>• Clauss, G., Meerestechnische Konstruktionen, Springer 1988.</li> <li>• Knauss, J.A., Introduction to Physical Oceanography, Waveland 2005.</li> <li>• Wright, J. et al., Waves, Tides and Shallow-Water Processes, Butterworth 2006.</li> <li>• Faltinsen, O.M., Sea Loads on Ships and Offshore Structures, Cambridge 1999.</li> </ul>

<b>Course L1614: Introduction to Maritime Technology</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Sven Hoog
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0663: Marine Geotechnics and Numerics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Marine Geotechnics (L0548)	Lecture	1	2
Marine Geotechnics (L0549)	Recitation Section (large)	1	1
Numerical Methods in Geotechnics (L0375)	Lecture	3	3
<b>Module Responsible</b>	Prof. Jürgen Grabe		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	complete modules: Geotechnics I-II, Mathematics I-III courses: Soil laboratory course		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Civil Engineering: Specialisation Geotechnical Engineering: Compulsory Civil Engineering: Specialisation Structural Engineering: Elective Compulsory Civil Engineering: Specialisation Coastal Engineering: Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Water and Environmental Engineering: Specialisation Cities: Elective Compulsory Water and Environmental Engineering: Specialisation Environment: Elective Compulsory Water and Environmental Engineering: Specialisation Water: Elective Compulsory		

Course L0548: Marine Geotechnics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Jürgen Grabe
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Geotechnical investigation an description of the seabed</li> <li>• Foundations of Offshore-Constructions</li> <li>• cCliff erosion</li> <li>• Sea dikes</li> <li>• Port structures</li> <li>• Flood protection structures</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• EAK (2002): Empfehlungen für Küstenschutzbauwerke</li> <li>• EAU (2004): Empfehlungen des Arbeitsausschusses Uferbauwerke</li> <li>• Poulos H.G. (1988): Marine Geotechnics. Unwin Hyman, London</li> <li>• Wagner P. (1990): Meerestechnik: Eine Einführung für Bauingenieure. Ernst &amp; Sohn, Berlin</li> </ul>

Course L0549: Marine Geotechnics	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Jürgen Grabe
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

<b>Course L0375: Numerical Methods in Geotechnics</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Dr. Hans Mathäus Stanford
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Topics: <ul style="list-style-type: none"> <li>• numerical simulations</li> <li>• numerical algorithms</li> <li>• finite element method</li> <li>• application of finite element method in geomechanics</li> <li>• constitutive models for soils</li> <li>• contact models for soil structure interaction</li> <li>• selected applications</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Wriggers P. (2001): Nichtlineare Finite-Elemente-Methoden, Springer Verlag, Berlin</li> <li>• Bathe Klaus-Jürgen (2002): Finite-Elemente-Methoden. Springer Verlag, Berlin</li> </ul>

Module M0860: Harbour Engineering and Harbour Planning			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Harbour Engineering (L0809)	Lecture	2	2
Harbour Engineering (L1414)	Project-/problem-based Learning	1	2
Port Planning and Port Construction (L0378)	Lecture	2	2
<b>Module Responsible</b>	Prof. Peter Fröhle		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basics of coastal engineering		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	The students are able to define in details and to choose design approaches for the functional design of a port and apply them to design tasks. They can design the fundamental elements of a port.		
<i>Knowledge</i>			
<i>Skills</i>	The students are able to select and apply appropriate approaches for the functional design of ports.		
<b>Personal Competence</b>	The students are able to deploy their gained knowledge in applied problems such as the functional design of ports. Additionally, they will be able to work in team with engineers of other disciplines.		
<i>Social Competence</i>			
<i>Autonomy</i>	The students will be able to independently extend their knowledge and apply it to new problems.		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	The duration of the examination is 150 min. The examination includes tasks with respect to the general understanding of the lecture contents and calculations tasks.		
<b>Assignment for the Following Curricula</b>	Civil Engineering: Specialisation Structural Engineering: Elective Compulsory Civil Engineering: Specialisation Geotechnical Engineering: Elective Compulsory Civil Engineering: Specialisation Coastal Engineering: Compulsory International Management and Engineering: Specialisation II. Civil Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0809: Harbour Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Peter Fröhle
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Fundamentals of harbor engineering               <ul style="list-style-type: none"> <li>◦ Maritime transportation and waterways engineering</li> <li>◦ Ships</li> </ul> </li> <li>• Elements of harbors               <ul style="list-style-type: none"> <li>◦ Harbor approaches and water-side harbor areas</li> <li>◦ Terminal design and handling of cargo</li> <li>◦ Quay-walls and piers</li> <li>◦ Equipment of harbors</li> <li>◦ Sluices and other special constructions</li> </ul> </li> <li>• Connection to inland transportation / inland waterway transportation</li> <li>• Protection of harbors               <ul style="list-style-type: none"> <li>◦ Breakwaters and Jetties</li> <li>◦ Wave protection of harbors</li> </ul> </li> <li>• Fishery and other small harbors</li> </ul>
<b>Literature</b>	Brinkmann, B.: Seehäfen, Springer 2005

Course L1414: Harbour Engineering	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Peter Fröhle
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course



Course L0378: Port Planning and Port Construction	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Frank Feindt
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Planning and implementation of major projects</li> <li>• Market analysis and traffic relations</li> <li>• Planning process and plan</li> <li>• Port planning in urban neighborhood</li> <li>• Development of the logistics center "Port of Hamburg" in the metropolis</li> <li>• Quays and waterfront structure</li> <li>• Special planning Law Harbor - securing of a flexible use of the port</li> <li>• Dimensioning of quays</li> <li>• Flood protection structures</li> <li>• Port of Hamburg - Infrastructure and development</li> <li>• Preparation of areas</li> <li>• Scour formation in front of shore structures</li> </ul>
<b>Literature</b>	Vorlesungsumdruck, s. <a href="http://www.tu-harburg.de/gbt">www.tu-harburg.de/gbt</a>

Module M1021: Marine Diesel Engine Plants			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Marine Diesel Engine Plants (L0637)	Lecture	3	4
Marine Diesel Engine Plants (L0638)	Recitation Section (large)	1	2
<b>Module Responsible</b>	Prof. Christopher Friedrich Wirz		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	Students can <ul style="list-style-type: none"> <li>• explain different types four / two-stroke engines and assign types to given engines,</li> <li>• name definitions and characteristics, as well as</li> <li>• elaborate on special features of the heavy oil operation, lubrication and cooling.</li> </ul>		
<i>Skills</i>	Students can <ul style="list-style-type: none"> <li>• evaluate the interaction of ship, engine and propeller,</li> <li>• use relationships between gas exchange, flushing, air demand, charge injection and combustion for the design of systems,</li> <li>• design waste heat recovery, starting systems, controls, automation, foundation and design machinery spaces , and</li> <li>• apply evaluation methods for excited motor noise and vibration.</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	The students are able to communicate and cooperate in a professional environment in the shipbuilding and component supply industry.		
<i>Autonomy</i>	The widespread scope of gained knowledge enables the students to handle situations in their future profession independently and confidently.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	20 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Energy Systems: Elective Compulsory Energy Systems: Specialisation Marine Engineering: Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0637: Marine Diesel Engine Plants	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Historischer Überblick</li> <li>• Bauarten von Vier- und Zweitaktmotoren als Schiffsmotoren</li> <li>• Vergleichsprozesse, Definitionen, Kenndaten</li> <li>• Zusammenwirken von Schiff, Motor und Propeller</li> <li>• Ausgeführte Schiffsdieselmotoren</li> <li>• Gaswechsel, Spülverfahren, Luftbedarf</li> <li>• Aufladung von Schiffsdieselmotoren</li> <li>• Einspritzung und Verbrennung</li> <li>• Schwerölbetrieb</li> <li>• Schmierung</li> <li>• Kühlung</li> <li>• Wärmebilanz</li> <li>• Abwärmennutzung</li> <li>• Anlassen und Umsteuern</li> <li>• Regelung, Automatisierung, Überwachung</li> <li>• Motorerregte Geräusche und Schwingungen</li> <li>• Fundamentierung</li> <li>• Gestaltung von Maschinenräumen</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• D. Woodyard: Pounder's Marine Diesel Engines</li> <li>• H. Meyer-Peter, F. Bernhardt: Handbuch der Schiffsbetriebstechnik</li> <li>• K. Kuiken: Diesel Engines</li> <li>• Mollenhauer, Tschöke: Handbuch Dieselmotoren</li> <li>• Projektierungsunterlagen der Motorenhersteller</li> </ul>

Course L0638: Marine Diesel Engine Plants	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Christopher Friedrich Wirz
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1132: Maritime Transport			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Maritime Transport (L0063)	Lecture	2	3
Maritime Transport (L0064)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Carlos Jahn		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>name different players involved in the maritime transport chain and their typical tasks;</li> <li>name common types of cargo and classify cargo to the corresponding categories;</li> <li>name and explain operation modes of maritime shipping, transportation options and management of maritime networks;</li> <li>illustrate main trade routes, straits (existing and possible in the future);</li> <li>name and discuss relevant factors for port / seaport terminal location planning.</li> </ul>		
<i>Knowledge</i>			
<b>Skills</b>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>define transportation modes, players involved and their functions in a maritime transportation network;</li> <li>identify possible cost drivers in a maritime transport chain and suggest possible reduction measures;</li> <li>identify, analyse, model and suggest optimisation measures regarding material and information flows within a maritime logistics chain.</li> </ul>		
<i>Skills</i>			
<b>Personal Competence</b>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>discuss and organise extensive work packages in groups;</li> <li>document and present the elaborated results.</li> </ul>		
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 minutes		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Logistics: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Production and Logistics: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Infrastructure and Mobility: Elective Compulsory Renewable Energies: Specialisation Wind Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0063: Maritime Transport	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Carlos Jahn
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	The lecture aims to provide detailed knowledge about maritime transportation and to describe its main challenges and functions. In this context, conventional and current problems are dealt with. All actors of a maritime transport chain are considered during the lecture. In this context, ports, vessels and sea routes are analysed and discussed in details. Conventional problems, planning tasks and current subjects, e. g. Green Logistics, are also part of the lecture.
<b>Literature</b>	<ul style="list-style-type: none"> <li>Brinkmann, Birgitt. Seehäfen: Planung und Entwurf. Berlin Heidelberg: Springer-Verlag, 2005.</li> <li>Schönknecht, Axel. Maritime Containerlogistik: Leistungsvergleich von Containerschiffen in intermodalen Transportketten. Berlin Heidelberg: Springer-Verlag, 2009.</li> <li>Stopford, Martin. Maritime Economics Routledge, 2009</li> </ul>

<b>Course L0064: Maritime Transport</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Carlos Jahn
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	The exercise lesson bases on the haptic management game MARITIME. MARITIME focuses on providing knowledge about structures and processes in a maritime transport network. Furthermore, the management game systematically provides process management methodology and also promotes personal skills of the participants.
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Brinkmann, Birgitt. Seehäfen: Planung und Entwurf. Berlin Heidelberg: Springer-Verlag, 2005.</li> </ul>

Module M1133: Port Logistics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Port Logistics (L0686)	Lecture                                      2                                      3
Port Logistics (L1473)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Carlos Jahn
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	none
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>describe the historical port development (regarding port functions, port terminals and the corresponding operating models) and consider these facts in the historical context;</li> <li>explain different types of seaport terminals and their typical characteristics (type of cargo, handling and transportation equipment, functional areas);</li> <li>name typical planning and scheduling tasks (e. g. berth planning, stowage planning, yard planning) as well as corresponding approaches (methods and tools) for performing these tasks in seaport terminals;</li> <li>name and discuss trends regarding planning and scheduling in innovative seaport terminals.</li> </ul>
<i>Skills</i>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>recognise functional areas within seaports and within seaport terminals;</li> <li>define and assess possible operation systems for a container terminal;</li> <li>conduct static calculations of container terminals regarding capacity requirements based on given conditions;</li> <li>reliably estimate how certain conditions effect typical logistics metrics in the context of the static planning process of selected seaport terminals.</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<p>The students are able to...</p> <ul style="list-style-type: none"> <li>discuss and organise extensive work packages in groups;</li> <li>document and present the elaborated results.</li> </ul>
<i>Autonomy</i>	<p>The students are able to</p> <ul style="list-style-type: none"> <li>research and select technical literature as well as norms and guidelines</li> <li>to hand in on time and to present an own share of a considerable written scientific work which was compiled in a small team together with other students</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 minutes
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Logistics: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Production and Logistics: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Infrastructure and Mobility: Elective Compulsory Renewable Energies: Specialisation Wind Energy Systems: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0686: Port Logistics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Carlos Jahn
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	The outstanding role of maritime transport for international trade requires efficient ports. These must meet numerous requirements in terms of profitability, speed, safety and environment. Recognising this, port logistics contains the planning, management, operation and control of material flows and the corresponding information flows in the system and its interfaces to several actors within and outside the port area. The course "Port Logistics" aims to provide skills to comprehend structures and processes in ports. It focuses on different terminal types, their characteristic layouts, the technical equipment which is used and the interaction between the actors.
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Brinkmann, Birgitt. Seehäfen: Planung und Entwurf. Berlin Heidelberg: Springer-Verlag, 2005.</li> </ul>

Course L1473: Port Logistics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Carlos Jahn
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	The exercise lesson focuses on analytical tasks in the field of terminal planning. During the exercise lesson, the students work in small groups on designing terminal layouts under consideration of given conditions. The calculated logistics metrics, respectively the corresponding terminal layouts must be illustrated in 2D and 3D using special planning software.
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Brinkmann, Birgitt. Seehäfen: Planung und Entwurf. Berlin Heidelberg: Springer-Verlag, 2005.</li> </ul>

Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	see FSPO		
<i>Skills</i>	see FSPO		
<b>Personal Competence</b>			
<i>Social Competence</i>	see FSPO		
<i>Autonomy</i>	see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		



Module M1146: Ship Vibration			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Ship Vibration (L1528)	Lecture	2	3
Ship Vibration (L1529)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Dr. Rüdiger Ulrich Franz von Bock und Polach		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Mechanis I - III Structural Analysis of Ships I Fundamentals of Ship Structural Design		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students can reproduce the acceptance criteria for vibrations on ships; they can explain the methods for the calculation of natural frequencies and forced vibrations of structural components and the entire hull girder; they understand the effect of exciting forces of the propeller and main engine and methods for their determination</p> <p><i>Skills</i> Students are capable to apply methods for the calculation of natural frequencies and exciting forces and resulting vibrations of ship structures including their assessment; they can model structures for the vibration analysis</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> The students are able to communicate and cooperate in a professional environment in the shipbuilding and component supply industry.</p> <p><i>Autonomy</i> Students are able to detect vibration-prone components on ships, to model the structure, to select suitable calculation methods and to assess the results</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	3 hours		
<b>Assignment for the Following Curricula</b>	Energy Systems: Specialisation Marine Engineering: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Compulsory Ship and Offshore Technology: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1528: Ship Vibration	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Rüdiger Ulrich Franz von Bock und Polach
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Introduction; assessment of vibrations</li> <li>2. Basic equations</li> <li>3. Beams with discrete / distributed masses</li> <li>4. Complex beam systems</li> <li>5. Vibration of plates and Grillages</li> <li>6. Deformation method / practical hints / measurements</li> <li>7. Hydrodynamic masses</li> <li>8. Spectral method</li> <li>9. Hydrodynamic masses acc. to Lewis</li> <li>10. Damping</li> <li>11. Shaft systems</li> <li>12. Propeller excitation</li> <li>13. Engines</li> </ol>
<b>Literature</b>	Siehe Vorlesungsskript

Course L1529: Ship Vibration	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Rüdiger Ulrich Franz von Bock und Polach
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	1. Introduction; assessment of vibrations 2. Basic equations 3. Beams with discrete / distributed masses 4. Complex beam systems 5. Vibration of plates and Grillages 6. Deformation method / practical hints / measurements 7. Hydrodynamic masses 8. Spectral method 9. Hydrodynamic masses acc. to Lewis 10. Damping 11. Shaft systems 12. Propeller excitation 13. Engines
<b>Literature</b>	Siehe Vorlesungsskript

Module M1268: Linear and Nonlinear Waves			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	<b>Hrs/wk</b> <b>CP</b>
Linear and Nonlinear Waves (L1737)		Project-/problem-based Learning	4            6
<b>Module Responsible</b>	Prof. Norbert Hoffmann		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Good Knowledge in Mathematics, Mechanics and Dynamics.		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	Students are able to reflect existing terms and concepts in Wave Mechanics and to develop and research new terms and concepts.		
<i>Skills</i>	Students are able to apply existing methods and procedures of Wave Mechanics and to develop novel methods and procedures.		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students can reach working results also in groups.		
<i>Autonomy</i>	Students are able to approach given research tasks individually and to identify and follow up novel research tasks by themselves.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	2 Hours		
<b>Assignment for the Following Curricula</b>	Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1737: Linear and Nonlinear Waves	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Norbert Hoffmann
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	Introduction into the Dynamics of Linear and Nonlinear Waves.
<b>Literature</b>	G.B. Witham, Linear and Nonlinear Waves. Wiley 1999. C.C. Mei, Theory and Applications of Ocean Surface Waves. World Scientific 2004.

Module M1148: Selected topics in Naval Architecture and Ocean Engineering	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Outfitting and Operation of Special Purpose Offshore Ships (L1896)	Lecture                      2                      3
Design of Underwater Vessels (L0670)	Lecture                      2                      3
Lattice-Boltzmann methods for the simulation of free surface flows (L2066)	Lecture                      2                      3
Modeling and Simulation of Maritime Systems (L2013)	Project-/problem-based Learning                      2                      3
Offshore Wind Parks (L0072)	Lecture                      2                      3
Ship Acoustics (L1605)	Lecture                      2                      3
Ship Dynamics (L0352)	Lecture                      2                      3
Selected Topics of Experimental and Theoretical Fluidynamics (L0240)	Lecture                      2                      3
Technical Elements and Fluid Mechanics of Sailing Ships (L0873)	Lecture                      2                      3
Technology of Naval Surface Vessels (L0765)	Lecture                      2                      3
<b>Module Responsible</b>	Prof. Sören Ehlers
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	none
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students are able to find their way through selected special areas within naval architecture and ocean engineering</li> <li>• Students are able to explain basic models and procedures in selected special areas.</li> <li>• Students are able to interrelate scientific and technical knowledge.</li> </ul>
<i>Skills</i>	Students are able to apply basic methods in selected areas of ship and ocean engineering.
<b>Personal Competence</b>	
<i>Social Competence</i>	The students are able to communicate and cooperate in a professional environment in the shipbuilding and component supply industry.
<i>Autonomy</i>	Students can chose independently, in which fields they want to deepen their knowledge and skills through the election of courses.
<b>Workload in Hours</b>	Depends on choice of courses
<b>Credit points</b>	6
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L1896: Outfitting and Operation of Special Purpose Offshore Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Prof. Sören Ehlers, Dr. Hendrik Vorhölter
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The lecture is separated into two parts. In the first part some basic skills necessary for the design of offshore vessels and their equipment will be repeated and where necessary deepened. In particular, the specialties which are common for the majority of offshore vessels will be addressed: rules and regulations, determination of operational limits as well as mooring and dynamic positioning.</p> <p>In the second part of the lecture single types of special offshore vessels and their equipment and outfitting will be addressed. For each type the specific requirements on design and operation will be discussed. Furthermore, the students shall be engaged with the preparation of short presentation about the specific ship types as incentive for the respective unit. In particular, it is planned to discuss the following ship types in the lecture:</p> <ul style="list-style-type: none"> <li>- Anchor handling and platform supply vessels</li> <li>- Cable -and pile lay vessels</li> <li>- Jack-up vessels</li> <li>- Heavy lift and offshore construction vessels</li> <li>- Dredgers and rock dumping vessels</li> <li>- Diving support vessels</li> </ul>
<b>Literature</b>	<p>Chakrabarti, S. (2005): Handbook of Offshore Engineering. Elsevier. Amsterdam, London</p> <p>Volker Patzold (2008): Der Nassabbau. Springer. Berlin</p> <p>Milwee, W. (1996): Modern Marine Salvage. Md Cornell Maritime Press. Centerville.</p> <p>DNVGL-ST-N001 „Marine Operations and Marin Warranty“</p> <p>IMCA M 103 "The Design and Operation of Dynamically Positioned Vessels" 2007-12</p> <p>IMCA M 182 "The Safe Operation of Dynamically Positioned Offshore Supply Vessels" 2006-03</p> <p>IMCA M 187 "Lifting Operations" 2007-10</p> <p>IMCA SEL 185 "Transfer of Personnel to and from Offshore Vessels" 2010-03</p>

Course L0670: Design of Underwater Vessels	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Peter Hauschildt
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>The lectures will give an overview about the design of underwater vessels. The Topics are:</p> <ol style="list-style-type: none"> <li>1.) Special requirements on the design of modern, conventional submarines</li> <li>2.) Design history</li> <li>3.) Generals description of submarines</li> <li>4.) Civil submersibles</li> <li>5.) Diving, trim, stability</li> <li>6.) Rudders and Propulsion systems</li> <li>7.) Air Independent propulsion</li> <li>8.) Signatures</li> <li>9.) Hydrodynamics and CFD</li> <li>10.) Weapon- and combatmangementsystems</li> <li>11.) Safety and rescue</li> <li>12.) Fatigue and shock</li> <li>13.) Ships technical systems</li> <li>14.) Electricals Systems and automation</li> <li>15.) Logisics</li> <li>16.) Accomodation</li> </ol> <p>Some of the lectures will be Hheld in form of a excursion to ThyssenKrupp Marine Systems in Kiel</p>
<b>Literature</b>	Gabler, Ubootsbau

Course L2066: Lattice-Boltzmann methods for the simulation of free surface flows	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Christian F. Janßen
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>This lecture addresses Lattice Boltzmann Methods for the simulation of free surface flows. After an introduction to the basic concepts of kinetic methods (LGCAs, LBM, ....), recent LBM extensions for the simulation of free-surface flows are discussed. Parallel to the lecture, selected maritime free-surface flow problems are to be solved numerically.</p>
<b>Literature</b>	<p>Krüger et al., "The Lattice Boltzmann Method - Principles and Practice", Springer</p> <p>Zhou, "Lattice Boltzmann Methods for Shallow Water Flows", Springer</p> <p>Janßen, "Kinetic approaches for the simulation of non-linear free surface flow problems in civil and environmental engineering", PhD thesis, TU Braunschweig, 2010.</p>

Course L2013: Modeling and Simulation of Maritime Systems	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Christian F. Janßen
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<p>In the scope of this lecture, students learn to model and solve selected maritime problems with the help of numerical programs and scripts.</p> <p>First, basic concepts of computational modeling are explained, from the physical modeling and discretization to the implementation and actual numerical solution of the problem. Then, available tools for the implementation and solution process are discussed, including high-level compiled and interpreted programming languages and computer algebra systems (e.g., Python; Matlab, Maple). In the second half of the class, selected maritime problems will be discussed and subsequently solved numerically by the students.</p>
<b>Literature</b>	<p>"Introduction to Computational Modeling Using C and Open-Source Tools" (J.M. Garrido, Chapman and Hall); "Introduction to Computational Models with Python" (J.M. Garrido, Chapman and Hall); "Programming Fundamentals" (MATLAB Handbook, MathWorks);</p>

Course L0072: Offshore Wind Parks	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	45 min
<b>Lecturer</b>	Dr. Alexander Mitzlaff
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Nonlinear Waves: Stability, pattern formation, solitary states</li> <li>• Bottom Boundary layers: wave boundary layers, scour, stability of marine slopes</li> <li>• Ice-structure interaction</li> <li>• Wave and tidal current energy conversion</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Chakrabarti, S., Handbook of Offshore Engineering, vol. I&amp;II, Elsevier 2005.</li> <li>• Mc Cormick, M.E., Ocean Wave Energy Conversion, Dover 2007.</li> <li>• Infeld, E., Rowlands, G., Nonlinear Waves, Solitons and Chaos, Cambridge 2000.</li> <li>• Johnson, R.S., A Modern Introduction to the Mathematical Theory of Water Waves, Cambridge 1997.</li> <li>• Lykousis, V. et al., Submarine Mass Movements and Their Consequences, Springer 2007.</li> <li>• Nielsen, P., Coastal Bottom Boundary Layers and Sediment Transport, World Scientific 2005.</li> <li>• Research Articles.</li> </ul>

Course L1605: Ship Acoustics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Dietrich Wittekind
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	
<b>Literature</b>	

Course L0352: Ship Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Klausur
<b>Examination duration and scale</b>	60 min
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Maneuverability of ships</p> <ul style="list-style-type: none"> <li>• Equations of motion</li> <li>• Hydrodynamic forces and moments</li> <li>• Linear equations and their solutions</li> <li>• Full-scale trials for evaluating the maneuvering performance</li> <li>• Regulations for maneuverability</li> <li>• Rudder</li> </ul> <p>Seakeeping</p> <ul style="list-style-type: none"> <li>• Representation of harmonic processes</li> <li>• Motions of a rigid ship in regular waves</li> <li>• Flow forces on ship cross sections</li> <li>• Strip method</li> <li>• Consequences induced by ship motion in regular waves</li> <li>• Behavior of ships in a stationary sea state</li> <li>• Long-term distribution of seaway influences</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Abdel-Maksoud, M., Schiffsdynamik, Vorlesungsskript, Institut für Fluidodynamik und Schiffstheorie, Technische Universität Hamburg-Harburg, 2014</li> <li>• Abdel-Maksoud, M., Ship Dynamics, Lecture notes, Institute for Fluid Dynamic and Ship Theory, Hamburg University of Technology, 2014</li> <li>• Bertram, V., Practical Ship Design Hydrodynamics, Butterworth-Heinemann, Linacre House - Jordan Hill, Oxford, United Kingdom, 2000</li> <li>• Bhattacharyya, R., Dynamics of Marine Vehicles, John Wiley &amp; Sons, Canada, 1978</li> <li>• Brix, J. (ed.), Manoeuvring Technical Manual, Seehafen-Verlag, Hamburg, 1993</li> <li>• Claus, G., Lehmann, E., Østergaard, C). Offshore Structures, I+II, Springer-Verlag, Berlin Heidelberg, Deutschland, 1992</li> <li>• Faltinsen, O. M., Sea Loads on Ships and Offshore Structures, Cambridge University Press, United Kingdom, 1990</li> <li>• Handbuch der Werften, Deutschland, 1986</li> <li>• Jensen, J. J., Load and Global Response of Ships, Elsevier Science, Oxford, United Kingdom, 2001</li> <li>• Lewis, Edward V. (ed.), Principles of Naval Architecture - Motion in Waves and Controllability, Society of Naval Architects and Marine Engineers, Jersey City, NJ, 1989</li> <li>• Lewandowski, E. M., The Dynamics of Marine Craft: Maneuvering and Seakeeping, World Scientific, USA, 2004</li> <li>• Lloyd, A., Ship Behaviour in Rough Weather, Gosport, Chichester, Sussex, United Kingdom, 1998</li> </ul>

Course L0240: Selected Topics of Experimental and Theoretical Fluid Dynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Will be announced at the beginning of the lecture. Exemplary topics are</p> <ol style="list-style-type: none"> <li>1. methods and procedures from experimental fluid mechanics</li> <li>2. rational Approaches towards flow physics modelling</li> <li>3. selected topics of theoretical computation fluid dynamics</li> <li>4. turbulent flows</li> </ol>
<b>Literature</b>	Wird in der Veranstaltung bekannt gegeben. To be announced during the lecture.



Course L0873: Technical Elements and Fluid Mechanics of Sailing Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Prof. Thomas Rung, Dipl.-Ing. Peter Schenzle
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Principles of Sailing Mechanics:</p> <ul style="list-style-type: none"> <li>- Sailing: Propulsion from relative motion</li> <li>- Lifting foils: Sails, wings, rudders, fins, keels</li> <li>- Wind climate: global, seasonal, meteorological, local</li> <li>- Aerodynamics of sails and sailing rigs</li> <li>- Hydrodynamics of Hulls and fins</li> </ul> <p>Technical Elements of Sailing:</p> <ul style="list-style-type: none"> <li>- Traditional and modern sail types</li> <li>- Modern and unconventional wind propulsors</li> <li>- Hull forms and keel-rudder-configurations</li> <li>- Sailing performance Prediction (VPP)</li> <li>- Auxiliary wind propulsion (motor-sailing)</li> </ul> <p>Configuration of Sailing Ships:</p> <ul style="list-style-type: none"> <li>- Balancing hull and sailing rig</li> <li>- Sailing-boats and -yachts</li> <li>- Traditional Tall Sailing Ships</li> <li>- Modern Wind-Ships</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Vorlesungs-Manuskript mit Literatur-Liste: Verteilt zur Vorlesung</li> <li>- B. Wagner: Fahrtgeschwindigkeitsberechnung für Segelschiffe, IfS-Rep. 132, 1967</li> <li>- B. Wagner: Sailing Ship Research at the Hamburg University, IfS-Script 2249, 1976</li> <li>- A.R. Cloughton et al.: Sailing Yacht Design 1&amp;2, University of Southampton, 1998</li> <li>- L. Larsson, R.E. Eliasson: Principles of Yacht Design, Adlard Coles Nautical, London, 2000</li> <li>- K. Hochkirch: Entwicklung einer Messyacht, Diss. TU Berlin, 2000</li> </ul>

Course L0765: Technology of Naval Surface Vessels	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Examination Form</b>	Mündliche Prüfung
<b>Examination duration and scale</b>	30 min
<b>Lecturer</b>	Dr. Martin SchötteIndreyer
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Operational scenarios, tasks, capabilities, requirements</li> <li>• Product and process models, rules and regulations</li> <li>• Survivability: threats, signatures, counter measures</li> <li>• Design characteristics</li> <li>• Energy and propulsion systems</li> <li>• Command and combat systems</li> <li>• Vulnerability: residual strength, residual functionality</li> </ul>
<b>Literature</b>	<p>Th. Christensen, H.-D. Ehrenberg, H. Götte, J. Wessel: Entwurf von Fregatten und Korvetten, in: H. Keil (Hrsg.), Handbuch der Werften, Bd. XXV, Schifffahrts-Verlag "Hansa" C. Schroedter &amp; Co., Hamburg (2000)</p> <p>16th International Ship and Offshore Structures Congress: Committee V.5 - Naval Ship Design (2006)</p> <p>P. G. Gates: Surface Warships - An Introduction to Design Principles, Brassey's Defence Publishers, London (1987)</p>

Module M1232: Arctic Technology			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Ice Engineering (L1607)	Lecture	2	2
Ice Engineering (L1615)	Recitation Section (small)	1	2
Ship structural design for arctic conditions (L1575)	Project-/problem-based Learning	2	2
<b>Module Responsible</b>	Prof. Sören Ehlers		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	none		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	The challenges and requirements due to ice can be explained. Ice loads can be explained and ice strengthening can be understood.		
<i>Skills</i>	The challenges and requirements due to ice can be assessed and the accuracy of these assessment can be evaluated. Calculation models to assess ice loads can be used and a structure can be designed accordingly.		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students are capable to present their structural design and discuss their decisions constructively in a group.		
<i>Autonomy</i>	Independent and individual assignment tasks can be carried out and presented whereby the capabilities to both, present and defend, the skills and findings will be achieved.		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Ship and Offshore Technology: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory		

Course L1607: Ice Engineering	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Walter Kuehnlein
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Ice, Ice Properties, Ice Failure Modes and Challenges and Requirements due to Ice               <ul style="list-style-type: none"> <li>◦ Introduction, what is/means ice engineering</li> <li>◦ Description of different kinds of ice, main ice properties and different ice failure modes</li> <li>◦ Why is ice so different compared to open water</li> <li>◦ Presentation of design challenges and requirements for structures and systems in ice covered waters</li> </ul> </li> <li>2. Ice Load Determination and Ice Model Testing               <ul style="list-style-type: none"> <li>◦ Overview of different empirical equations for simple determination of ice loads</li> <li>◦ Discussion and interpretation of the different equations and results</li> <li>◦ Introduction to ice model tests</li> <li>◦ What are the requirements for ice model tests, what parameters have to be scaled</li> <li>◦ What can be simulated and how to use the results of such ice model tests</li> </ul> </li> <li>3. Computational Modelling of Ice-Structure Interaction Processes               <ul style="list-style-type: none"> <li>◦ Dynamic fracture and continuum mechanics for modelling ice-structure interaction processes</li> <li>◦ Alternative numerical crack propagation modelling methods. Examples of cohesive element models for real life structures.</li> <li>◦ Discussion of contribution of ice properties, hydrodynamics and rubble.</li> </ul> </li> <li>4. Ice Design Philosophies and Perspectives               <ul style="list-style-type: none"> <li>◦ What has to be considered when designing structures or systems for ice covered waters</li> <li>◦ What are the main differences compared to open water design</li> <li>◦ Ice Management</li> <li>◦ What are the main ice design philosophies and why is an integrated concept so important for ice</li> </ul> </li> </ol> <p><b>Learning Objectives</b></p> <p>The course will provide an introduction into ice engineering. Different kinds of ice and their different failure modes including numerical methods for ice load simulations are presented. Main design issues including design philosophies for structures and systems for ice covered waters are introduced. The course shall enable the attendees to understand the fundamental challenges due to ice covered waters and help them to understand ice engineering reports and presentations.</p>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Proceedings OMAE</li> <li>• Proceedings POAC</li> <li>• Proceedings ATC</li> </ul>

Course L1615: Ice Engineering	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Walter Kuehnlein
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1575: Ship structural design for arctic conditions	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sören Ehlers
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	The structural design under ice loads will be carried out for an individual case
<b>Literature</b>	FSICR, IACS PC and assorted publications

Module M1178: Manoeuvrability and Shallow Water Ship Hydrodynamics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Manoeuvrability of Ships (L1597)	Lecture	2	3
Shallow Water Ship Hydrodynamics (L1598)	Lecture	2	3
<b>Module Responsible</b>	Prof. Moustafa Abdel-Maksoud		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	B.Sc. Schiffbau		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>The students learn the motion equation and how to describe hydrodynamic forces. They'll be able to develop methods for analysis of manoeuvring behaviour of ships and explaining the Nomoto equation. The students will know the common model tests as well as their assets and drawbacks.</p> <p>Furthermore, the students learn the basics of assessment and prognosis of ship manoeuvrability. Basics of characteristics of flows around ships in shallow water regarding ship propulsion and manoeuvrability will be acquired.</p>		
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	180 min		
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Ship and Offshore Technology: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory		

Course L1597: Manoeuvrability of Ships	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• coordinates &amp; degrees of freedom</li> <li>• governing equations of motion</li> <li>• hydrodynamic forces &amp; moments</li> <li>• ruder forces</li> <li>• navigation based on linearised eq. of motion (exemplary solutions, yaw stability)</li> <li>• manoeuvring test (constraint &amp; unconstrained motion)</li> <li>• slender body approximation</li> </ul> <p><b>Learning Outcomes</b></p> <p>Introduction into basic concepts for the assessment and prognosis of ship manoeuvrability.</p> <p>Ability to develop methods for analysis of manoeuvring behaviour of ships.</p>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Crane, C. L. H., Eda, A. L., Principles of Naval Architecture, Chapter 9, Controllability, SNAME, New York, 1989</li> <li>• Brix, J., Manoeuvring Technical Manual, Seehafen Verlag GmbH, Hamburg 1993</li> <li>• Söding, H., Manövrieren, Vorlesungsmansript, Institut für Fluidodynamik und Schiffstheorie, TUHH, Hamburg, 1995</li> </ul>

Course L1598: Shallow Water Ship Hydrodynamics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Moustafa Abdel-Maksoud, Dr. Norbert Stuntz
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Special Aspects of Shallow Water Hydrodynamics, Vertical and Horizontal Constraints, Irregularities in Channel Bed</li> <li>• Fundamental Equations of Shallow Water Hydrodynamics</li> <li>• Approximation of Shallow Water Waves, Boussinesq's Approximation</li> <li>• Ship Waves in Deep Water and under critical, non-critical and supercritical Velocities</li> <li>• Solitary Waves, Critical Speed Range, Extinction of Waves</li> <li>• Aspects of Ship motions in Canals with limited water depth</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• PNA (1988): Principle of Naval Architecture, Vol. II, ISBN 0-939773-01-5</li> <li>• Schneekluth (1988): Hydromechanik zum Schiffsentwurf</li> <li>• Jiang, T. (2001): Ship Waves in Shallow Water, Fortschritt-Berichte VDI, Series 12, No 466, ISBN 3-18-346612-0</li> </ul>

Module M1165: Ship Safety	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Ship Safety (L1267)	Lecture
Ship Safety (L1268)	Recitation Section (large)
<b>Hrs/wk</b>	<b>CP</b>
2	4
2	2
<b>Module Responsible</b>	Prof. Stefan Krüger
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Ship Design, Hydrostatics, Statistical Processes
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The student shall learn to integrate safety aspects into the ship design process. This includes the understanding and application of existing rules as well as the understanding of the safety concept and level which is targeted by a rule. Further, methods of demonstrating equivalent safety levels are introduced.
<i>Skills</i>	<p>The lectures start with an overview about general safety concepts for technical systems. The maritime safety organizations are introduced, their responses and duties. Then, the general difference between prescriptive and performance based rules is tackled. For different examples in ship design, the influence of the rules on the design is illustrated. Further, limitations of safety rules with respect to the physical background are shown. Concepts of demonstrating equivalent levels of safety by direct calculations are discussed. The following fields will be treated.</p> <ul style="list-style-type: none"> <li>- Freeboard, water- and weathertight subdivisions, openings</li> <li>- all aspects of intact stability, including special problems such as grain code</li> <li>- damage stability for passenger vessels including Stockholm agreement</li> <li>- damage stability for cargo vessels</li> <li>- on board stability, inclining experiment and stability booklet</li> <li>- Relevant manoeuvring information</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	The student learns to take responsibility for the safety of his design.
<i>Autonomy</i>	Responsible certification of technical designs.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	180 min
<b>Assignment for the Following Curricula</b>	Naval Architecture and Ocean Engineering: Core qualification: Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory

Course L1267: Ship Safety	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Stefan Krüger
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The lectures start with an overview about general safety concepts for technical systems. The maritime safety organizations are introduced, their responses and duties. Then, the general difference between prescriptive and performance based rules is tackled. For different examples in ship design, the influence of the rules on the design is illustrated. Further, limitations of safety rules with respect to the physical background are shown. Concepts of demonstrating equivalent levels of safety by direct calculations are discussed. The following fields will be treated.</p> <ul style="list-style-type: none"> <li>- Freeboard, water- and weathertight subdivisions, openings</li> <li>- all aspects of intact stability, including special problems such as grain code</li> <li>- damage stability for passenger vessels including Stockholm agreement</li> <li>- damage stability for cargo vessels</li> <li>- on board stability, inclining experiment and stability booklet</li> <li>- Relevant manoeuvring information</li> </ul>
<b>Literature</b>	SOLAS, LOAD LINES, CODE ON INTACT STABILITY. Alle IMO, London.

Course L1268: Ship Safety	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Stefan Krüger
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

## Specialization Numerics and Computer Science

The focus of the specialization „numerics and computer science“ is on the acquisition of in-depth knowledge and skills in engineering-related fields of computer science and numerical analysis. This is made possible by modules in the elective area on the topics distributed or efficient algorithms or algorithms of structural mechanics, process automation technology, digital image analysis, pattern recognition and data compression, approximation and stability, machine learning and data mining, matrix algorithms, Numerical Analysis and Real-Time Systems. This cross-sectional technologies are now largely anchored in modern research and development process of mechanical engineering systems established. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M0633: Industrial Process Automation	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Industrial Process Automation (L0344)	Lecture                                      2                                      3
Industrial Process Automation (L0345)	Recitation Section (small)              2                                      3
<b>Module Responsible</b>	Prof. Alexander Schlaefer
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	mathematics and optimization methods principles of automata principles of algorithms and data structures programming skills
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The students can evaluate and assess discrete event systems. They can evaluate properties of processes and explain methods for process analysis. The students can compare methods for process modelling and select an appropriate method for actual problems. They can discuss scheduling methods in the context of actual problems and give a detailed explanation of advantages and disadvantages of different programming methods.
<i>Skills</i>	The students are able to develop and model processes and evaluate them accordingly. This involves taking into account optimal scheduling, understanding algorithmic complexity and implementation using PLCs.
<b>Personal Competence</b>	
<i>Social Competence</i>	The students work in teams to solve problems.
<i>Autonomy</i>	The students can reflect their knowledge and document the results of their work.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 minutes
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation General Process Engineering: Elective Compulsory Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Production Management: Specialisation Production Technology: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Chemical Process Engineering: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory



Course L0344: Industrial Process Automation	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- foundations of problem solving and system modeling, discrete event systems</li> <li>- properties of processes, modeling using automata and Petri-nets</li> <li>- design considerations for processes (mutex, deadlock avoidance, liveness)</li> <li>- optimal scheduling for processes</li> <li>- optimal decisions when planning manufacturing systems, decisions under uncertainty</li> <li>- software design and software architectures for automation, PLCs</li> </ul>
<b>Literature</b>	J. Lunze: „Automatisierungstechnik“, Oldenbourg Verlag, 2012 Reisig: Petrinetze: Modellierungstechnik, Analysemethoden, Fallstudien; Vieweg+Teubner 2010 Hruz, Zhou: Modeling and Control of Discrete-event Dynamic Systems; Springer 2007 Li, Zhou: Deadlock Resolution in Automated Manufacturing Systems, Springer 2009 Pinedo: Planning and Scheduling in Manufacturing and Services, Springer 2009

Course L0345: Industrial Process Automation	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Schlaefer
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1222: Design and Implementation of Software Systems			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Design and Implementation of Software Systems (L1657)	Lecture	2	3
Design and Implementation of Software Systems (L1658)	Practical Course	2	3
<b>Module Responsible</b>	Prof. Bernd-Christian Renner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	- Imperativ programming languages (C, Pascal, Fortran or similar) - Simple data types (integer, double, char, boolean), arrays, if-then-else, for, while, procedure and function calls		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> Students are able to describe mechatronic systems and define requirements. <i>Skills</i> Students are able to design and implement mechatronic systems. They are able to argue the combination of Hard- and Software and the interfaces.		
<b>Personal Competence</b>	<i>Social Competence</i> Students are able to work goal-oriented in small mixed groups, learning and broadening teamwork abilities and define task within the team. <i>Autonomy</i> Students are able to solve individually exercises related to this lecture with instructional direction. Students are able to plan, execute and summarize a mechatronic experiment.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Mechatronics: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory		

Course L1657: Design and Implementation of Software Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Bernd-Christian Renner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	This course covers software design and implementation of mechatronic systems, tools for automation in Java. Content: <ul style="list-style-type: none"> <li>• Introduction to software techniques</li> <li>• Procedural Programming</li> <li>• Object oriented software design</li> <li>• Java</li> <li>• Event based programming</li> <li>• Formal methods</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• "The Pragmatic Programmer: From Journeyman to Master" Andrew Hunt, David Thomas, Ward Cunningham</li> <li>• "Core LEGO MINDSTORMS Programming: Unleash the Power of the Java Platform" Brian Bagnall Prentice Hall PTR, 1st edition (March, 2002) ISBN 0130093645</li> <li>• "Objects First with Java: A Practical Introduction using BlueJ" David J. Barnes &amp; Michael Kölling Prentice Hall/ Pearson Education; 2003, ISBN 0-13-044929-6</li> </ul>

Course L1658: Design and Implementation of Software Systems	
<b>Typ</b>	Practical Course
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Bernd-Christian Renner
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0926: Distributed Algorithms			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Distributed Algorithms (L1071)	Lecture	2	3
Distributed Algorithms (L1072)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Volker Turau		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>Algorithms and data structures</li> <li>Distributed systems</li> <li>Discrete mathematics</li> <li>Graph theory</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students know the main abstractions of distributed algorithms (synchronous/asynchronous model, message passing and shared memory model). They are able to describe complexity measures for distributed algorithms (round , message and memory complexity). They explain well known distributed algorithms for important problems such as leader election, mutual exclusion, graph coloring, spanning trees. They know the fundamental techniques used for randomized algorithms.</p> <p><i>Skills</i> Students design their own distributed algorithms and analyze their complexity. They make use of known standard algorithms. They compute the complexity of randomized algorithms.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p><i>Autonomy</i></p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	45 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Computer and Software Engineering: Elective Compulsory Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Information and Communication Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory		

Course L1071: Distributed Algorithms	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Volker Turau
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>Leader Election</li> <li>Colorings &amp; Independent Sets</li> <li>Tree Algorithms</li> <li>Minimal Spanning Trees</li> <li>Randomized Distributed Algorithms</li> <li>Mutual Exclusion</li> </ul>
<b>Literature</b>	<ol style="list-style-type: none"> <li>David Peleg: Distributed Computing - A Locality-Sensitive Approach. SIAM Monograph, 2000</li> <li>Gerard Tel: Introduction to Distributed Algorithms, Cambridge University Press, 2nd edition, 2000</li> <li>Nancy Lynch: Distributed Algorithms. Morgan Kaufmann, 1996</li> <li>Volker Turau: Algorithmische Graphentheorie. Oldenbourg Wissenschaftsverlag, 3. Auflage, 2004.</li> </ol>

Course L1072: Distributed Algorithms	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Volker Turau
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0551: Pattern Recognition and Data Compression			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Pattern Recognition and Data Compression (L0128)	Lecture	4	6
<b>Module Responsible</b>	Prof. Rolf-Rainer Grigat		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Linear algebra (including PCA, unitary transforms), stochastics and statistics, binary arithmetics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students can name the basic concepts of pattern recognition and data compression.</p> <p>Students are able to discuss logical connections between the concepts covered in the course and to explain them by means of examples.</p> <p><i>Skills</i></p> <p>Students can apply statistical methods to classification problems in pattern recognition and to prediction in data compression. On a sound theoretical and methodical basis they can analyze characteristic value assignments and classifications and describe data compression and video signal coding. They are able to use highly sophisticated methods and processes of the subject area. Students are capable of assessing different solution approaches in multidimensional decision-making areas.</p> <p><i>Personal Competence</i></p> <p><i>Social Competence</i> k.A.</p> <p><i>Autonomy</i></p> <p>Students are capable of identifying problems independently and of solving them scientifically, using the methods they have learnt.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	60 Minutes, Content of Lecture and materials in StudIP		
<b>Assignment for the Following Curricula</b>	<p>Computer Science: Specialisation Intelligence Engineering: Elective Compulsory</p> <p>Electrical Engineering: Specialisation Information and Communication Systems: Elective Compulsory</p> <p>Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory</p> <p>Information and Communication Systems: Specialisation Secure and Dependable IT Systems, Focus Software and Signal Processing: Elective Compulsory</p> <p>Information and Communication Systems: Specialisation Communication Systems, Focus Signal Processing: Elective Compulsory</p> <p>International Management and Engineering: Specialisation II. Information Technology: Elective Compulsory</p> <p>International Management and Engineering: Specialisation II. Electrical Engineering: Elective Compulsory</p> <p>Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory</p> <p>Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory</p>		

Course L0128: Pattern Recognition and Data Compression	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Rolf-Rainer Grigat
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<p>Structure of a pattern recognition system, statistical decision theory, classification based on statistical models, polynomial regression, dimension reduction, multilayer perceptron regression, radial basis functions, support vector machines, unsupervised learning and clustering, algorithm-independent machine learning, mixture models and EM, adaptive basis function models and boosting, Markov random fields</p> <p>Information, entropy, redundancy, mutual information, Markov processes, basic coding schemes (code length, run length coding, prefix-free codes), entropy coding (Huffman, arithmetic coding), dictionary coding (LZ77/Deflate/LZMA2, LZ78/LZW), prediction, DPCM, CALIC, quantization (scalar and vector quantization), transform coding, prediction, decorrelation (DPCM, DCT, hybrid DCT, JPEG, JPEG-LS), motion estimation, subband coding, wavelets, HEVC (H.265, MPEG-H)</p>
<b>Literature</b>	<p>Schürmann: Pattern Classification, Wiley 1996  Murphy, Machine Learning, MIT Press, 2012  Barber, Bayesian Reasoning and Machine Learning, Cambridge, 2012  Duda, Hart, Stork: Pattern Classification, Wiley, 2001  Bishop: Pattern Recognition and Machine Learning, Springer 2006</p> <p>Salomon, Data Compression, the Complete Reference, Springer, 2000  Sayood, Introduction to Data Compression, Morgan Kaufmann, 2006  Ohm, Multimedia Communication Technology, Springer, 2004  Solari, Digital video and audio compression, McGraw-Hill, 1997  Tekalp, Digital Video Processing, Prentice Hall, 1995</p>

Module M0606: Numerical Algorithms in Structural Mechanics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Numerical Algorithms in Structural Mechanics (L0284)	Lecture                                      2                                      3
Numerical Algorithms in Structural Mechanics (L0285)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Alexander Düster
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Mathematics I, II, III, Mechanics I, II, III, IV Differential Equations 2 (Partial Differential Equations)
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to + give an overview of the standard algorithms that are used in finite element programs. + explain the structure and algorithm of finite element programs. + specify problems of numerical algorithms, to identify them in a given situation and to explain their mathematical and computer science background.
<i>Skills</i>	Students are able to + construct algorithms for given numerical methods. + select for a given problem of structural mechanics a suitable algorithm. + apply numerical algorithms to solve problems of structural mechanics. + implement algorithms in a high-level programming language (here C++). + critically judge and verify numerical algorithms.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to + solve problems in heterogeneous groups and to document the corresponding results.
<i>Autonomy</i>	Students are able to + assess their knowledge by means of exercises and E-Learning.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	2h
<b>Assignment for the Following Curricula</b>	Materials Science: Specialisation Modeling: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Technomathematics: Specialisation III. Engineering Science: Elective Compulsory Technomathematics: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0284: Numerical Algorithms in Structural Mechanics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	1. Motivation 2. Basics of C++ 3. Numerical integration 4. Solution of nonlinear problems 5. Solution of linear equation systems 6. Verification of numerical algorithms 7. Selected algorithms and data structures of a finite element code
<b>Literature</b>	[1] D. Yang, C++ and object-oriented numeric computing, Springer, 2001. [2] K.-J. Bathe, Finite-Elemente-Methoden, Springer, 2002.

Course L0285: Numerical Algorithms in Structural Mechanics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Alexander Düster
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> see FSPO <i>Skills</i> see FSPO		
<b>Personal Competence</b>	<i>Social Competence</i> see FSPO <i>Autonomy</i> see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		



Module M0627: Machine Learning and Data Mining			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Machine Learning and Data Mining (L0340)	Lecture	2	4
Machine Learning and Data Mining (L0510)	Recitation Section (small)	2	2
<b>Module Responsible</b>	NN		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Calculus</li> <li>• Stochastics</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students can explain the difference between instance-based and model-based learning approaches, and they can enumerate basic machine learning technique for each of the two basic approaches, either on the basis of static data, or on the basis of incrementally incoming data . For dealing with uncertainty, students can describe suitable representation formalisms, and they explain how axioms, features, parameters, or structures used in these formalisms can be learned automatically with different algorithms. Students are also able to sketch different clustering techniques. They depict how the performance of learned classifiers can be improved by ensemble learning, and they can summarize how this influences computational learning theory. Algorithms for reinforcement learning can also be explained by students.</p> <p><i>Skills</i></p> <p>Student derive decision trees and, in turn, propositional rule sets from simple and static data tables and are able to name and explain basic optimization techniques. They present and apply the basic idea of first-order inductive learning. Students apply the BME, MAP, ML, and EM algorithms for learning parameters of Bayesian networks and compare the different algorithms. They also know how to carry out Gaussian mixture learning. They can contrast kNN classifiers, neural networks, and support vector machines, and name their basic application areas and algorithmic properties. Students can describe basic clustering techniques and explain the basic components of those techniques. Students compare related machine learning techniques, e.g., k-means clustering and nearest neighbor classification. They can distinguish various ensemble learning techniques and compare the different goals of those techniques.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i></p> <p><i>Autonomy</i></p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 minutes		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Information Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0340: Machine Learning and Data Mining	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Rainer Marrone
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Decision trees</li> <li>• First-order inductive learning</li> <li>• Incremental learning: Version spaces</li> <li>• Uncertainty</li> <li>• Bayesian networks</li> <li>• Learning parameters of Bayesian networks BME, MAP, ML, EM algorithm</li> <li>• Learning structures of Bayesian networks</li> <li>• Gaussian Mixture Models</li> <li>• KNN classifier, neural network classifier, support vector machine (SVM) classifier</li> <li>• Clustering Distance measures, k-means clustering, nearest neighbor clustering</li> <li>• Kernel Density Estimation</li> <li>• Ensemble Learning</li> <li>• Reinforcement Learning</li> <li>• Computational Learning Theory</li> </ul>
<b>Literature</b>	<ol style="list-style-type: none"> <li>1. Artificial Intelligence: A Modern Approach (Third Edition), Stuart Russel, Peter Norvig, Prentice Hall, 2010, Chapters 13, 14, 18-21</li> <li>2. Machine Learning: A Probabilistic Perspective, Kevin Murphy, MIT Press 2012</li> </ol>

Course L0510: Machine Learning and Data Mining	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Rainer Marrone
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0653: High-Performance Computing			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Fundamentals of High-Performance Computing (L0242)	Lecture	2	3
Fundamentals of High-Performance Computing (L1416)	Project-/problem-based Learning	2	3
<b>Module Responsible</b>	Prof. Thomas Rung		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Basic knowledge in usage of modern IT environment</li> <li>• Programming skills</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students are able to outline the fundamentals of numerical algorithms for high-performance computers by reference to modern hardware examples. Students can explain the relation between hard- and software aspects for the design of algorithms.</p> <p><i>Skills</i> Student can perform a critical assesment of the computational efficiency of simulation approaches.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> Students are able to develop and code algorithms in a team.</p> <p><i>Autonomy</i></p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	1.5h		
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Naval Architecture and Ocean Engineering: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0242: Fundamentals of High-Performance Computing	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Fundamentals of modern hardware architectur, critical hard- & software aspects for efficient processing of exemplary algorithms, concepts for shared- and distributed-memory systems, implementations for accelerator hardware (GPGPUs)
<b>Literature</b>	

Course L1416: Fundamentals of High-Performance Computing	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thomas Rung
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0692: Approximation and Stability			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Approximation and Stability (L0487)	Lecture	3	4
Approximation and Stability (L0488)	Recitation Section (small)	1	2
<b>Module Responsible</b>	Prof. Marko Lindner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Linear Algebra: systems of linear equations, least squares problems, eigenvalues, singular values</li> <li>• Analysis: sequences, series, differentiation, integration</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>Students are able to</p> <ul style="list-style-type: none"> <li>• sketch and interrelate basic concepts of functional analysis (Hilbert space, operators),</li> <li>• name and understand concrete approximation methods,</li> <li>• name and explain basic stability theorems,</li> <li>• discuss spectral quantities, conditions numbers and methods of regularisation</li> </ul>		
<i>Knowledge</i>			
<i>Skills</i>	<p>Students are able to</p> <ul style="list-style-type: none"> <li>• apply basic results from functional analysis,</li> <li>• apply approximation methods,</li> <li>• apply stability theorems,</li> <li>• compute spectral quantities,</li> <li>• apply regularisation methods.</li> </ul>		
<b>Personal Competence</b>	<p>Students are able to solve specific problems in groups and to present their results appropriately (e.g. as a seminar presentation).</p>		
<i>Social Competence</i>			
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students are capable of checking their understanding of complex concepts on their own. They can specify open questions precisely and know where to get help in solving them.</li> <li>• Students have developed sufficient persistence to be able to work for longer periods in a goal-oriented manner on hard problems.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	20 min		
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0487: Approximation and Stability	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Marko Lindner
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<p>This course is about solving the following basic problems of Linear Algebra,</p> <ul style="list-style-type: none"> <li>• systems of linear equations,</li> <li>• least squares problems,</li> <li>• eigenvalue problems</li> </ul> <p>but now in function spaces (i.e. vector spaces of infinite dimension) by a stable approximation of the problem in a space of finite dimension.</p> <p><b>Contents:</b></p> <ul style="list-style-type: none"> <li>• crash course on Hilbert spaces: metric, norm, scalar product, completeness</li> <li>• crash course on operators: boundedness, norm, compactness, projections</li> <li>• uniform vs. strong convergence, approximation methods</li> <li>• applicability and stability of approximation methods, Polski's theorem</li> <li>• Galerkin methods, collocation, spline interpolation, truncation</li> <li>• convolution and Toeplitz operators</li> <li>• crash course on <math>C^*</math>-algebras</li> <li>• convergence of condition numbers</li> <li>• convergence of spectral quantities: spectrum, eigen values, singular values, pseudospectra</li> <li>• regularisation methods (truncated SVD, Tichonov)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• R. Hagen, S. Roch, B. Silbermann: <math>C^*</math>-Algebras in Numerical Analysis</li> <li>• H. W. Alt: Lineare Funktionalanalysis</li> <li>• M. Lindner: Infinite matrices and their finite sections</li> </ul>

Course L0488: Approximation and Stability	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Marko Lindner
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0711: Numerical Mathematics II	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Numerical Mathematics II (L0568)	Lecture                                      2                                      3
Numerical Mathematics II (L0569)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Sabine Le Borne
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Numerical Mathematics I</li> <li>• MATLAB knowledge</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<p>Students are able to</p> <ul style="list-style-type: none"> <li>• name advanced numerical methods for interpolation, integration, linear least squares problems, eigenvalue problems, nonlinear root finding problems and explain their core ideas,</li> <li>• repeat convergence statements for the numerical methods,</li> <li>• sketch convergence proofs,</li> <li>• explain practical aspects of numerical methods concerning runtime and storage needs</li> </ul> <p style="padding-left: 40px;">explain aspects regarding the practical implementation of numerical methods with respect to computational and storage complexity.</p> <ul style="list-style-type: none"> <li>•</li> </ul>
<i>Skills</i>	<p>Students are able to</p> <ul style="list-style-type: none"> <li>• implement, apply and compare advanced numerical methods in MATLAB,</li> <li>• justify the convergence behaviour of numerical methods with respect to the problem and solution algorithm and to transfer it to related problems,</li> <li>• for a given problem, develop a suitable solution approach, if necessary through composition of several algorithms, to execute this approach and to critically evaluate the results</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<p>Students are able to</p> <ul style="list-style-type: none"> <li>• work together in heterogeneously composed teams (i.e., teams from different study programs and background knowledge), explain theoretical foundations and support each other with practical aspects regarding the implementation of algorithms.</li> </ul>
<i>Autonomy</i>	<p>Students are capable</p> <ul style="list-style-type: none"> <li>• to assess whether the supporting theoretical and practical exercises are better solved individually or in a team,</li> <li>• to assess their individual progress and, if necessary, to ask questions and seek help.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	25 min
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computer Science: Specialisation Computer and Software Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Information and Communication Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory

Course L0568: Numerical Mathematics II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ol style="list-style-type: none"> <li>1. Error and stability: Notions and estimates</li> <li>2. Interpolation: Rational and trigonometric interpolation</li> <li>3. Quadrature: Gaussian quadrature, orthogonal polynomials</li> <li>4. Linear systems: Perturbation theory of decompositions, structured matrices</li> <li>5. Eigenvalue problems: LR-, QD-, QR-Algorithmus</li> <li>6. Krylov space methods: Arnoldi-, Lanczos methods</li> </ol>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Stoer/Bulirsch: Numerische Mathematik 1, Springer</li> <li>• Dahmen, Reusken: Numerik für Ingenieure und Naturwissenschaftler, Springer</li> </ul>

Course L0569: Numerical Mathematics II	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0881: Mathematical Image Processing			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Mathematical Image Processing (L0991)	Lecture	3	4
Mathematical Image Processing (L0992)	Recitation Section (small)	1	2
<b>Module Responsible</b>	Prof. Marko Lindner		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Analysis: partial derivatives, gradient, directional derivative</li> <li>• Linear Algebra: eigenvalues, least squares solution of a linear system</li> </ul>		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>Students are able to</p> <p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>• characterize and compare diffusion equations</li> <li>• explain elementary methods of image processing</li> <li>• explain methods of image segmentation and registration</li> <li>• sketch and interrelate basic concepts of functional analysis</li> </ul> <p>Students are able to</p> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>• implement and apply elementary methods of image processing</li> <li>• explain and apply modern methods of image processing</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>Students are able to work together in heterogeneously composed teams (i.e., teams from different study programs and background knowledge) and to explain theoretical foundations.</p> <p><i>Autonomy</i></p> <ul style="list-style-type: none"> <li>• Students are capable of checking their understanding of complex concepts on their own. They can specify open questions precisely and know where to get help in solving them.</li> <li>• Students have developed sufficient persistence to be able to work for longer periods in a goal-oriented manner on hard problems.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	20 min		
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Computational Science and Engineering: Specialisation Kernfächer Mathematik (2 Kurse): Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory		

Course L0991: Mathematical Image Processing	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Marko Lindner
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• basic methods of image processing</li> <li>• smoothing filters</li> <li>• the diffusion / heat equation</li> <li>• variational formulations in image processing</li> <li>• edge detection</li> <li>• image segmentation</li> <li>• image registration</li> </ul>
<b>Literature</b>	Bredies/Lorenz: Mathematische Bildverarbeitung



<b>Course L0992: Mathematical Image Processing</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Marko Lindner
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0716: Hierarchical Algorithms	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Hierarchical Algorithms (L0585)	Lecture                                      2                                      3
Hierarchical Algorithms (L0586)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Sabine Le Borne
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematics I, II, III for Engineering students (german or english) or Analysis &amp; Linear Algebra I + II as well as Analysis III for Technomathematicians</li> <li>• Programming experience in C</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p>Students are able to</p> <p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>• name representatives of hierarchical algorithms and list their characteristics,</li> <li>• explain construction techniques for hierarchical algorithms,</li> <li>• discuss aspects regarding the efficient implementation of hierarchical algorithms.</li> </ul> <p>Students are able to</p> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>• implement the hierarchical algorithms discussed in the lecture,</li> <li>• analyse the storage and computational complexities of the algorithms,</li> <li>• adapt algorithms to problem settings of various applications and thus develop problem adapted variants.</li> </ul> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• work together in heterogeneously composed teams (i.e., teams from different study programs and background knowledge), explain theoretical foundations and support each other with practical aspects regarding the implementation of algorithms.</li> </ul> <p><i>Autonomy</i></p> <p>Students are capable</p> <ul style="list-style-type: none"> <li>• to assess whether the supporting theoretical and practical exercises are better solved individually or in a team,</li> <li>• to work on complex problems over an extended period of time,</li> <li>• to assess their individual progress and, if necessary, to ask questions and seek help.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	20 min
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Computational Science and Engineering: Specialisation Kernfächer Mathematik (2 Kurse): Elective Compulsory Mathematical Modelling in Engineering: Theory, Numerics, Applications: Specialisation II. Modelling and Simulation of Complex Systems (TUHH): Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0585: Hierarchical Algorithms	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Low rank matrices</li> <li>• Separable expansions</li> <li>• Hierarchical matrix partitions</li> <li>• Hierarchical matrices</li> <li>• Formatted matrix operations</li> <li>• Applications</li> <li>• Additional topics (e.g. H2 matrices, matrix functions, tensor products)</li> </ul>
<b>Literature</b>	W. Hackbusch: Hierarchische Matrizen: Algorithmen und Analysis

Course L0586: Hierarchical Algorithms	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0550: Digital Image Analysis			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Digital Image Analysis (L0126)	Lecture	4	6
<b>Module Responsible</b>	Prof. Rolf-Rainer Grigat		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	System theory of one-dimensional signals (convolution and correlation, sampling theory, interpolation and decimation, Fourier transform, linear time-invariant systems), linear algebra (Eigenvalue decomposition, SVD), basic stochastics and statistics (expectation values, influence of sample size, correlation and covariance, normal distribution and its parameters), basics of Matlab, basics in optics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>Students can</p> <ul style="list-style-type: none"> <li>• Describe imaging processes</li> <li>• Depict the physics of sensorics</li> <li>• Explain linear and non-linear filtering of signals</li> <li>• Establish interdisciplinary connections in the subject area and arrange them in their context</li> <li>• Interpret effects of the most important classes of imaging sensors and displays using mathematical methods and physical models.</li> </ul> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• Use highly sophisticated methods and procedures of the subject area</li> <li>• Identify problems and develop and implement creative solutions.</li> </ul> <p><i>Skills</i></p> <p>Students can solve simple arithmetical problems relating to the specification and design of image processing and image analysis systems.</p> <p>Students are able to assess different solution approaches in multidimensional decision-making areas.</p> <p>Students can undertake a prototypical analysis of processes in Matlab.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>k.A.</p> <p><i>Autonomy</i></p> <p>Students can solve image analysis tasks independently using the relevant literature.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	60 Minutes, Content of Lecture and materials in StudIP		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Information and Communication Systems: Elective Compulsory Electrical Engineering: Specialisation Medical Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Information and Communication Systems: Specialisation Communication Systems, Focus Signal Processing: Elective Compulsory Information and Communication Systems: Specialisation Secure and Dependable IT Systems, Focus Software and Signal Processing: Elective Compulsory International Management and Engineering: Specialisation II. Information Technology: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Microelectronics and Microsystems: Specialisation Communication and Signal Processing: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory		

Course L0126: Digital Image Analysis	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Rolf-Rainer Grigat
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Image representation, definition of images and volume data sets, illumination, radiometry, multispectral imaging, reflectivities, shape from shading</li> <li>• Perception of luminance and color, color spaces and transforms, color matching functions, human visual system, color appearance models</li> <li>• imaging sensors (CMOS, CCD, HDR, X-ray, IR), sensor characterization (EMVA1288), lenses and optics</li> <li>• spatio-temporal sampling (interpolation, decimation, aliasing, leakage, moiré, flicker, apertures)</li> <li>• features (filters, edge detection, morphology, invariance, statistical features, texture)</li> <li>• optical flow ( variational methods, quadratic optimization, Euler-Lagrange equations)</li> <li>• segmentation (distance, region growing, cluster analysis, active contours, level sets, energy minimization and graph cuts)</li> <li>• registration (distance and similarity, variational calculus, iterative closest points)</li> </ul>
<b>Literature</b>	Bredies/Lorenz, Mathematische Bildverarbeitung, Vieweg, 2011 Wedel/Cremers, Stereo Scene Flow for 3D Motion Analysis, Springer 2011 Handels, Medizinische Bildverarbeitung, Vieweg, 2000 Pratt, Digital Image Processing, Wiley, 2001 Jain, Fundamentals of Digital Image Processing, Prentice Hall, 1989

Module M1020: Numerics of Partial Differential Equations	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Numerics of Partial Differential Equations (L1247)	Lecture                                      2                                      3
Numerics of Partial Differential Equations (L1248)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Sabine Le Borne
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematik I - IV (for Engineering Students) or Analysis &amp; Linear Algebra I + II for Technomathematicians</li> <li>• Numerical mathematics 1</li> <li>• Numerical treatment of ordinary differential equations</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>• Students can classify partial differential equations according to the three basic types.</li> <li>• For each type, students know suitable numerical approaches.</li> <li>• Students know the theoretical convergence results for these approaches.</li> </ul>
<i>Skills</i>	Students are capable to formulate solution strategies for given problems involving partial differential equations, to comment on theoretical properties concerning convergence and to implement and test these methods in practice.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to work together in heterogeneously composed teams (i.e., teams from different study programs and background knowledge) and to explain theoretical foundations.
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Students are capable of checking their understanding of complex concepts on their own. They can specify open questions precisely and know where to get help in solving them.</li> <li>• Students have developed sufficient persistence to be able to work for longer periods in a goal-oriented manner on hard problems.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	25 min
<b>Assignment for the Following Curricula</b>	Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Technomathematics: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory

Course L1247: Numerics of Partial Differential Equations	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Elementary Theory and Numerics of PDEs</p> <ul style="list-style-type: none"> <li>• types of PDEs</li> <li>• well posed problems</li> <li>• finite differences</li> <li>• finite elements</li> <li>• finite volumes</li> <li>• applications</li> </ul>
<b>Literature</b>	<p>Dietrich Braess: Finite Elemente: Theorie, schnelle Löser und Anwendungen in der Elastizitätstheorie, Berlin u.a., Springer 2007</p> <p>Susanne Brenner, Ridgway Scott: The Mathematical Theory of Finite Element Methods, Springer, 2008</p> <p>Peter Deuffhard, Martin Weiser: Numerische Mathematik 3</p>

Course L1248: Numerics of Partial Differential Equations	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Sabine Le Borne, Dr. Patricio Farrell
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0586: Efficient Algorithms			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Efficient Algorithms (L0120)	Lecture	2	3
Efficient Algorithms (L1207)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Siegfried Rump		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Programming in Matlab and/or C Basic knowledge in discrete mathematics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> The students are able to explain the basic theory and methods of network algorithms and in particular their data structures. They are able to analyze the computational behavior and computing time of linear programming algorithms as well network algorithms. Moreover the students can distinguish between efficiently solvable and NP-hard problems.</p> <p><i>Skills</i> The students are able to analyze complex tasks and can determine possibilities to transform them into networking algorithms. In particular they can efficiently implement basic algorithms and data structures of LP- and network algorithms and identify possible weaknesses. They are able to distinguish between different efficient data structures and are able to use them appropriately.</p> <p><i>Personal Competence</i></p> <p><i>Social Competence</i> The students have the skills to solve problems together in small groups and to present the achieved results in an appropriate manner.</p> <p><i>Autonomy</i> The students are able to retrieve necessary informations from the given literature and to combine them with the topics of the lecture. Throughout the lecture they can check their abilities and knowledge on the basis of given exercises and test questions providing an aid to optimize their learning process.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Computer and Software Engineering: Elective Compulsory Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Information and Communication Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory		



Course L0120: Efficient Algorithms	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Siegfried Rump
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Linear Programming</li> <li>- Data structures</li> <li>- Leftist heaps</li> <li>- Minimum spanning tree</li> <li>- Shortest path</li> <li>- Maximum flow</li> <li>- NP-hard problems via max-cut</li> </ul>
<b>Literature</b>	R. E. Tarjan: Data Structures and Network Algorithms. CBMS 44, Society for Industrial and Applied Mathematics, Philadelphia, PA, 1983. Wesley, 2011 <a href="http://algs4.cs.princeton.edu/home/">http://algs4.cs.princeton.edu/home/</a> V. Chvátal, "Linear Programming", Freeman, New York, 1983.

Course L1207: Efficient Algorithms	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Siegfried Rump
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0549: Scientific Computing and Accuracy			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Verification Methods (L0122)	Lecture	2	3
Verification Methods (L1208)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Siegfried Rump		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge in numerics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	The students have deeper knowledge of numerical and semi-numerical methods with the goal to compute principally exact and accurate error bounds. For several fundamental problems they know algorithms with the verification of the correctness of the computed result.		
<i>Skills</i>	The students can devise algorithms for several basic problems which compute rigorous error bounds for the solution and analyze the sensitivity with respect to variation of the input data as well.		
<b>Personal Competence</b>			
<i>Social Competence</i>	The students have the skills to solve problems together in small groups and to present the achieved results in an appropriate manner.		
<i>Autonomy</i>	The students are able to retrieve necessary informations from the given literature and to combine them with the topics of the lecture. Throughout the lecture they can check their abilities and knowledge on the basis of given exercises and test questions providing an aid to optimize their learning process.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computer Science: Specialisation Computer and Software Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Technomathematics: Specialisation II. Informatics: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Process Engineering: Specialisation Process Engineering: Elective Compulsory Process Engineering: Specialisation Chemical Process Engineering: Elective Compulsory		

Course L0122: Verification Methods	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Siegfried Rump
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Fast and accurate interval arithmetic</li> <li>• Error-free transformations</li> <li>• Verification methods for linear and nonlinear systems</li> <li>• Verification methods for finite integrals</li> <li>• Treatment of multiple zeros</li> <li>• Automatic differentiation</li> <li>• Implementation in Matlab/INTLAB</li> <li>• Practical applications</li> </ul>
<b>Literature</b>	Neumaier: Interval Methods for Systems of Equations. In: Encyclopedia of Mathematics and its Applications. Cambridge University Press, 1990 S.M. Rump. Verification methods: Rigorous results using floating-point arithmetic. Acta Numerica, 19:287-449, 2010.

Course L1208: Verification Methods	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Siegfried Rump
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0677: Digital Signal Processing and Digital Filters	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Digital Signal Processing and Digital Filters (L0446)	Lecture                                      3                                      4
Digital Signal Processing and Digital Filters (L0447)	Recitation Section (large)                      1                                      2
<b>Module Responsible</b>	Prof. Gerhard Bauch
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematics 1-3</li> <li>• Signals and Systems</li> <li>• Fundamentals of signal and system theory as well as random processes.</li> <li>• Fundamentals of spectral transforms (Fourier series, Fourier transform, Laplace transform)</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The students know and understand basic algorithms of digital signal processing. They are familiar with the spectral transforms of discrete-time signals and are able to describe and analyse signals and systems in time and image domain. They know basic structures of digital filters and can identify and assess important properties including stability. They are aware of the effects caused by quantization of filter coefficients and signals. They are familiar with the basics of adaptive filters. They can perform traditional and parametric methods of spectrum estimation, also taking a limited observation window into account.
<i>Skills</i>	The students are able to apply methods of digital signal processing to new problems. They can choose and parameterize suitable filter structures. In particular, they can design adaptive filters according to the minimum mean squared error (MMSE) criterion and develop an efficient implementation, e.g. based on the LMS or RLS algorithm. Furthermore, the students are able to apply methods of spectrum estimation and to take the effects of a limited observation window into account.
<b>Personal Competence</b>	
<i>Social Competence</i>	The students can jointly solve specific problems.
<i>Autonomy</i>	The students are able to acquire relevant information from appropriate literature sources. They can control their level of knowledge during the lecture period by solving tutorial problems, software tools, clicker system.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 min
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Electrical Engineering: Specialisation Information and Communication Systems: Elective Compulsory Electrical Engineering: Specialisation Control and Power Systems: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Computational Science and Engineering: Specialisation Kernfächer Ingenieurwissenschaften (2 Kurse): Elective Compulsory Information and Communication Systems: Specialisation Communication Systems, Focus Signal Processing: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Microelectronics and Microsystems: Specialisation Microelectronics Complements: Elective Compulsory Microelectronics and Microsystems: Specialisation Communication and Signal Processing: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0446: Digital Signal Processing and Digital Filters	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Gerhard Bauch
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Transforms of discrete-time signals:                             <ul style="list-style-type: none"> <li>◦ Discrete-time Fourier Transform (DTFT)</li> <li>◦ Discrete Fourier-Transform (DFT), Fast Fourier Transform (FFT)</li> <li>◦ Z-Transform</li> </ul> </li> <li>• Correspondence of continuous-time and discrete-time signals, sampling, sampling theorem</li> <li>• Fast convolution, Overlap-Add-Method, Overlap-Save-Method</li> <li>• Fundamental structures and basic types of digital filters</li> <li>• Characterization of digital filters using pole-zero plots, important properties of digital filters</li> <li>• Quantization effects</li> <li>• Design of linear-phase filters</li> <li>• Fundamentals of stochastic signal processing and adaptive filters                             <ul style="list-style-type: none"> <li>◦ MMSE criterion</li> <li>◦ Wiener Filter</li> <li>◦ LMS- and RLS-algorithm</li> </ul> </li> <li>• Traditional and parametric methods of spectrum estimation</li> </ul>
<b>Literature</b>	K.-D. Kammeyer, K. Kroschel: Digitale Signalverarbeitung. Vieweg Teubner. V. Oppenheim, R. W. Schaffer, J. R. Buck: Zeitdiskrete Signalverarbeitung. Pearson Studium A. V. W. Hess: Digitale Filter. Teubner. Oppenheim, R. W. Schaffer: Digital signal processing. Prentice Hall. S. Haykin: Adaptive filter theory. L. B. Jackson: Digital filters and signal processing. Kluwer. T.W. Parks, C.S. Burrus: Digital filter design. Wiley.

Course L0447: Digital Signal Processing and Digital Filters	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Gerhard Bauch
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1336: Soft Computing	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Soft Computing (L1869)	Lecture
<b>Hrs/wk</b>	<b>CP</b>
4	6
<b>Module Responsible</b>	Prof. Karl-Heinz Zimmermann
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Bachelor in Computer Science. Basics in higher mathematics are inevitable, like calculus, linear algebra, graph theory, and optimization.
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to formalize, compute, and analyze belief networks, alignments of sequences, hidden Markov models, phylogenetic tree models, neural networks, and fuzzy controllers. In particular, inference and learning in belief networks are important topics that the students should be able to master.
<i>Skills</i>	Students can apply the relevant algorithms and determine their complexity, and they can make use of the statistics language R.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to solve specific problems alone or in a group and to present the results accordingly.
<i>Autonomy</i>	Students are able to acquire new knowledge from newer literature and to associate the acquired knowledge to other fields.
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	25 min
<b>Assignment for the Following Curricula</b>	Bioprocess Engineering: Specialisation A - General Bioprocess Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation General Process Engineering: Elective Compulsory Chemical and Bioprocess Engineering: Specialisation Bioprocess Engineering: Elective Compulsory Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Information and Communication Technology: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Management and Engineering: Specialisation II. Information Technology: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory

Course L1869: Soft Computing	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Karl-Heinz Zimmermann
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	Students are able to formalize, compute, and analyze belief networks, alignments of sequences, hidden Markov models, phylogenetic tree models, neural networks, and fuzzy controllers. In particular, inference and learning in belief networks are important topics that the students should be able to master. Students can apply the relevant algorithms and determine their complexity, and they can make use of the statistics language R.
<b>Literature</b>	<ol style="list-style-type: none"> <li>David Barber, Bayes Reasoning and Machine Learning, Cambridge Univ. Press, Cambridge, 2012.</li> <li>Volker Claus, Stochastische Automaten, Teubner, Stuttgart, 1971.</li> <li>Ernst Klement, Radko Mesiar, Endre Pap, Triangular Norms, Kluwer, Dordrecht, 2000.</li> <li>Timo Koski, John M. Noble, Bayesian Networks, Wiley, New York, 2009.</li> <li>Dimitris Margaritis, Learning Bayesian Network Model Structure from Data, PhD thesis, Carnegie Mellon University, Pittsburgh, 2003.</li> <li>Hidetoshi Nishimori, Statistical Physics of Spin Glasses and Information Processing, Oxford Univ. Press, London, 2001.</li> <li>James R. Norris, Markov Chains, Cambridge Univ. Press, Cambridge, 1996.</li> <li>Maria Rizzo, Statistical Computing with R, Chapman &amp; Hall/CRC, Boca Raton, 2008.</li> <li>Peter Sprites, Clark Glymour, Richard Scheines, Causation, Prediction, and Search, Springer, New York, 1993.</li> <li>Raul Rojas, Neural Networks, Springer, Berlin, 1996.</li> <li>Lior Pachter, Bernd Sturmfels, Algebraic Statistics for Computational Biology, Cambridge Univ. Press, Cambridge, 2005.</li> <li>David A. Sprecher, From Algebra to Computational Algorithms, Docent Press, Boston, 2017.</li> <li>Karl-Heinz Zimmermann, Algebraic Statistics, TubDok, Hamburg, 2016.</li> </ol>

Module M0720: Matrix Algorithms	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Matrix Algorithms (L0984)	Lecture                                      2                                      3
Matrix Algorithms (L0985)	Recitation Section (small)              2                                      3
<b>Module Responsible</b>	Dr. Jens-Peter Zemke
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Mathematics I - III</li> <li>• Numerical Mathematics 1/ Numerics</li> <li>• Basic knowledge of the programming languages Matlab and C</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students are able to</p> <ol style="list-style-type: none"> <li>1. name, state and classify state-of-the-art Krylov subspace methods for the solution of the core problems of the engineering sciences, namely, eigenvalue problems, solution of linear systems, and model reduction;</li> <li>2. state approaches for the solution of matrix equations (Sylvester, Lyapunov, Riccati).</li> </ol> <p><i>Skills</i></p> <p>Students are capable to</p> <ol style="list-style-type: none"> <li>1. implement and assess basic Krylov subspace methods for the solution of eigenvalue problems, linear systems, and model reduction;</li> <li>2. assess methods used in modern software with respect to computing time, stability, and domain of applicability;</li> <li>3. adapt the approaches learned to new, unknown types of problem.</li> </ol> <p><i>Personal Competence</i></p> <p>Students can</p> <ul style="list-style-type: none"> <li>• develop and document joint solutions in small teams;</li> <li>• form groups to further develop the ideas and transfer them to other areas of applicability;</li> <li>• form a team to develop, build, and advance a software library.</li> </ul> <p><i>Autonomy</i></p> <p>Students are able to</p> <ul style="list-style-type: none"> <li>• correctly assess the time and effort of self-defined work;</li> <li>• assess whether the supporting theoretical and practical exercises are better solved individually or in a team;</li> <li>• define test problems for testing and expanding the methods;</li> <li>• assess their individual progress and, if necessary, to ask questions and seek help.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	30 min
<b>Assignment for the Following Curricula</b>	Electrical Engineering: Specialisation Modeling and Simulation: Elective Compulsory Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mathematical Modelling in Engineering: Theory, Numerics, Applications: Specialisation II. Modelling and Simulation of Complex Systems (TUHH): Elective Compulsory Technomathematics: Specialisation I. Mathematics: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory

Course L0984: Matrix Algorithms	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Jens-Peter Zemke
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Part A: Krylov Subspace Methods:               <ul style="list-style-type: none"> <li>◦ Basics (derivation, basis, Ritz, OR, MR)</li> <li>◦ Arnoldi-based methods (Arnoldi, GMRes)</li> <li>◦ Lanczos-based methods (Lanczos, CG, BiCG, QMR, SymmLQ, PvL)</li> <li>◦ Sonneveld-based methods (IDR, BiCGStab, TFQMR, IDR(s))</li> </ul> </li> <li>• Part B: Matrix Equations:               <ul style="list-style-type: none"> <li>◦ Sylvester Equation</li> <li>◦ Lyapunov Equation</li> <li>◦ Algebraic Riccati Equation</li> </ul> </li> </ul>
<b>Literature</b>	Skript

Course L0985: Matrix Algorithms	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Jens-Peter Zemke
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	Siehe korrespondierende Vorlesung



Module M0552: 3D Computer Vision	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
3D Computer Vision (L0129)	Lecture
3D Computer Vision (L0130)	Recitation Section (small)
<b>Hrs/wk</b>	<b>CP</b>
2	3
2	3
<b>Module Responsible</b>	Prof. Rolf-Rainer Grigat
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	<ul style="list-style-type: none"> <li>• Knowledge of the modules Digital Image Analysis and Pattern Recognition and Data Compression are used in the practical task</li> <li>• Linear Algebra (including PCA, SVD), nonlinear optimization (Levenberg-Marquardt), basics of stochastics and basics of Matlab are required and cannot be explained in detail during the lecture.</li> </ul>
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<p><i>Knowledge</i> Students can explain and describe the field of projective geometry.</p> <p>Students are capable of</p> <ul style="list-style-type: none"> <li>• Implementing an exemplary 3D or volumetric analysis task</li> <li>• Using highly sophisticated methods and procedures of the subject area</li> <li>• Identifying problems and</li> <li>• Developing and implementing creative solution suggestions.</li> </ul> <p><i>Skills</i> With assistance from the teacher students are able to link the contents of the three subject areas (modules)</p> <ul style="list-style-type: none"> <li>• Digital Image Analysis</li> <li>• Pattern Recognition and Data Compression and</li> <li>• 3D Computer Vision</li> </ul> <p>in practical assignments.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i> Students can collaborate in a small team on the practical realization and testing of a system to reconstruct a three-dimensional scene or to evaluate volume data sets.</p> <p><i>Autonomy</i> Students are able to solve simple tasks independently with reference to the contents of the lectures and the exercise sets.</p> <p>Students are able to solve detailed problems independently with the aid of the tutorial's programming task.</p>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	60 Minutes, Content of Lecture and materials in StudIP
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory Information and Communication Systems: Specialisation Communication Systems, Focus Signal Processing: Elective Compulsory Information and Communication Systems: Specialisation Secure and Dependable IT Systems, Focus Software and Signal Processing: Elective Compulsory Mechanical Engineering and Management: Specialisation Mechatronics: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Microelectronics and Microsystems: Specialisation Communication and Signal Processing: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory

Course L0129: 3D Computer Vision	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Rolf-Rainer Grigat
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Projective Geometry and Transformations in 2D und 3D in homogeneous coordinates</li> <li>• Projection matrix, calibration</li> <li>• Epipolar Geometry, fundamental and essential matrices, weak calibration, 5 point algorithm</li> <li>• Homographies 2D and 3D</li> <li>• Trifocal Tensor</li> <li>• Correspondence search</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Skriptum Grigat/Wenzel</li> <li>• Hartley, Zisserman: Multiple View Geometry in Computer Vision. Cambridge 2003.</li> </ul>

Course L0130: 3D Computer Vision	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Rolf-Rainer Grigat
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0629: Intelligent Autonomous Agents and Cognitive Robotics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Intelligent Autonomous Agents and Cognitive Robotics (L0341)	Lecture	2	4
Intelligent Autonomous Agents and Cognitive Robotics (L0512)	Recitation Section (small)	2	2
<b>Module Responsible</b>	Rainer Marrone		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Vectors, matrices, Calculus		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>Students can explain the agent abstraction, define intelligence in terms of rational behavior, and give details about agent design (goals, utilities, environments). They can describe the main features of environments. The notion of adversarial agent cooperation can be discussed in terms of decision problems and algorithms for solving these problems. For dealing with uncertainty in real-world scenarios, students can summarize how Bayesian networks can be employed as a knowledge representation and reasoning formalism in static and dynamic settings. In addition, students can define decision making procedures in simple and sequential settings, with and with complete access to the state of the environment. In this context, students can describe techniques for solving (partially observable) Markov decision problems, and they can recall techniques for measuring the value of information. Students can identify techniques for simultaneous localization and mapping, and can explain planning techniques for achieving desired states. Students can explain coordination problems and decision making in a multi-agent setting in term of different types of equilibria, social choice functions, voting protocol, and mechanism design techniques.</p> <p><i>Skills</i></p> <p>Students can select an appropriate agent architecture for concrete agent application scenarios. For simplified agent application students can derive decision trees and apply basic optimization techniques. For those applications they can also create Bayesian networks/dynamic Bayesian networks and apply bayesian reasoning for simple queries. Students can also name and apply different sampling techniques for simplified agent scenarios. For simple and complex decision making students can compute the best action or policies for concrete settings. In multi-agent situations students will apply techniques for finding different equilibria states, e.g., Nash equilibria. For multi-agent decision making students will apply different voting protocols and compare and explain the results.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i></p> <p>Students are able to discuss their solutions to problems with others. They communicate in English</p> <p><i>Autonomy</i></p> <p>Students are able of checking their understanding of complex concepts by solving variants of concrete problems</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 minutes		
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Production Management: Specialisation Production Technology: Elective Compulsory International Management and Engineering: Specialisation II. Information Technology: Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory		

Course L0341: Intelligent Autonomous Agents and Cognitive Robotics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 92, Study Time in Lecture 28
<b>Lecturer</b>	Rainer Marrone
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Definition of agents, rational behavior, goals, utilities, environment types</li> <li>• Adversarial agent cooperation: Agents with complete access to the state(s) of the environment, games, Minimax algorithm, alpha-beta pruning, elements of chance</li> <li>• Uncertainty: Motivation: agents with no direct access to the state(s) of the environment, probabilities, conditional probabilities, product rule, Bayes rule, full joint probability distribution, marginalization, summing out, answering queries, complexity, independence assumptions, naive Bayes, conditional independence assumptions</li> <li>• Bayesian networks: Syntax and semantics of Bayesian networks, answering queries revised (inference by enumeration), typical-case complexity, pragmatics: reasoning from effect (that can be perceived by an agent) to cause (that cannot be directly perceived).</li> <li>• Probabilistic reasoning over time: Environmental state may change even without the agent performing actions, dynamic Bayesian networks, Markov assumption, transition model, sensor model, inference problems: filtering, prediction, smoothing, most-likely explanation, special cases: hidden Markov models, Kalman filters, Exact inferences and approximations</li> <li>• Decision making under uncertainty: Simple decisions: utility theory, multivariate utility functions, dominance, decision networks, value of information Complex decisions: sequential decision problems, value iteration, policy iteration, MDPs Decision-theoretic agents: POMDPs, reduction to multidimensional continuous MDPs, dynamic decision networks</li> <li>• Simultaneous Localization and Mapping</li> <li>• Planning</li> <li>• Game theory (Golden Balls: Split or Share) Decisions with multiple agents, Nash equilibrium, Bayes-Nash equilibrium</li> <li>• Social Choice Voting protocols, preferences, paradoxes, Arrow's Theorem,</li> <li>• Mechanism Design Fundamentals, dominant strategy implementation, Revelation Principle, Gibbard-Satterthwaite Impossibility Theorem, Direct mechanisms, incentive compatibility, strategy-proofness, Vickrey-Groves-Clarke mechanisms, expected externality mechanisms, participation constraints, individual rationality, budget balancedness, bilateral trade, Myerson-Satterthwaite Theorem</li> </ul>
<b>Literature</b>	<ol style="list-style-type: none"> <li>1. Artificial Intelligence: A Modern Approach (Third Edition), Stuart Russell, Peter Norvig, Prentice Hall, 2010, Chapters 2-5, 10-11, 13-17</li> <li>2. Probabilistic Robotics, Thrun, S., Burgard, W., Fox, D. MIT Press 2005</li> <li>3. Multiagent Systems: Algorithmic, Game-Theoretic, and Logical Foundations, Yoav Shoham, Kevin Leyton-Brown, Cambridge University Press, 2009</li> </ol>

Course L0512: Intelligent Autonomous Agents and Cognitive Robotics	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Rainer Marrone
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

## Specialization Product Development and Production

At the center of the specialization „product development and production“ is the acquisition of knowledge and skills for developing, designing and manufacturing of mechanical engineering products. This includes product planning, systematic and methodical development of solution concepts, the design and construction of products with special emphasis on component stress and cost considerations, to the derivation and creation of manufacturing documentation and the implementation in production.

Module M0815: Product Planning	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Product Planning (L0851)	Project-/problem-based Learning                      3                      3
Product Planning Seminar (L0853)	Project-/problem-based Learning                      2                      3
<b>Module Responsible</b>	Prof. Cornelius Herstatt
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Good basic-knowledge of Business Administration
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students will gain insights into: <ul style="list-style-type: none"> <li>• Product Planning               <ul style="list-style-type: none"> <li>◦ Process</li> <li>◦ Methods</li> </ul> </li> <li>• Design thinking               <ul style="list-style-type: none"> <li>◦ Process</li> <li>◦ Methods</li> <li>◦ User integration</li> </ul> </li> </ul>
<i>Skills</i>	Students will gain deep insights into: <ul style="list-style-type: none"> <li>• Product Planning               <ul style="list-style-type: none"> <li>◦ Process-related aspects</li> <li>◦ Organisational-related aspects</li> <li>◦ Human-Ressource related aspects</li> <li>◦ Working-tools, methods and instruments</li> <li>◦</li> </ul> </li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>• Interact within a team</li> <li>• Raise awareness for globabl issues</li> </ul>
<i>Autonomy</i>	<ul style="list-style-type: none"> <li>• Gain access to knowledge sources</li> <li>• Interpret complex cases</li> <li>• Develop presentation skills</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 minutes
<b>Assignment for the Following Curricula</b>	Global Innovation Management: Core qualification: Compulsory International Management and Engineering: Specialisation I. Electives Management: Elective Compulsory Mechanical Engineering and Management: Specialisation Management: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0851: Product Planning	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Cornelius Herstatt
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Product Planning Process</p> <p>This integrated lecture is designed to understand major issues, activities and tools in the context of systematic product planning, a key activity for managing the front-end of innovation, i.e.:</p> <ul style="list-style-type: none"> <li>• Systematic scanning of markets for innovation opportunities</li> <li>• Understanding strengths/weakness and specific core competences of a firm as platforms for innovation</li> <li>• Exploring relevant sources for innovation (customers, suppliers, Lead Users, etc.)</li> <li>• Developing ideas for radical innovation, relying on the creativeness of employees, using techniques to stimulate creativity and creating a stimulating environment</li> <li>• Transferring ideas for innovation into feasible concepts which have a high market attractively</li> </ul>
<b>Literature</b>	Ulrich, K./Eppinger, S.: Product Design and Development, 2nd. Edition, McGraw-Hill 2010

Course L0853: Product Planning Seminar	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Cornelius Herstatt
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	Seminar is integrative part of the Module Product Planning (for content see lecture) and can not be chosen independantly
<b>Literature</b>	see/siehe Vorlesung Produktplanung/Product Planning

Module M0867: Production Planning & Control and Digital Enterprise			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
The Digital Enterprise (L0932)	Lecture	2	2
Production Planning and Control (L0929)	Lecture	2	2
Production Planning and Control (L0930)	Recitation Section (small)	1	1
Exercise: The Digital Enterprise (L0933)	Recitation Section (small)	1	1
<b>Module Responsible</b>	Prof. Hermann Lödding		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Fundamentals of Production and Quality Management		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> Students can explain the contents of the module in detail and take a critical position to them.</p> <p><i>Skills</i> Students are capable of choosing and applying models and methods from the module to industrial problems.</p>		
<b>Personal Competence</b>	<p><i>Social Competence</i> Students can develop joint solutions in mixed teams and present them to others.</p> <p><i>Autonomy</i> -</p>		
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	180 Minuten		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Production and Logistics: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L0932: The Digital Enterprise	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Axel Friedewald
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Due to the developments of Industry 4.0, digitalization and interconnectivity become a strategic advantage for companies in the international competition. This lecture focuses on the relevant modules and enables the participants to evaluate current developments in this context. In particular, knowledge management, simulation, process modelling and virtual technologies are covered.</p> <p>Content:</p> <ul style="list-style-type: none"> <li>• Business Process Management and Data Modelling, Simulation</li> <li>• Knowledge and Competence Management</li> <li>• Process Management (PPC, Workflow Management)</li> <li>• Computer Aided Planning (CAP) and NC-Programming</li> <li>• Virtual Reality (VR) and Augmented Reality (AR)</li> <li>• Computer Aided Quality Management (CAQ)</li> <li>• Industry 4.0</li> </ul>
<b>Literature</b>	Scheer, A.-W.: ARIS - vom Geschäftsprozeß zum Anwendungssystem. Springer-Verlag, Berlin 4. Aufl. 2002 Schuh, G. et. al.: Produktionsplanung und -steuerung, Springer-Verlag, Berlin 3. Auflage 2006 Becker, J.; Luczak, H.: Workflowmanagement in der Produktionsplanung und -steuerung. Springer-Verlag, Berlin 2004 Pfeifer, T.; Schmitt, R.: Masing Handbuch Qualitätsmanagement. Hanser-Verlag, München 5. Aufl. 2007 Kühn, W.: Digitale Fabrik. Hanser-Verlag, München 2006

Course L0929: Production Planning and Control	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Hermann Lödding
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Models of Production and Inventory Management</li> <li>• Production Programme Planning and Lot Sizing</li> <li>• Order and Capacity Scheduling</li> <li>• Selected Strategies of PPC</li> <li>• Manufacturing Control</li> <li>• Production Controlling</li> <li>• Supply Chain Management</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Vorlesungsskript</li> <li>• Lödding, H: Verfahren der Fertigungssteuerung, Springer 2008</li> <li>• Nyhuis, P.; Wiendahl, H.-P.: Logistische Kennlinien, Springer 2002</li> </ul>

Course L0930: Production Planning and Control	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Hermann Lödding
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L0933: Exercise: The Digital Enterprise	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Dr. Axel Friedewald
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	<p>Siehe korrespondierende Vorlesung</p> <p>See interlocking course</p>



Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	see FSPO		
<i>Skills</i>	see FSPO		
<b>Personal Competence</b>			
<i>Social Competence</i>	see FSPO		
<i>Autonomy</i>	see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Module M1024: Methods of Integrated Product Development			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Integrated Product Development II (L1254)	Lecture	3	3
Integrated Product Development II (L1255)	Project-/problem-based Learning	2	3
<b>Module Responsible</b>	Prof. Dieter Krause		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basic knowledge of Integrated product development and applying CAE systems		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>After passing the module students are able to:</p> <p><i>Knowledge</i></p> <ul style="list-style-type: none"> <li>explain technical terms of design methodology,</li> <li>describe essential elements of construction management,</li> <li>describe current problems and the current state of research of integrated product development.</li> </ul> <p>After passing the module students are able to:</p> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>select and apply proper construction methods for non-standardized solutions of problems as well as adapt new boundary conditions,</li> <li>solve product development problems with the assistance of a workshop based approach,</li> <li>choose and execute appropriate moderation techniques.</li> </ul> <p><b>Personal Competence</b></p> <p>After passing the module students are able to:</p> <p><i>Social Competence</i></p> <ul style="list-style-type: none"> <li>prepare and lead team meetings and moderation processes,</li> <li>work in teams on complex tasks,</li> <li>represent problems and solutions and advance ideas.</li> </ul> <p>After passing the module students are able to:</p> <p><i>Autonomy</i></p> <ul style="list-style-type: none"> <li>give a structured feedback and accept a critical feedback,</li> <li>implement the accepted feedback autonomously.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	30 Minuten		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory Aircraft Systems Engineering: Specialisation Air Transportation Systems: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory		

Course L1254: Integrated Product Development II	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p><b>Lecture</b></p> <p>The lecture extends and enhances the learned content of the module "Integrated Product Development and lightweight design" and is based on the knowledge and skills acquired there.</p> <p>Topics of the course include in particular:</p> <ul style="list-style-type: none"> <li>• Methods of product development,</li> <li>• Presentation techniques,</li> <li>• Industrial Design,</li> <li>• Design for variety</li> <li>• Modularization methods,</li> <li>• Design catalogs,</li> <li>• Adapted QFD matrix,</li> <li>• Systematic material selection,</li> <li>• Assembly oriented design,</li> </ul> <p>Construction management</p> <ul style="list-style-type: none"> <li>• CE mark, declaration of conformity including risk assessment,</li> <li>• Patents, patent rights, patent monitoring</li> <li>• Project management (cost, time, quality) and escalation principles,</li> <li>• Development management for mechatronics,</li> <li>• Technical Supply Chain Management.</li> </ul> <p><b>Exercise (PBL)</b></p> <p>In the exercise the content presented in the lecture "Integrated Product Development II" and methods of product development and design management will be enhanced.</p> <p>Students learn an independently moderated and workshop based approach through industry related practice examples to solve complex and currently existing issues in product development. They will learn the ability to apply important methods of product development and design management autonomous and acquire further expertise in the field of integrated product development. Besides personal skills, such as teamwork, guiding discussions and representing work results will be acquired through the workshop based structure of the event under its own planning and management.</p>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Andreasen, M.M., Design for Assembly, Berlin, Springer 1985.</li> <li>• Ashby, M. F.: Materials Selection in Mechanical Design, München, Spektrum 2007.</li> <li>• Beckmann, H.: Supply Chain Management, Berlin, Springer 2004.</li> <li>• Hartmann, M., Rieger, M., Funk, R., Rath, U.: Zielgerichtet moderieren. Ein Handbuch für Führungskräfte, Berater und Trainer, Weinheim, Beltz 2007.</li> <li>• Pahl, G., Beitz, W.: Konstruktionslehre, Berlin, Springer 2006.</li> <li>• Roth, K.H.: Konstruieren mit Konstruktionskatalogen, Band 1-3, Berlin, Springer 2000.</li> <li>• Simpson, T.W., Siddique, Z., Jiao, R.J.: Product Platform and Product Family Design. Methods and Applications, New York, Springer 2013.</li> </ul>

Course L1255: Integrated Product Development II	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1143: Mechanical Design Methodology	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Mechanical Design Methodology (L1523)	Lecture                                      3                                      4
Mechanical Design Methodology (L1524)	Recitation Section (small)                      1                                      2
<b>Module Responsible</b>	Prof. Josef Schlattmann
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Science-based working on product design considering targeted application of specific product design techniques
<i>Skills</i>	Creative handling of processes used for scientific preparation and formulation of complex product design problems / Application of various product design techniques following theoretical aspects.
<b>Personal Competence</b>	
<i>Social Competence</i>	
<i>Autonomy</i>	
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Oral exam
<b>Examination duration and scale</b>	30 min
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L1523: Mechanical Design Methodology	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	4
<b>Workload in Hours</b>	Independent Study Time 78, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Josef Schlattmann
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Systematic reflection and analysis of the mechanical design process</li> <li>• Process structuring in sections (task, functions, acting principles, design-elements and total construction) as well as levels (working-, controlling-, and deciding-levels)</li> <li>• Creativity (basics, methods, practical application in mechatronics)</li> <li>• Diverse methods applied as tools (function structure, GALFMOS, AEIOU method, GAMPFT, simulation tools, TRIZ)</li> <li>• Evaluation and selection (technical-economical evaluation, preference matrix)</li> <li>• Value analysis, cost-benefit analysis</li> <li>• Low-noise design of technical products</li> <li>• Project monitoring and leading (leading projects / employees, organisation in product development, creating ideas / responsibility and communication)</li> <li>• Aesthetic product design (industrial design, colouring, specific examples / exercises)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Pahl, G.; Beitz, W.; Feldhusen, J.; Grote, K.-H.: Konstruktionslehre: Grundlage erfolgreicher Produktentwicklung, Methoden und Anwendung, 7. Auflage, Springer Verlag, Berlin 2007</li> <li>• VDI-Richtlinien: 2206; 2221 ff</li> </ul>

<b>Course L1524: Mechanical Design Methodology</b>	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Josef Schlattmann
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Systematic reflection and analysis of the mechanical design process</li> <li>• Process structuring in sections (task, functions, acting principles, design-elements and total construction) as well as levels (working-, controlling-, and deciding-levels)</li> <li>• Creativity (basics, methods, practical application in mechatronics)</li> <li>• Diverse methods applied as tools (function structure, GALFMOS, AEIOU method, GAMPFT, simulation tools, TRIZ)</li> <li>• Evaluation and selection (technical-economical evaluation, preference matrix)</li> <li>• Value analysis, cost-benefit analysis</li> <li>• Low-noise design of technical products</li> <li>• Project monitoring and leading (leading projects / employees, organisation in product development, creating ideas / responsibility and communication)</li> <li>• Aesthetic product design (industrial design, colouring, specific examples / exercises)</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Pahl, G.; Beitz, W.; Feldhusen, J.; Grote, K.-H.: Konstruktionslehre: Grundlage erfolgreicher Produktentwicklung, Methoden und Anwendung, 7. Auflage, Springer Verlag, Berlin 2007</li> <li>• VDI-Richtlinien: 2206; 2221ff</li> </ul>

Module M1281: Advanced Topics in Vibration			
<b>Courses</b>			
<b>Title</b>		<b>Typ</b>	<b>Hrs/wk</b> <b>CP</b>
Advanced Topics in Vibration (L1743)		Project-/problem-based Learning	4            6
<b>Module Responsible</b>	Prof. Norbert Hoffmann		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Vibration Theory		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	Students are able to reflect existing terms and concepts of Advanced Vibrations and to develop and research new terms and concepts.		
<i>Skills</i>	Students are able to apply existing methods and procedures of Advanced Vibrations and to develop novel methods and procedures.		
<b>Personal Competence</b>			
<i>Social Competence</i>	Students can reach working results also in groups.		
<i>Autonomy</i>	Students are able to approach given research tasks individually and to identify and follow up novel research tasks by themselves.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	2 Hours		
<b>Assignment for the Following Curricula</b>	Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Mechatronics: Specialisation Intelligent Systems and Robotics: Elective Compulsory Mechatronics: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory		

Course L1743: Advanced Topics in Vibration	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	4
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Lecturer</b>	Prof. Norbert Hoffmann, Merten Tiedemann, Sebastian Kruse
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	Research Topics in Vibrations.
<b>Literature</b>	Aktuelle Veröffentlichungen

<b>Module M0805: Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics )</b>			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics ) (L0516)	Lecture	2	3
Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics ) (L0518)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Otto von Estorff		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Mechanics I (Statics, Mechanics of Materials) and Mechanics II (Hydrostatics, Kinematics, Dynamics) Mathematics I, II, III (in particular differential equations)		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i> The students possess an in-depth knowledge in acoustics regarding acoustic waves, noise protection, and psycho acoustics and are able to give an overview of the corresponding theoretical and methodical basis.</p> <p><i>Skills</i> The students are capable to handle engineering problems in acoustics by theory-based application of the demanding methodologies and measurement procedures treated within the module.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p><i>Autonomy</i> The students are able to independently solve challenging acoustical problems in the areas treated within the module. Possible conflicting issues and limitations can be identified and the results are critically scrutinized.</p>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	30 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory International Management and Engineering: Specialisation II. Aviation Systems: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Technomathematics: Core qualification: Elective Compulsory Technomathematics: Specialisation III. Engineering Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory		

<b>Course L0516: Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics )</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Introduction and Motivation</li> <li>- Acoustic quantities</li> <li>- Acoustic waves</li> <li>- Sound sources, sound radiation</li> <li>- Sound energy and intensity</li> <li>- Sound propagation</li> <li>- Signal processing</li> <li>- Psycho acoustics</li> <li>- Noise</li> <li>- Measurements in acoustics</li> </ul>
<b>Literature</b>	Cremer, L.; Heckl, M. (1996): Körperschall. Springer Verlag, Berlin Veit, I. (1988): Technische Akustik. Vogel-Buchverlag, Würzburg Veit, I. (1988): Flüssigkeitsschall. Vogel-Buchverlag, Würzburg

<b>Course L0518: Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics )</b>	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M0563: Robotics	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Robotics: Modelling and Control (L0168)	Lecture                                      3                                      3
Robotics: Modelling and Control (L1305)	Recitation Section (small)                      2                                      3
<b>Module Responsible</b>	Prof. Uwe Weltin
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Fundamentals of electrical engineering Broad knowledge of mechanics Fundamentals of control theory
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	Students are able to describe fundamental properties of robots and solution approaches for multiple problems in robotics. Students are able to derive and solve equations of motion for various manipulators.
<i>Skills</i>	Students can generate trajectories in various coordinate systems. Students can design linear and partially nonlinear controllers for robotic manipulators.
<b>Personal Competence</b>	
<i>Social Competence</i>	Students are able to work goal-oriented in small mixed groups. Students are able to recognize and improve knowledge deficits independently.
<i>Autonomy</i>	With instructor assistance, students are able to evaluate their own knowledge level and define a further course of study.
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Computer Science: Specialisation Intelligence Engineering: Elective Compulsory Aircraft Systems Engineering: Specialisation Aircraft Systems: Elective Compulsory Computational Science and Engineering: Specialisation Systems Engineering and Robotics: Elective Compulsory International Production Management: Specialisation Production Technology: Elective Compulsory International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Mechanical Engineering and Management: Core qualification: Compulsory Mechatronics: Core qualification: Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory

Course L0168: Robotics: Modelling and Control	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Uwe Weltin
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	Fundamental kinematics of rigid body systems Newton-Euler equations for manipulators Trajectory generation Linear and nonlinear control of robots
<b>Literature</b>	Craig, John J.: Introduction to Robotics Mechanics and Control, Third Edition, Prentice Hall. ISBN 0201-54361-3 Spong, Mark W.; Hutchinson, Seth; Vidyasagar, M. : Robot Modeling and Control. WILEY. ISBN 0-471-64990-2



Course L1305: Robotics: Modelling and Control	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Uwe Weltin
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1025: Fluidics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Fluidics (L1256)	Lecture	2	3
Fluidics (L1371)	Project-/problem-based Learning	1	2
Fluidics (L1257)	Recitation Section (large)	1	1
<b>Module Responsible</b>	Prof. Dieter Krause		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Good knowledge of mechanics (stereo statics, elastostatics, hydrostatics, kinematics and kinetics), fluid mechanics, and engineering design		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	After passing the module students are able to <ul style="list-style-type: none"> <li>• explain structures and functionalities of hydrostatic, pneumatic, and hydrodynamic components,</li> <li>• explain the interaction of hydraulic components in hydraulic systems,</li> <li>• explain open and closed loop control of hydraulic systems,</li> <li>• describe functioning and applications of hydrodynamic torque converters, brakes and clutches as well as centrifugal pumps and aggregates in plant technology</li> </ul>		
<i>Skills</i>	After passing the module students are able to <ul style="list-style-type: none"> <li>• analyse and assess hydraulic and pneumatic components and systems,</li> <li>• design and dimension hydraulic systems for mechanical applications,</li> <li>• perform numerical simulations of hydraulic systems based on abstract problem definitions,</li> <li>• select and adapt pump characteristic curves for hydraulic systems</li> <li>• dimension hydrodynamic torque converters and brakes for mechanical aggregates.</li> </ul>		
<b>Personal Competence</b>			
<i>Social Competence</i>	After passing the module students are able to <ul style="list-style-type: none"> <li>• discuss and present functional context in groups,</li> <li>• organise teamwork autonomously.</li> </ul>		
<i>Autonomy</i>	After passing the module students are able to <ul style="list-style-type: none"> <li>• obtain necessary knowledge for the simulation.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Mechatronics: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1256: Fluidics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p><b>Lecture</b></p> <p>Hydrostatics</p> <ul style="list-style-type: none"> <li>• physical fundamentals</li> <li>• hydraulic fluids</li> <li>• hydrostatic machines</li> <li>• valves</li> <li>• components</li> <li>• hydrostatic transmissions</li> <li>• examples from industry</li> </ul> <p>Pneumatics</p> <ul style="list-style-type: none"> <li>• generation of compressed air</li> <li>• pneumatic motors</li> <li>• Examples of use</li> </ul> <p>Hydrodynamics</p> <ul style="list-style-type: none"> <li>• physical fundamentals</li> <li>• hydraulic continuous-flow machines</li> <li>• hydrodynamic transmissions</li> <li>• interoperation of motor and transmission</li> </ul> <p><b>Exercise</b></p> <p>Hydrostatics</p> <ul style="list-style-type: none"> <li>• reading and design of hydraulic diagrams</li> <li>• dimensioning of hydrostatic traction and working drives</li> <li>• performance calculation</li> </ul> <p>Hydrodynamics</p> <ul style="list-style-type: none"> <li>• calculation / dimensioning of hydrodynamic torque converters</li> <li>• calculation / dimensioning of centrifugal pumps</li> <li>• creating and reading of characteristic curves of pumps and systems</li> </ul> <p>Field trip</p> <ul style="list-style-type: none"> <li>• field trip to a regional company from the hydraulic industry.</li> </ul> <p><b>Exercise</b></p> <p>Numerical simulation of hydrostatic systems</p> <ul style="list-style-type: none"> <li>• getting to know a numerical simulation environment for hydraulic systems</li> <li>• transformation of a task into a simulation model</li> <li>• simulation of common components</li> <li>• variation of simulation parameters</li> <li>• using simulations for system dimensioning and optimisation</li> <li>• (partly) self-organised teamwork</li> </ul>
<b>Literature</b>	<p>Bücher</p> <ul style="list-style-type: none"> <li>• Murrenhoff, H.: Grundlagen der Fluidtechnik - Teil 1: Hydraulik, Shaker Verlag, Aachen, 2011</li> <li>• Murrenhoff, H.: Grundlagen der Fluidtechnik - Teil 2: Pneumatik, Shaker Verlag, Aachen, 2006</li> <li>• Matthies, H.J. Renius, K.Th.: Einführung in die Ölhydraulik, Teubner Verlag, 2006</li> <li>• Beitz, W., Grote, K.-H.: Dubbel - Taschenbuch für den Maschinenbau, Springer-Verlag, Berlin, aktuelle Auflage</li> </ul> <p>Skript zur Vorlesung</p>

Course L1371: Fluidics	
<b>Typ</b>	Project-/problem-based Learning
<b>Hrs/wk</b>	1
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 46, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1257: Fluidics	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Dieter Krause
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Module M1183: Laser systems and methods of manufacturing design and analysis			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Laser Systems and Process Technologies (L1612)	Lecture	2	3
Methods for Analysing Production Processes (L0876)	Lecture	2	3
<b>Module Responsible</b>	Prof. Wolfgang Hintze		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>			
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>			
<i>Skills</i>			
<b>Personal Competence</b>			
<i>Social Competence</i>			
<i>Autonomy</i>			
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	180 min		
<b>Assignment for the Following Curricula</b>	Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1612: Laser Systems and Process Technologies	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Claus Emmelmann
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Fundamentals of laser technology</li> <li>• Laser beam sources: CO<sub>2</sub>-, Nd:YAG-, Fiber- and Diodelasers</li> <li>• Laser system technology: beam forming, beam guidance systems, beam motion and beam control</li> <li>• Laser-based manufacturing technologies: generation, marking, cutting, joining, surface treatment</li> <li>• Quality assurance and economical aspects of laser material processing</li> <li>• Markets and Applications of laser technology</li> <li>• Student group exercises</li> </ul>
<b>Literature</b>	<ul style="list-style-type: none"> <li>• Hügel, H. , T. Graf: Laser in der Fertigung : Strahlquellen, Systeme, Fertigungsverfahren, 3. Aufl., Vieweg + Teubner Wiesbaden 2014.</li> <li>• Eichler, J., Eichler. H. J.: Laser: Bauformen, Strahlführung, Anwendungen, 7. Aufl., Springer-Verlag Berlin Heidelberg 2010.</li> <li>• Steen W. M.; Mazumder J.: Laser material processing, 4th Edition, Springer-Verlag London 2010.</li> <li>• J.C. Ion: Laser processing of engineering materials: principles, procedure and industrial applications, Elsevier Butterworth-Heinemann 2005.</li> <li>• Gebhardt, A.: Understanding additive manufacturing, München [u.a.] Hanser 2011</li> </ul>

<b>Course L0876: Methods for Analysing Production Processes</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Wolfgang Hintze
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Modelling and simulation of machining and forming processes</li> <li>• Numerical simulation of forces, temperatures, deformation in machining</li> <li>• Analysis of vibration problems in machining (chatter, modal analysis,..)</li> <li>• Knowledge based process planning</li> <li>• Design of experiments</li> <li>• Machinability of nonmetallic materials</li> <li>• Analysis of interaction between machining process and machine tool systems with regard to process stability and quality</li> <li>• Simulation of machining processes by virtual reality methods</li> </ul>
<b>Literature</b>	Tönshoff, H.K.; Denkena, B.; Spanen Grundlagen, Springer (2004) Klocke, F.; König, W.; Fertigungsverfahren Umformen, Springer (2006) Weck, M.; Werkzeugmaschinen Fertigungssysteme 3, Springer (2001) Weck, M.; Werkzeugmaschinen Fertigungssysteme 5, Springer (2001)

Module M0806: Technical Acoustics II (Room Acoustics, Computational Methods)			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Technical Acoustics II (Room Acoustics, Computational Methods) (L0519)	Lecture	2	3
Technical Acoustics II (Room Acoustics, Computational Methods) (L0521)	Recitation Section (large)	2	3
<b>Module Responsible</b>	Prof. Otto von Estorff		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Technical Acoustics I (Acoustic Waves, Noise Protection, Psycho Acoustics) Mechanics I (Statics, Mechanics of Materials) and Mechanics II (Hydrostatics, Kinematics, Dynamics) Mathematics I, II, III (in particular differential equations)		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> The students possess an in-depth knowledge in acoustics regarding room acoustics and computational methods and are able to give an overview of the corresponding theoretical and methodical basis. <i>Skills</i> The students are capable to handle engineering problems in acoustics by theory-based application of the demanding computational methods and procedures treated within the module.		
<b>Personal Competence</b>	<i>Social Competence</i> Students can work in small groups on specific problems to arrive at joint solutions. <i>Autonomy</i> The students are able to independently solve challenging acoustical problems in the areas treated within the module. Possible conflicting issues and limitations can be identified and the results are critically scrutinized.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>	20-30 Minuten		
<b>Assignment for the Following Curricula</b>	Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory Mechatronics: Specialisation System Design: Elective Compulsory Product Development, Materials and Production: Core qualification: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory		

Course L0519: Technical Acoustics II (Room Acoustics, Computational Methods)	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Room acoustics</li> <li>- Sound absorber</li> <li>- Standard computations</li> <li>- Statistical Energy Approaches</li> <li>- Finite Element Methods</li> <li>- Boundary Element Methods</li> <li>- Geometrical acoustics</li> <li>- Special formulations</li> <li>- Practical applications</li> <li>- Hands-on Sessions: Programming of elements (Matlab)</li> </ul>
<b>Literature</b>	Cremer, L.; Heckl, M. (1996): Körperschall. Springer Verlag, Berlin Veit, I. (1988): Technische Akustik. Vogel-Buchverlag, Würzburg Veit, I. (1988): Flüssigkeitsschall. Vogel-Buchverlag, Würzburg Gaul, L.; Fiedler, Ch. (1997): Methode der Randelemente in Statik und Dynamik. Vieweg, Braunschweig, Wiesbaden Bathe, K.-J. (2000): Finite-Elemente-Methoden. Springer Verlag, Berlin

<b>Course L0521: Technical Acoustics II (Room Acoustics, Computational Methods)</b>	
<b>Typ</b>	Recitation Section (large)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Otto von Estorff
<b>Language</b>	EN
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course



Module M1174: Automation Technology and Systems	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Handling and Assembly Systems (L1591)	Lecture                                      2                                      2
Handling and Assembly Systems (L1738)	Recitation Section (small)                      1                                      1
Automation Technology (L1590)	Lecture                                      2                                      2
Automation Technology (L1739)	Recitation Section (small)                      1                                      1
<b>Module Responsible</b>	Prof. Thorsten Schüppstuhl
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	without major course assessment
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	Students
<i>Knowledge</i>	<ul style="list-style-type: none"> <li>know the characteristic components of an automation systems and have good understanding of their interaction</li> <li>know methods for a systematical analysis of automation tasks and are able to use them</li> <li>have special competences in industrial robot based automation systems</li> </ul>
<i>Skills</i>	<p>Students are able to...</p> <ul style="list-style-type: none"> <li>analyze complex Automation tasks</li> <li>develop application based concepts and solutions</li> <li>design subsystems and integrate into one system</li> <li>investigate and evaluate safety of machinery</li> <li>create simple programs for robots and programmable logic controllers</li> <li>design of circuit for pneumatic applications</li> </ul>
<b>Personal Competence</b>	Students are able to ...
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>find solutions for automation and handling tasks in groups</li> <li>develop solutions in a production environment with qualified personnel at technical level and represent decisions.</li> </ul>
<i>Autonomy</i>	<p>Students are able to ...</p> <ul style="list-style-type: none"> <li>analyze automation tasks independently</li> <li>generate programs for robots and programmable logic devices autonomously</li> <li>develop solutions for practice oriented tasks of automation independently</li> <li>design safety concepts for automation applications</li> <li>assess consequences of their professional actions and responsibilities</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	120 min
<b>Assignment for the Following Curricula</b>	Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory

Course L1591: Handling and Assembly Systems	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thorsten Schüppstuhl
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Fundamentals and terminology of handling and assembly systems</p> <ul style="list-style-type: none"> <li>-Analysis of parts and handling tasks</li> <li>-Supply and transfer systems</li> <li>-Gripper</li> <li>-Industrial robots: structure, control and programming</li> <li>-Safety of machinery</li> </ul>
<b>Literature</b>	<p>Stefan Hesse Grundlagen der Handhabungstechnik ISBN: 3446418725 München Hanser, 2010</p>

Course L1738: Handling and Assembly Systems	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Thorsten Schüppstuhl
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	See interlocking course
<b>Literature</b>	See interlocking course

Course L1590: Automation Technology	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Thorsten Schüppstuhl
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>-Introduction to the production Automation including their different fields of application, important terms, automation history and upcoming trends</li> <li>-Overview of different actuator concepts and their principles</li> <li>-Design of pneumatic wiring diagrams</li> <li>-Energyefficiency in the production</li> <li>-Review of automatic identification systems like Barcode and RFID</li> <li>-Overview of the structure, components and algorithms of an image processing system</li> <li>-Introduction to buscommunication an the different general concepts</li> <li>-Comparision of Programmable logic controllers and hard-wired programmed logic controllers including the upcoming trends</li> </ul>
<b>Literature</b>	Reinhard Langmann: Taschenbuch der Automatisierung Holger Watter: Hydraulik und Pneumatik Horst Walter Grollius: Grundlagen der Pneumatik Hubertus Murrenhoff: Grundlagen der Fluidtechnik Christian Demant: Industrielle Bildverarbeitung Michael ten Hompel: Identifikationssysteme und Automatisierung Hans-Jürgen Gevatter, Ulrich Grünhaupt: Handbuch der Mess- und Automatisierungstechnik in der Produktion

Course L1739: Automation Technology	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	1
<b>CP</b>	1
<b>Workload in Hours</b>	Independent Study Time 16, Study Time in Lecture 14
<b>Lecturer</b>	Prof. Thorsten Schüppstuhl
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>-Introduction to the production Automation including their different fields of application, important terms, automation history and upcoming trends</li> <li>-Overview of different actuator concepts and their principles</li> <li>-Design of pneumatic wiring diagrams</li> <li>-Energyefficiency in the production</li> <li>-Review of automatic identification systems like Barcode and RFID</li> <li>-Overview of the structure, components and algorithms of an image processing system</li> <li>-Introduction to buscommunication an the different general concepts</li> <li>-Comparision of Programmable logic controllers and hard-wired programmed logic controllers including the upcoming trends</li> </ul>
<b>Literature</b>	<p>Reinhard Langmann: Taschenbuch der Automatisierung</p> <p>Holger Watter: Hydraulik und Pneumatik</p> <p>Horst Walter Grollius: Grundlagen der Pneumatik</p> <p>Hubertus Murrenhoff: Grundlagen der Fluidtechnik</p> <p>Christian Demant: Industrielle Bildverarbeitung</p> <p>Michael ten Hompel: Identifikationssysteme und Automatisierung</p> <p>Hans-Jürgen Gevatter, Ulrich Grünhaupt: Handbuch der Mess- und Automatisierungstechnik in der Produktion</p>

Module M0739: Factory Planning & Production Logistics			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Factory Planning (L1445)	Lecture	3	3
Production Logistics (L1446)	Lecture	2	3
<b>Module Responsible</b>	Prof. Jochen Kreuzfeldt		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Bachelor degree in logistics		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>The students will acquire the following knowledge:</p> <ol style="list-style-type: none"> <li>1. The students know the latest trends and developments in the planning of factories.</li> <li>2. The students can explain basic procedures of factory planning and are able to deploy these procedures while considering different conditions.</li> <li>3. The students know different methods of factory planning and are able to deal critically with these methods.</li> </ol> <p>The students will acquire the following skills:</p> <ol style="list-style-type: none"> <li>1. The students are able to analyze factories and other material flow systems with regard to new development and the need for change of these logistical systems.</li> <li>2. The students are able to plan and redesign factories and other material handling systems.</li> <li>3. The students are able to develop procedures for the implementation of new and revised material flow systems.</li> </ol> <p><b>Personal Competence</b></p> <p>The students will acquire the following social skills:</p> <ol style="list-style-type: none"> <li>1. The students are able to develop plans for the development of new and improvement of existing material flow systems within a group.</li> <li>2. The developed planning proposal from the group work can be documented and presented together.</li> <li>3. The students are able to derive suggestions for improvement from the feedback on the planning proposals and can even provide constructive criticism themselves.</li> </ol> <p>The students will acquire the following independent competencies:</p> <ol style="list-style-type: none"> <li>1. The students can plan and re-design material flow systems using existing planning procedures.</li> <li>2. The students can evaluate independently the strengths and weaknesses of several techniques for factory planning and choose appropriate methods in a given context.</li> <li>3. The students are able to carry out autonomously new plans and transformations of material flow systems.</li> </ol>		
<b>Workload in Hours</b>	Independent Study Time 110, Study Time in Lecture 70		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	120 min		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Logistics: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Logistics, Infrastructure and Mobility: Specialisation Production and Logistics: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory		

Course L1445: Factory Planning	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	3
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 48, Study Time in Lecture 42
<b>Lecturer</b>	Prof. Jochen Kreuzfeldt
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The lecture gives an introduction into the planning of factories and material flows. The students will learn process models and methods to plan new factories and improve existing material flow systems. The course includes three basic topics:</p> <ol style="list-style-type: none"> <li>(1) Analysis of factory and material flow systems</li> <li>(2) Development and re-planning of factory and material flow systems</li> <li>(3) Implementation and realization of factory planning</li> </ol> <p>The students are introduced into several different methods and models per topic. Practical examples and planning exercises deepen the methods and explain the application of factory planning. Current trends and issues in the factory planning round off the lecture.</p>
<b>Literature</b>	<p>Bracht, Uwe; Wenzel, Sigrid; Geckler, Dieter (2011): Digitale Fabrik: Methoden und Praxisbeispiele. 1. Aufl.: Springer, Berlin.</p> <p>Helbing, Kurt W. (2010): Handbuch Fabrikprojektierung. Berlin, Heidelberg: Springer Berlin Heidelberg.</p> <p>Lotter, Bruno; Wiendahl, Hans-Peter (2012): Montage in der industriellen Produktion: Optimierte Abläufe, rationelle Automatisierung. 2. Aufl.: Springer, Berlin.</p> <p>Müller, Egon; Engelmann, Jörg; Löffler, Thomas; Jörg, Strauch (2009): Energieeffiziente Fabriken planen und betreiben. Berlin, Heidelberg: Springer Berlin Heidelberg.</p> <p>Schenk, Michael; Müller, Egon; Wirth, Siegfried (2014): Fabrikplanung und Fabrikbetrieb. Methoden für die wandlungsfähige, vernetzte und ressourceneffiziente Fabrik. 2. Aufl. Berlin [u.a.]: Springer Vieweg.</p> <p>Wiendahl, Hans-Peter; Reichardt, Jürgen; Nyhuis, Peter (2009): Handbuch Fabrikplanung: Konzept, Gestaltung und Umsetzung wandlungsfähiger Produktionsstätten. Carl Hanser Verlag.</p>

Course L1446: Production Logistics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dipl.-Ing. Arnd Schirrmann
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Introduction: situation, significance and main innovation focuses of logistics in a production company, aspects of procurement, production, distribution and disposal logistics, production and transport networks</li> <li>• Logistics as a production strategy: logistics-oriented method of working in a factory, throughput time, corporate strategy, structured networking, reducing complexity, integrated organization, integrated product and production logistics (IPPL)</li> <li>• Logistics-compatible production and process structuring; logistics-compatible product, material flow, information and organizational structures</li> <li>• Logistics-oriented production control: situation and development tendencies, logistics and cybernetics, market-oriented production planning, control, monitoring, PPS systems and production control, cybernetic production organization and control, production logistics control systems.</li> <li>• Production logistics planning: key performance indicators, developing a production logistics concept, computerized aids to planning production logistics, IPPL functions, economic efficiency of logistics projects</li> <li>• Production logistics controlling: production logistics and controlling, material flow-oriented cost transparency, cost controlling (process cost accounting, costs model in IPPL), process controlling (integrated production system, methods and tools, MEPOT.net method portal)</li> </ul>
<b>Literature</b>	Pawellek, G.: Produktionslogistik: Planung - Steuerung - Controlling. Carl Hanser Verlag 2007

## Specialization Materials Science

The focus of the specialization „materials technology“ is the acquisition of in-depth knowledge and skills in materials technology. One main focus is on the creation of modern material models. Modules in the electives are the material modeling and Multi-scale modeling phenomena and methods in materials science, polymer processing, as well as plastics and composites. In addition, subjects in the Technical Supplement Course for TMBMS (according FSPO) are freely selectable.

Module M1342: Polymers	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Structure and Properties of Polymers (L0389)	Lecture                      2                      3
Processing and design with polymers (L1892)	Lecture                      2                      3
<b>Module Responsible</b>	Dr. Hans Wittich
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Basics: chemistry / physics / material science
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	Students can use the knowledge of plastics and define the necessary testing and analysis.
<i>Knowledge</i>	They can explain the complex relationships structure-property relationship and the interactions of chemical structure of the polymers, including to explain neighboring contexts (e.g. sustainability, environmental protection).
<i>Skills</i>	Students are capable of <ul style="list-style-type: none"> <li>- using standardized calculation methods in a given context to mechanical properties (modulus, strength) to calculate and evaluate the different materials.</li> <li>- For mechanical recycling problems selecting appropriate solutions and sizing example Stiffness, corrosion resistance.</li> </ul>
<b>Personal Competence</b>	Students can,
<i>Social Competence</i>	- arrive at work results in groups and document them. <ul style="list-style-type: none"> <li>- provide appropriate feedback and handle feedback on their own performance constructively.</li> </ul>
<i>Autonomy</i>	Students are able to, <ul style="list-style-type: none"> <li>- assess their own strengths and weaknesses</li> <li>- assess their own state of learning in specific terms and to define further work steps on this basis guided by teachers.</li> <li>- assess possible consequences of their professional activity.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	180 min
<b>Assignment for the Following Curricula</b>	Materials Science: Specialisation Engineering Materials: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprotheses: Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Elective Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory

<b>Course L0389: Structure and Properties of Polymers</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Dr. Hans Wittich
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Structure and properties of polymers</li> <li>- Structure of macromolecules</li> <li>Constitution, Configuration, Conformation, Bonds, Synthesis, Molecular weight distribution</li> <li>- Morphology</li> <li>amorph, crystalline, blends</li> <li>- Properties</li> <li>Elasticity, plasticity, viscoelasticity</li> <li>- Thermal properties</li> <li>- Electrical properties</li> <li>- Theoretical modelling</li> <li>- Applications</li> </ul>
<b>Literature</b>	Ehrenstein: Polymer-Werkstoffe, Carl Hanser Verlag

<b>Course L1892: Processing and design with polymers</b>	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Bodo Fiedler, Dr. Hans Wittich
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<p>Manufacturing of Polymers: General Properties; Calendering; Extrusion; Injection Moulding; Thermoforming, Foaming; Joining</p> <p>Designing with Polymers: Materials Selection; Structural Design; Dimensioning</p>
<b>Literature</b>	<p>Osswald, Menges: Materials Science of Polymers for Engineers, Hanser Verlag</p> <p>Crawford: Plastics engineering, Pergamon Press</p> <p>Michaeli: Einführung in die Kunststoffverarbeitung, Hanser Verlag</p> <p>Konstruieren mit Kunststoffen, Gunter Erhard, Hanser Verlag</p>

Module M1152: Modeling Across The Scales			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Modeling Across The Scales (L1537)	Lecture	2	3
Modeling Across The Scales - Exercise (L1538)	Recitation Section (small)	2	3
<b>Module Responsible</b>	Prof. Swantje Bargmann		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	mechanics I mechanics II		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>			
<i>Knowledge</i>	The students can describe different deformation mechanisms on different scales and can name the appropriate kind of modeling concept suited for its description.		
<i>Skills</i>	The students are able to predict first estimates of the effective material behavior based on the material's microstructure. They are able to correlate and describe the damage behavior of materials based on their micromechanical behavior. In particular, they are able to apply their knowledge to different problems of material science and evaluate and implement material models into a finite element code.		
<b>Personal Competence</b>			
<i>Social Competence</i>	The students are able to present solutions to specialists and to develop ideas further.		
<i>Autonomy</i>	The students are able to assess their own strengths and weaknesses and to define tasks themselves.		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Oral exam		
<b>Examination duration and scale</b>			
<b>Assignment for the Following Curricula</b>	Computational Science and Engineering: Specialisation Scientific Computing: Elective Compulsory Materials Science: Specialisation Modeling: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1537: Modeling Across The Scales	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Swantje Bargmann
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• modeling of deformation mechanisms in materials at different scales (e.g., molecular dynamics, crystal plasticity, phenomenological models, ...)</li> <li>• relationship between microstructure and macroscopic mechanical material behavior</li> <li>• Eshelby problem</li> <li>• effective material properties, concept of RVE</li> <li>• homogenisation methods, coupling of scales (micro-meso-macro)</li> <li>• micromechanical concepts for the description of damage and failure behavior</li> </ul>
<b>Literature</b>	D. Gross, T. Seelig, Bruchmechanik: Mit einer Einführung in die Mikromechanik, Springer T. Zohdi, P. Wriggers: An Introduction to Computational Micromechanics D. Raabe: Computational Materials Science, The Simulation of Materials, Microstructures and Properties, Wiley-Vch G. Gottstein., Physical Foundations of Materials Science, Springer



Course L1538: Modeling Across The Scales - Exercise	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Swantje Bargmann
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• modeling of deformation mechanisms in materials at different scales (e.g., molecular dynamics, crystal plasticity, phenomenological models, ...)</li> <li>• relationship between microstructure and macroscopic mechanical material behavior</li> <li>• Eshelby problem</li> <li>• effective material properties, concept of RVE</li> <li>• homogenisation methods, coupling of scales (micro-meso-macro)</li> <li>• micromechanical concepts for the description of damage and failure behavior</li> </ul>
<b>Literature</b>	<p>D. Gross, T. Seelig, Bruchmechanik: Mit einer Einführung in die Mikromechanik, Springer</p> <p>T. Zohdi, P. Wriggers: An Introduction to Computational Micromechanics</p> <p>D. Raabe: Computational Materials Science, The Simulation of Materials, Microstructures and Properties, Wiley-Vch</p> <p>G. Gottstein., Physical Foundations of Materials Science, Springer</p>

Module M1170: Phenomena and Methods in Materials Science			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Experimental Methods for the Characterization of Materials (L1580)	Lecture	2	3
Phase equilibria and transformations (L1579)	Lecture	2	3
<b>Module Responsible</b>	Prof. Patrick Huber		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Fundamentals of Materials Science (I and II)		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p><i>Knowledge</i></p> <p>The students will be able to explain the properties of advanced materials along with their applications in technology, in particular metallic, ceramic, polymeric, semiconductor, modern composite materials (biomaterials) and nanomaterials.</p> <p><i>Skills</i></p> <p>The students will be able to select material configurations according to the technical needs and, if necessary, to design new materials considering architectural principles from the micro- to the macroscale. The students will also gain an overview on modern materials science, which enables them to select optimum materials combinations depending on the technical applications.</p> <p><b>Personal Competence</b></p> <p><i>Social Competence</i></p> <p>The students are able to present solutions to specialists and to develop ideas further.</p> <p><i>Autonomy</i></p> <p>The students are able to ...</p> <ul style="list-style-type: none"> <li>• assess their own strengths and weaknesses.</li> <li>• define tasks independently.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	90 min		
<b>Assignment for the Following Curricula</b>	International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Materials Science: Core qualification: Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory		

Course L1580: Experimental Methods for the Characterization of Materials	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Patrick Huber
<b>Language</b>	DE/EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>• Structural characterization by photons, neutrons and electrons (in particular X-ray and neutron scattering, electron microscopy, tomography)</li> <li>• Mechanical and thermodynamical characterization methods (indenter measurements, mechanical compression and tension tests, specific heat measurements)</li> <li>• Characterization of optical, electrical and magnetic properties (spectroscopy, electrical conductivity and magnetometry)</li> </ul>
<b>Literature</b>	William D. Callister und David G. Rethwisch, Materialwissenschaften und Werkstofftechnik, Wiley&Sons, Asia (2011). William D. Callister, Materials Science and Technology, Wiley& Sons, Inc. (2007).

Course L1579: Phase equilibria and transformations	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Jörg Weißmüller
<b>Language</b>	DE
<b>Cycle</b>	SoSe
<b>Content</b>	Fundamentals of statistical physics, formal structure of phenomenological thermodynamics, simple atomistic models and free-energy functions of solid solutions and compounds. Corrections due to nonlocal interaction (elasticity, gradient terms). Phase equilibria and alloy phase diagrams as consequence thereof. Simple atomistic considerations for interaction energies in metallic solid solutions. Diffusion in real systems. Kinetics of phase transformations for real-life boundary conditions. Partitioning, stability and morphology at solidification fronts. Order of phase transformations; glass transition. Phase transitions in nano- and microscale systems.
<b>Literature</b>	Wird im Rahmen der Lehrveranstaltung bekannt gegeben.

Module M1182: Technical Elective Course for TMBMS (according to Subject Specific Regulations)			
Courses			
Title	Typ	Hrs/wk	CP
<b>Module Responsible</b>	Prof. Robert Seifried		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	see FSPO		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<i>Knowledge</i> see FSPO <i>Skills</i> see FSPO		
<b>Personal Competence</b>	<i>Social Competence</i> see FSPO <i>Autonomy</i> see FSPO		
<b>Workload in Hours</b>	Depends on choice of courses		
<b>Credit points</b>	6		
<b>Assignment for the Following Curricula</b>	Theoretical Mechanical Engineering: Specialisation Product Development and Production: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Aircraft Systems Engineering: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Maritime Technology: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Numerics and Computer Science: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Bio- and Medical Technology: Elective Compulsory		

Module M1343: Fibre-polymer-composites			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Structure and properties of fibre-polymer-composites (L1894)	Lecture	2	3
Design with fibre-polymer-composites (L1893)	Lecture	2	3
<b>Module Responsible</b>	Prof. Bodo Fiedler		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Basics: chemistry / physics / materials science		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>Students can use the knowledge of fiber-reinforced composites (FRP) and its constituents to play (fiber / matrix) and define the necessary testing and analysis.</p> <p><i>Knowledge</i> They can explain the complex relationships structure-property relationship and the interactions of chemical structure of the polymers, their processing with the different fiber types, including to explain neighboring contexts (e.g. sustainability, environmental protection). Students are capable of</p> <p><i>Skills</i></p> <ul style="list-style-type: none"> <li>- using standardized calculation methods in a given context to mechanical properties (modulus, strength) to calculate and evaluate the different materials.</li> <li>- Approximate sizing using the network theory of the structural elements implement and evaluate.</li> <li>- For mechanical recycling problems selecting appropriate solutions and sizing example Stiffness, corrosion resistance.</li> </ul> <p><b>Personal Competence</b></p> <p>Students can,</p> <p><i>Social Competence</i></p> <ul style="list-style-type: none"> <li>- arrive at work results in groups and document them.</li> <li>- provide appropriate feedback and handle feedback on their own performance constructively.</li> </ul> <p>Students are able to,</p> <p><i>Autonomy</i></p> <ul style="list-style-type: none"> <li>- assess their own strengths and weaknesses</li> <li>- assess their own state of learning in specific terms and to define further work steps on this basis guided by teachers.</li> <li>- assess possible consequences of their professional activity.</li> </ul>		
<b>Workload in Hours</b>	Independent Study Time 124, Study Time in Lecture 56		
<b>Credit points</b>	6		
<b>Examination</b>	Written exam		
<b>Examination duration and scale</b>	180 min		
<b>Assignment for the Following Curricula</b>	Energy Systems: Core qualification: Elective Compulsory Aircraft Systems Engineering: Specialisation Cabin Systems: Elective Compulsory International Management and Engineering: Specialisation II. Product Development and Production: Elective Compulsory Materials Science: Specialisation Engineering Materials: Elective Compulsory Mechanical Engineering and Management: Core qualification: Compulsory Product Development, Materials and Production: Specialisation Product Development: Elective Compulsory Product Development, Materials and Production: Specialisation Production: Elective Compulsory Product Development, Materials and Production: Specialisation Materials: Compulsory Renewable Energies: Specialisation Bioenergy Systems: Elective Compulsory Renewable Energies: Specialisation Solar Energy Systems: Elective Compulsory Renewable Energies: Specialisation Wind Energy Systems: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory		

Course L1894: Structure and properties of fibre-polymer-composites	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Bodo Fiedler
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Microstructure and properties of the matrix and reinforcing materials and their interaction</li> <li>- Development of composite materials</li> <li>- Mechanical and physical properties</li> <li>- Mechanics of Composite Materials</li> <li>- Laminate theory</li> <li>- Test methods</li> <li>- Non destructive testing</li> <li>- Failure mechanisms</li> <li>- Theoretical models for the prediction of properties</li> <li>- Application</li> </ul>
<b>Literature</b>	Hall, Clyne: Introduction to Composite materials, Cambridge University Press Daniel, Ishai: Engineering Mechanics of Composites Materials, Oxford University Press Mallick: Fibre-Reinforced Composites, Marcel Dekker, New York

Course L1893: Design with fibre-polymer-composites	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	3
<b>Workload in Hours</b>	Independent Study Time 62, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Bodo Fiedler
<b>Language</b>	EN
<b>Cycle</b>	SoSe
<b>Content</b>	Designing with Composites: Laminate Theory; Failure Criteria; Design of Pipes and Shafts; Sandwich Structures; Notches; Joining Techniques; Compression Loading; Examples
<b>Literature</b>	Konstruieren mit Kunststoffen, Gunter Erhard , Hanser Verlag

Module M1199: Advanced Functional Materials	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b>
Advanced Functional Materials (L1625)	Lecture
<b>Hrs/wk</b>	<b>CP</b>
2	6
<b>Module Responsible</b>	Prof. Patrick Huber
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Basic knowledge in Materials Science, e.g. Materials Science I/II
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	The students will be able to explain the properties of advanced materials along with their applications in technology, in particular metallic, ceramic, polymeric, semiconductor, modern composite materials (biomaterials) and nanomaterials.
<i>Skills</i>	The students will be able to select material configurations according to the technical needs and, if necessary, to design new materials considering architectural principles from the micro- to the macroscale. The students will also gain an overview on modern materials science, which enables them to select optimum materials combinations depending on the technical applications.
<b>Personal Competence</b>	
<i>Social Competence</i>	The students are able to present solutions to specialists and to develop ideas further.
<i>Autonomy</i>	The students are able to ... <ul style="list-style-type: none"> <li>• assess their own strengths and weaknesses.</li> <li>• gather new necessary expertise by their own.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 152, Study Time in Lecture 28
<b>Credit points</b>	6
<b>Examination</b>	Presentation
<b>Examination duration and scale</b>	30 min
<b>Assignment for the Following Curricula</b>	Materials Science: Core qualification: Compulsory Mechanical Engineering and Management: Specialisation Materials: Elective Compulsory Biomedical Engineering: Specialisation Artificial Organs and Regenerative Medicine: Elective Compulsory Biomedical Engineering: Specialisation Implants and Endoprostheses: Elective Compulsory Biomedical Engineering: Specialisation Medical Technology and Control Theory: Elective Compulsory Biomedical Engineering: Specialisation Management and Business Administration: Elective Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory

Course L1625: Advanced Functional Materials	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 152, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Patrick Huber, Prof. Stefan Müller, Prof. Bodo Fiedler, Prof. Gerold Schneider, Prof. Jörg Weißmüller, Prof. Christian Cyron
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	1. Porous Solids - Preparation, Characterization and Functionalities 2. Fluidics with nanoporous membranes 3. Thermoplastic elastomers 4. Optimization of polymer properties by nanoparticles 5. Fiber composites in automotive 6. Modeling of materials based on quantum mechanics 7. Biomaterials
<b>Literature</b>	Wird in der Veranstaltung bekannt gegeben

Module M1198: Materials Physics and Atomistic Materials Modeling	
<b>Courses</b>	
<b>Title</b>	<b>Typ</b> <b>Hrs/wk</b> <b>CP</b>
Atomistic Materials Modeling (L1672)	Lecture                                      2                                      2
Materials Physics (L1624)	Lecture                                      2                                      2
Exercises in Materials Physics and Modeling (L2002)	Recitation Section (small)                      2                                      2
<b>Module Responsible</b>	Prof. Patrick Huber
<b>Admission Requirements</b>	None
<b>Recommended Previous Knowledge</b>	Advanced mathematics, physics and chemistry for students in engineering or natural sciences
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	
<i>Knowledge</i>	<p>The students are able to</p> <ul style="list-style-type: none"> <li>- explain the fundamentals of condensed matter physics</li> <li>- describe the fundamentals of the microscopic structure and mechanics, thermodynamics and optics of materials systems.</li> <li>- to understand concept and realization of advanced methods in atomistic modeling as well as to estimate their potential and limitations.</li> </ul>
<i>Skills</i>	<p>After attending this lecture the students</p> <ul style="list-style-type: none"> <li>• can perform calculations regarding the thermodynamics, mechanics, electrical and optical properties of condensed matter systems</li> <li>• are able to transfer their knowledge to related technological and scientific fields, e.g. materials design problems.</li> <li>• can select appropriate model descriptions for specific materials science problems and are able to further develop simple models.</li> </ul>
<b>Personal Competence</b>	
<i>Social Competence</i>	The students are able to present solutions to specialists and to develop ideas further.
<i>Autonomy</i>	Students are able to assess their knowledge continuously on their own by exemplified practice. The students are able to assess their own strengths and weaknesses and define tasks independently.
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Credit points</b>	6
<b>Examination</b>	Written exam
<b>Examination duration and scale</b>	90 min
<b>Assignment for the Following Curricula</b>	Materials Science: Core qualification: Compulsory Theoretical Mechanical Engineering: Technical Complementary Course: Elective Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory

Course L1672: Atomistic Materials Modeling	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Meißner
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	<ul style="list-style-type: none"> <li>- Why atomistic materials modeling</li> <li>- Newton's equations of motion and numerical approaches</li> <li>- Ergodicity</li> <li>- Atomic models</li> <li>- Basics of quantum mechanics</li> <li>- Atomic &amp; molecular many-electron systems</li> <li>- Hartree-Fock and Density-Functional Theory</li> <li>- Monte-Carlo Methods</li> <li>- Molecular Dynamics Simulations</li> <li>- Phase Field Simulations</li> </ul>
<b>Literature</b>	Daan Frenkel & Berend Smit „Understanding Molecular Simulations“ Mark E. Tuckerman „Statistical Mechanics: Theory and Molecular Simulations“ Andrew R. Leach „Molecular Modelling: Principles and Applications“ Herman J. Berendsen „Simulating the Physical World“



Course L1624: Materials Physics	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Patrick Huber
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	<p>Für den <b>Elektromagnetismus</b>:</p> <ul style="list-style-type: none"> <li>• Bergmann-Schäfer: „Lehrbuch der Experimentalphysik“, Band 2: „Elektromagnetismus“, de Gruyter</li> </ul> <p>Für die <b>Atomphysik</b>:</p> <ul style="list-style-type: none"> <li>• Haken, Wolf: „Atom- und Quantenphysik“, Springer</li> </ul> <p>Für die <b>Materialphysik und Elastizität</b>:</p> <ul style="list-style-type: none"> <li>• Hornbogen, Warlimont: „Metallkunde“, Springer</li> </ul>

Course L2002: Exercises in Materials Physics and Modeling	
<b>Typ</b>	Recitation Section (small)
<b>Hrs/wk</b>	2
<b>CP</b>	2
<b>Workload in Hours</b>	Independent Study Time 32, Study Time in Lecture 28
<b>Lecturer</b>	Prof. Robert Meißner
<b>Language</b>	DE/EN
<b>Cycle</b>	WiSe
<b>Content</b>	
<b>Literature</b>	<ul style="list-style-type: none"> <li>- Daan Frenkel &amp; Berend Smit: Understanding Molecular Simulation from Algorithms to Applications</li> <li>- Rudolf Gross und Achim Marx: Festkörperphysik</li> <li>- Neil Ashcroft and David Mermin: Solid State Physics</li> </ul>

Module M1218: Lecture: Multiscale Materials			
<b>Courses</b>			
<b>Title</b>	<b>Typ</b>	<b>Hrs/wk</b>	<b>CP</b>
Multiscale Materials (L1659)	Lecture	6	6
<b>Module Responsible</b>	Prof. Gerold Schneider		
<b>Admission Requirements</b>	None		
<b>Recommended Previous Knowledge</b>	Fundamentals in physics and chemistry, Fundamentals and enhanced fundamentals in materials science, Advanced mathematics, Fundamentals of the theory elasticity		
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results		
<b>Professional Competence</b>	<p>The master students will be able to explain...</p> <p>...the fundamental chemical and physical properties of metals, ceramics and polymers.</p> <p>... the correlation of chemical and physical phenomena on the atomic, meso and macroscale and its consequences for the macroscopic properties of materials.</p> <p>The master students will then be able understand the dependence of the macroscopic material properties on the underlying hierarchical levels.</p> <p>After attending this lecture the students can ...</p> <p>...perform materials design for multiscale materials.</p>		
<b>Personal Competence</b>	<p>The students have an interdisciplinary knowledge of the current state of research in the field of multiscale materials. Thus, they can competently discuss with the appropriate target group both with materials scientists, physicists, chemists, mechanical engineers or process engineers.</p>		
<b>Social Competence</b>	<p>The students are able to ...</p> <p>...assess their own strengths and weaknesses.</p> <p>...define tasks independently.</p>		
<b>Autonomy</b>			
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84		
<b>Credit points</b>	6		
<b>Examination</b>	Presentation		
<b>Examination duration and scale</b>	90 minutes including discussion, short academic report		
<b>Assignment for the Following Curricula</b>	Materials Science: Core qualification: Compulsory Theoretical Mechanical Engineering: Specialisation Materials Science: Elective Compulsory		

Course L1659: Multiscale Materials	
<b>Typ</b>	Lecture
<b>Hrs/wk</b>	6
<b>CP</b>	6
<b>Workload in Hours</b>	Independent Study Time 96, Study Time in Lecture 84
<b>Lecturer</b>	Prof. Gerold Schneider, Prof. Norbert Huber, Prof. Stefan Müller, Prof. Patrick Huber, Prof. Manfred Eich, Prof. Bodo Fiedler, Dr. Erica Lilleodden, Prof. Karl Schulte, Prof. Jörg Weißmüller, Prof. Christian Cyron
<b>Language</b>	DE
<b>Cycle</b>	WiSe
<b>Content</b>	<p>The materials discussed in this lecture differ from „conventional“ ones due to their individual hierarchic microstructure. In conventional microstructure design, the morphology is adjusted, for instance, by thermal treatment and concurrent mechanical deformation. The material is continually and steadily optimized by small changes in structure or chemical composition, also in combination with self-organization processes (precipitation alloys, ceramic glasses, eutectic structures).</p> <p>The presented materials consist of functionalized elementary functional units based on polymers, ceramics, metals and carbon nanotubes (CNTs), which are used to create macroscopic hierarchical material systems, whose characteristic lengths range from the nanometer to the centimeter scale. These elementary functional units are either core-shell structures or cavities in metals created by alloy corrosion and subsequent polymer filling.</p> <p>Three classes of material systems will be presented:</p> <p>First, hierarchically structured ceramic/metal-polymer material systems similar to naturally occurring examples, namely nacre (1 hierarchical level), enamel (3 hierarchical levels) and bone (5 hierarchical levels) will be discussed. Starting with an elementary functional unit consisting of ceramic nanoparticles with a polymeric coating, a material is created in which on each hierarchical level, "hard" particles, made of the respective lower hierarchical level, are present in a soft polymer background. The resulting core-shell structure on each hierarchical level is the fundamental difference compared to a compound material made of rigid interpenetrating ceramic or metallic networks.</p> <p>The second material system is based on nanoporous gold, which acts as a prototypical material for new components in light weight construction with simultaneous actuator properties. Their production and resulting length-scale specific mechanical properties will be explained. Furthermore, related scale-spanning theoretical models for their mechanical behavior will be introduced. This covers the entire scale from the electronic structure on the atomic level up to centimeter-sized macroscopic samples.</p> <p>The third material system discussed in the lecture are novel hierarchical nanostructured materials based on thermally stable ceramics and metals for high-temperature photonics with potential use in thermophotovoltaic systems (TPVs) and thermal barrier coatings (TBCs). Direct and inverted 3D-photonic crystal structures (PhCs) as well as novel optically hyperbolic media, in particular, are worthwhile noting. Due to their periodicity and diffraction index contrast, PhCs exhibit a photonic band structure, characterized by photonic band gaps, areas of particularly high photonic densities of states and special dispersion relations. The presented properties are to be used to reflect thermal radiation in TBCs in a strong and directed manner, as well as to link radiation effectively and efficiently in TPVs.</p>
<b>Literature</b>	Aktuelle Publikationen

## Thesis

Master Thesis

Module M-002: Master Thesis	
Courses	
Title	Typ
Hrs/wk	CP
<b>Module Responsible</b>	Professoren der TUHH
<b>Admission Requirements</b>	<ul style="list-style-type: none"> <li>According to General Regulations §21 (1):</li> </ul> <p>At least 60 credit points have to be achieved in study programme. The examinations board decides on exceptions.</p>
<b>Recommended Previous Knowledge</b>	
<b>Educational Objectives</b>	After taking part successfully, students have reached the following learning results
<b>Professional Competence</b>	<ul style="list-style-type: none"> <li>The students can use specialized knowledge (facts, theories, and methods) of their subject competently on specialized issues.</li> <li>The students can explain in depth the relevant approaches and terminologies in one or more areas of their subject, describing current developments and taking up a critical position on them.</li> <li>The students can place a research task in their subject area in its context and describe and critically assess the state of research.</li> </ul>
<i>Knowledge</i>	
<i>Skills</i>	<p>The students are able:</p> <ul style="list-style-type: none"> <li>To select, apply and, if necessary, develop further methods that are suitable for solving the specialized problem in question.</li> <li>To apply knowledge they have acquired and methods they have learnt in the course of their studies to complex and/or incompletely defined problems in a solution-oriented way.</li> <li>To develop new scientific findings in their subject area and subject them to a critical assessment.</li> </ul>
<b>Personal Competence</b>	Students can
<i>Social Competence</i>	<ul style="list-style-type: none"> <li>Both in writing and orally outline a scientific issue for an expert audience accurately, understandably and in a structured way.</li> <li>Deal with issues competently in an expert discussion and answer them in a manner that is appropriate to the addressees while upholding their own assessments and viewpoints convincingly.</li> </ul>
<i>Autonomy</i>	<p>Students are able:</p> <ul style="list-style-type: none"> <li>To structure a project of their own in work packages and to work them off accordingly.</li> <li>To work their way in depth into a largely unknown subject and to access the information required for them to do so.</li> <li>To apply the techniques of scientific work comprehensively in research of their own.</li> </ul>
<b>Workload in Hours</b>	Independent Study Time 900, Study Time in Lecture 0
<b>Credit points</b>	30
<b>Examination</b>	Thesis
<b>Examination duration and scale</b>	According to General Regulations
<b>Assignment for the Following Curricula</b>	Civil Engineering: Thesis: Compulsory Bioprocess Engineering: Thesis: Compulsory Chemical and Bioprocess Engineering: Thesis: Compulsory Computer Science: Thesis: Compulsory Electrical Engineering: Thesis: Compulsory Energy and Environmental Engineering: Thesis: Compulsory Energy Systems: Thesis: Compulsory Environmental Engineering: Thesis: Compulsory Aircraft Systems Engineering: Thesis: Compulsory Global Innovation Management: Thesis: Compulsory Computational Science and Engineering: Thesis: Compulsory Computational Science and Engineering: Thesis: Compulsory Information and Communication Systems: Thesis: Compulsory International Production Management: Thesis: Compulsory International Management and Engineering: Thesis: Compulsory Joint European Master in Environmental Studies - Cities and Sustainability: Thesis: Compulsory Logistics, Infrastructure and Mobility: Thesis: Compulsory Materials Science: Thesis: Compulsory Mathematical Modelling in Engineering: Theory, Numerics, Applications: Thesis: Compulsory Mechanical Engineering and Management: Thesis: Compulsory Mechatronics: Thesis: Compulsory Biomedical Engineering: Thesis: Compulsory Microelectronics and Microsystems: Thesis: Compulsory Product Development, Materials and Production: Thesis: Compulsory

Renewable Energies: Thesis: Compulsory
Naval Architecture and Ocean Engineering: Thesis: Compulsory
Ship and Offshore Technology: Thesis: Compulsory
Theoretical Mechanical Engineering: Thesis: Compulsory
Process Engineering: Thesis: Compulsory
Water and Environmental Engineering: Thesis: Compulsory